

Stochastic Grid Bundling Method for Backward Stochastic Differential Equations

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Backward Stochastic Differential Equations

- Settings:
 - A filtered complete probability space $(\Omega, \mathcal{F}, \mathbb{F}, \mathbb{P})$
 - $W := (W_t)_{0 \leq t \leq T}$ is a d -dimensional Brownian motion adapted to \mathbb{F}
- Forward Backward Stochastic Differential Equation

$$\begin{cases} dX_t = \mu(t, X_t)dt + \sigma(t, X_t)dW_t, & X_0 = x_0, \\ dY_t = -f(t, X_t, Y_t, Z_t)dt + Z_t dW_t, & Y_T = \Phi(X_T), \end{cases}$$

- $\mu : \Omega \times [0, T] \times \mathbb{R}^q \rightarrow \mathbb{R}^q$ and $\sigma : \Omega \times [0, T] \times \mathbb{R}^q \rightarrow \mathbb{R}^{q \times d}$
- $f : \Omega \times [0, T] \times \mathbb{R}^q \times \mathbb{R} \times \mathbb{R}^d \rightarrow \mathbb{R}$
- $\Phi : \Omega \times \mathbb{R}^q \rightarrow \mathbb{R}$
- Solution: (Y_t, Z_t) which satisfies the equation, adapts to \mathbb{F} and satisfies some regularity requirements.

Discretization

For a given time grid $\pi = \{0 = t_0 < \dots < t_N = T\}$, we define the backward time discretizations (Y^π, Z^π) based on the theta-scheme from [Zhao et al., 2012]:

$$\begin{aligned} Y_{t_N}^\pi &= \Phi(X_{t_N}^\pi), \quad Z_{t_N}^\pi = \nabla \Phi(X_{t_N}^\pi) \sigma(t_N, X_{t_N}^\pi) \\ Z_{t_k}^\pi &= -\theta_2^{-1}(1 - \theta_2) \mathbb{E}_{t_k} \left[Z_{t_{k+1}}^\pi \right] + \frac{1}{\Delta_k} \theta_2^{-1} \mathbb{E}_{t_k} \left[Y_{t_{k+1}}^\pi \Delta W_k^T \right] \\ &\quad + \theta_2^{-1}(1 - \theta_2) \mathbb{E}_{t_k} \left[f_{k+1}(Y_{t_{k+1}}^\pi, Z_{t_{k+1}}^\pi) \Delta W_k^T \right], \quad k = N - 1, \dots, 0 \\ Y_{t_k}^\pi &= \mathbb{E}_{t_k} \left[Y_{t_{k+1}}^\pi \right] + \Delta_k \theta_1 f_k(Y_{t_k}^\pi, Z_{t_k}^\pi) \\ &\quad + \Delta_k (1 - \theta_1) \mathbb{E}_{t_k} \left[f_{k+1}(Y_{t_{k+1}}^\pi, Z_{t_{k+1}}^\pi) \right], \quad k = N - 1, \dots, 0, \end{aligned}$$

where $f_k(y, z) := f(t_k, X_{t_k}^\pi, y, z)$, $0 \leq \theta_1 \leq 1$ and $0 < \theta_2 \leq 1$.

Discretization (cont.)

- Note that:
 - the globally Lipschitz driver assumption is in force;
 - we use a Markovian approximation $X_{t_k}^\pi, t_k \in \pi$:
 - $X_{t_{k+1}}^\pi = X_{t_k}^\pi + b(t_k, X_{t_k}^\pi)\Delta_k + \sigma(t_k, X_{t_k}^\pi)\Delta W_k$;
 - due to the Markovian setting, there exist functions $y_k^{(\theta_1, \theta_2)}(x)$ and $z_k^{(\theta_1, \theta_2)}(x)$ such that

$$Y_{t_k}^\pi = y_k^{(\theta_1, \theta_2)}(X_{t_k}^\pi), \quad Z_{t_k}^\pi = z_k^{(\theta_1, \theta_2)}(X_{t_k}^\pi).$$

- Question:
How to approximate $\mathbb{E}_{t_k}^x \left[y_{k+1}^{(\theta_1, \theta_2)}(X_{t_{k+1}}^\pi) \right]$, $\mathbb{E}_{t_k}^x \left[y_{k+1}^{(\theta_1, \theta_2)}(X_{t_{k+1}}^\pi) \Delta W_k^T \right]$,
and other similar quantities along the time grid?

Stochastic Grid Bundling Method

- Non-nested Monte Carlo scheme

- It starts with the simulation of M independent samples of $(X_{t_k}^\pi)_{0 \leq k \leq N}$, denoted by $(X_{t_k}^{\pi,m})_{1 \leq m \leq M, 0 \leq k \leq N}$.
- The simulation is only performed once.
- The terminal values for each path are:

$$y_N^{(\theta_1, \theta_2), R, I}(X_{t_N}^{\pi, m}) = \Phi(X_{t_N}^{\pi, m}),$$

$$z_N^{(\theta_1, \theta_2), R}(X_{t_N}^{\pi, m}) = \nabla \Phi(X_{t_N}^{\pi, m}) \sigma(t_N, X_{t_N}^{\pi, m}), \quad m = 1, \dots, M.$$

Recurring steps in time (I)

- Non-nested Monte Carlo scheme
- Regress-later
 - The least-squares regression technique for functions is performed on the random variable $X_{t_{k+1}}^\pi$
 - Then we use the (analytical) expectation of the resulting approximation in our algorithm.
 - This will remove the "statistical" error at the regression step.
 - To ensure the stability of our algorithm, the regression coefficients must be bounded above.
 - It means that an error notion should be given by the program when the Euclidean norm of any regression coefficient vector is greater than a predetermined constant L .

Regress now and Regress later

- Regress now

$$\begin{pmatrix} \eta_1(X_{t_k}^{\pi,1}) & & \eta_Q(X_{t_k}^{\pi,1}) \\ & \ddots & \\ \eta_1(X_{t_k}^{\pi,\#B}) & & \eta_Q(X_{t_k}^{\pi,\#B}) \end{pmatrix} \begin{pmatrix} \alpha_1 \\ \vdots \\ \alpha_Q \end{pmatrix} = \begin{pmatrix} g(X_{t_{k+1}}^{\pi,1}) \\ \vdots \\ g(X_{t_{k+1}}^{\pi,\#B}) \end{pmatrix}$$

$$\mathbb{E}[g(X_{t_{k+1}}^{\pi}) | X_{t_k}^{\pi} = x] \approx \sum_{l=1}^Q \alpha_l \eta_l(x)$$

- Regress later

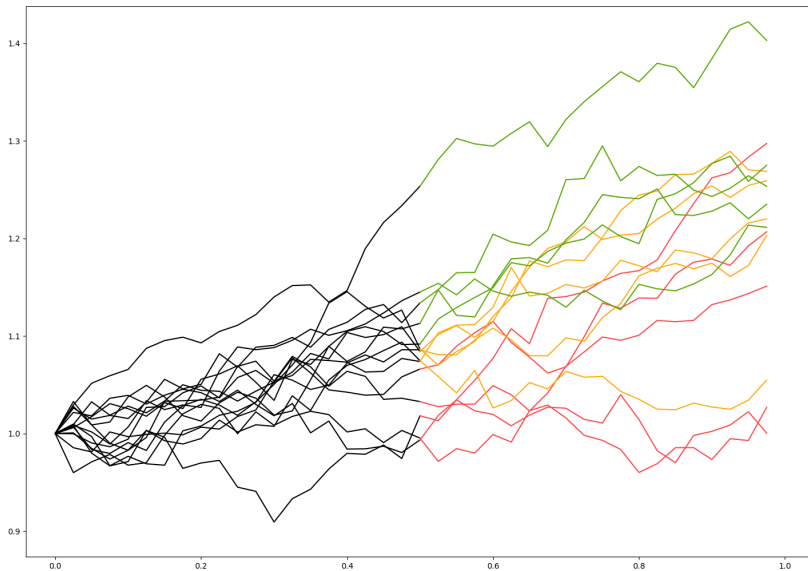
$$\begin{pmatrix} \eta_1(X_{t_{k+1}}^{\pi,1}) & & \eta_Q(X_{t_{k+1}}^{\pi,1}) \\ & \ddots & \\ \eta_1(X_{t_{k+1}}^{\pi,\#B}) & & \eta_Q(X_{t_{k+1}}^{\pi,\#B}) \end{pmatrix} \begin{pmatrix} \alpha_1 \\ \vdots \\ \alpha_Q \end{pmatrix} = \begin{pmatrix} g(X_{t_{k+1}}^{\pi,1}) \\ \vdots \\ g(X_{t_{k+1}}^{\pi,\#B}) \end{pmatrix}$$

$$\mathbb{E}[g(X_{t_{k+1}}^{\pi}) | X_{t_k}^{\pi} = x] \approx \sum_{l=1}^Q \alpha_l \mathbb{E}[\eta_l(X_{t_{k+1}}^{\pi}) | X_{t_k}^{\pi} = x]$$

Recurring steps in time (II)

- Non-nested Monte Carlo scheme
- Regress-later
- Localization (Bundling)
 - At each time period, all paths are bundled into $\mathcal{B}_{t_k}(1), \dots, \mathcal{B}_{t_k}(B)$ (almost) equal-size, non-overlapping partitions based on the result of $(X_{t_k}^{\pi, m})$.
 - We perform the approximation separately at each bundle.

Bundling



Formulation

Specifically, the bundle regression parameters $\alpha_{k+1}(b)$, $\beta_{k+1}(b)$, $\gamma_{k+1}(b)$ are defined as

$$\alpha_{k+1}(b) = \arg \min_{\alpha \in \mathbb{R}^Q} \frac{\sum_{m=1}^M (p(X_{t_{k+1}}^{\pi,m})\alpha - y_{k+1}^{(\theta_1, \theta_2), R, I}(X_{t_{k+1}}^{\pi,m}))^2 \mathbf{1}_{\mathcal{B}_{t_k}(b)}(X_{t_k}^{\pi,m})}{\sum_{m=1}^M \mathbf{1}_{\mathcal{B}_{t_k}(b)}(X_{t_k}^{\pi,m})}$$

$$\beta_{i,k+1}(b) = \arg \min_{\beta \in \mathbb{R}^Q} \frac{\sum_{m=1}^M (p(X_{t_{k+1}}^{\pi,m})\beta - z_{i,k+1}^{(\theta_1, \theta_2), R}(X_{t_{k+1}}^{\pi,m}))^2 \mathbf{1}_{\mathcal{B}_{t_k}(b)}(X_{t_k}^{\pi,m})}{\sum_{m=1}^M \mathbf{1}_{\mathcal{B}_{t_k}(b)}(X_{t_k}^{\pi,m})}$$

$$\gamma_{k+1}(b) =$$

$$\arg \min_{\gamma \in \mathbb{R}^Q} \frac{\sum_{m=1}^M (p(X_{t_{k+1}}^{\pi,m})\gamma - f_{k+1}(y_{k+1}^{(\theta_1, \theta_2), R, I}, z_{k+1}^{(\theta_1, \theta_2), R}))^2 \mathbf{1}_{\mathcal{B}_{t_k}(b)}(X_{t_k}^{\pi,m})}{\sum_{m=1}^M \mathbf{1}_{\mathcal{B}_{t_k}(b)}(X_{t_k}^{\pi,m})}$$

Formulation (cont.)

The approximate functions within the bundle at time k are defined by :

$$z_{r,k}^{(\theta_1, \theta_2), R}(b, x) = -\theta_2^{-1}(1 - \theta_2)\mathbb{E}_{t_k}^x \left[\rho(X_{t_{k+1}}^\pi) \right] \beta_{k+1}(b) \\ + \theta_2^{-1}\mathbb{E}_{t_k}^x \left[\frac{\Delta W_{r,k}}{\Delta_k} \rho(X_{t_{k+1}}^\pi) \right] (\alpha_{k+1}(b) + (1 - \theta_2)\Delta_k \gamma_{k+1}(b)),$$

$$y_k^{(\theta_1, \theta_2), R, 0}(b, x) = \mathbb{E}_{t_k}^x \left[\rho(X_{t_{k+1}}^\pi) \right] \alpha_{k+1}(b),$$

$$y_k^{(\theta_1, \theta_2), R, i}(b, x) = \Delta_k \theta_1 f_k(y_k^{\pi, R, i-1}(x), z_k^{\pi, R}(x)) + h_k(x),$$

$$h_k(b, x) = \mathbb{E}_{t_k}^x \left[\rho(X_{t_{k+1}}^\pi) \right] (\alpha_{k+1}(b) + \Delta_k(1 - \theta_1)\gamma_{k+1}(b)), \quad i = 1, \dots, l,$$

with

$$y_k^{(\theta_1, \theta_2), R, l}(x) = \sum_{b=1}^B \mathbf{1}_{x \in \mathcal{B}_{t_k}(b)} y_k^{(\theta_1, \theta_2), R, l}(b, x)$$

and similarly for z .

Refined Regression

Theorem 1

Assume that for a real function v that is bounded in a compact set and $\int v^2(x)\nu(dx) \leq \infty$, then

$$\begin{aligned} & \hat{\mathbb{E}}_S \left[\iint |v(y) - \tilde{v}(x, y)|^2 \nu(dx, dy) \right] \\ & \leq \frac{\vartheta(L')}{\hat{\mathbb{E}}[\mathbf{1}_S]} \hat{\mathbb{E}} \left[\sum_{B \in \mathbb{B}} \int_B \int \nu(dx, dy) \frac{(\log(\sum_{m=1}^M \mathbf{1}_B(X^m)) + 1)Q}{\sum_{m=1}^M \mathbf{1}_B(X^m)} \right] \\ & + \frac{8}{\hat{\mathbb{E}}[\mathbf{1}_S]} \hat{\mathbb{E}} \left[\sum_{B \in \mathbb{B}} \int_B \int \nu(dx, dy) (\inf_{\phi \in H} \sup_{x \in B} \mathbb{E} [|v(Y) - \phi(Y)|^2 | X = x] \wedge L') \right] \\ & + \hat{\mathbb{E}}_S \left[\iint |v(y) - \tilde{v}(x, y)|^2 (1 - \mathbf{1}_A(y)) \nu(dx, dy) \right] \end{aligned}$$

Example 1

We consider the BSDE:

$$\begin{cases} dX_t = dW_t, \\ dY_t = -(Y_t Z_t - Z_t + 2.5Y_t - \sin(t + X_t) \cos(t + X_t) \\ \quad - 2 \sin(t + X_t))dt + Z_t dW_t, \end{cases}$$

with the initial and terminal conditions $x_0 = 0$ and $Y_T = \sin(X_T + T)$.
The exact solution is given by

$$(Y_t, Z_t) = (\sin(X_t + t), \cos(X_t + t)).$$

The terminal time is set to be $T = 1$ and $(Y_0, Z_0) = (0, 1)$.

We run the examples with the basis functions $\eta(x) = (1, x, x^2)$ and bundle based on the value of x .

| Test Case | Example | θ_1 | θ_2 | I | M | N | B | L |
|-----------|---------|------------|------------|---|----------|-------|-------|-------|
| D | 1 | 0.5 | 0.5 | 4 | 2^{2J} | 2^J | 2^J | 100 |
| E | 1 | 0.5 | 0.5 | 4 | 2^{2J} | 2^J | 2^J | 10000 |
| F | 1 | 0.5 | 0.5 | 4 | 2^{2J} | 2^J | 2^J | — |

$$|Y_0 - y_0^{(\theta_1, \theta_2), R}(x_0)|$$

| J | 2 | 3 | 4 | 5 |
|---|-------------------------|-------------------------|-------------------------|-------------------------|
| D | NA | 9.2870×10^{-2} | 1.0114×10^{-1} | 8.1415×10^{-2} |
| E | 29.2228 | 7.8601×10^{-1} | 3.9639×10^{-1} | 5.2388×10^{-2} |
| F | 2.2154×10^{15} | 1.9059×10^{56} | 3.4731×10^{-1} | 5.8511×10^{-2} |
| J | 6 | 7 | 8 | |
| D | 3.9920×10^{-3} | 1.5486×10^{-2} | NA | |
| E | 1.1931×10^{-2} | 1.2395×10^{-2} | 1.4347×10^{-3} | |
| F | 2.0485×10^{-3} | 6.8277×10^{-3} | 2.6705×10^{-3} | |

Example 2: European option

We consider a market where the assets satisfy:

$$dS_{i,t} = \mu_i S_{i,t} dt + \sigma_i S_{i,t} dB_{i,t}, \quad 1 \leq i \leq q$$

with B_t being a correlated q -dimension Wiener process with

$$dB_{i,t} dB_{j,t} = \rho_{ij} dt.$$

The parameters ρ_{ij} form a symmetric matrix ρ ,

$$\rho = \begin{pmatrix} 1 & \rho_{12} & \rho_{13} & \cdots & \rho_{1q} \\ \rho_{21} & 1 & \rho_{23} & \cdots & \rho_{2q} \\ \vdots & \vdots & \vdots & & \vdots \\ \rho_{q1} & \rho_{q2} & \rho_{q3} & \cdots & 1 \end{pmatrix},$$

and we assume it is invertible. By performing a Cholesky decomposition on ρ such that $LL^T = \rho$, we relate B_t to standard Brownian motion

$$B_t = LW_t.$$

Example 2: European option (cont.)

For a European option with terminal payoff $g(S_T)$, a replicating portfolio Y_t , containing $\omega_{i,t}$ of asset $S_{i,t}$ and $Z_t = (\omega_{1,t}\sigma_1 S_{1,t}, \dots, \omega_{q,t}\sigma_q S_{q,t})L$ solve the BSDE,

$$\begin{cases} dY_t = -(-rY_t - Z_t L^{-1}(\frac{\mu-r}{\sigma})) dt + Z_t dW_t; \\ Y_T = g(S_T), \end{cases}$$

where $(\frac{\mu-r}{\sigma}) = (\frac{\mu_1-r}{\sigma_1}, \dots, \frac{\mu_q-r}{\sigma_q})^T$.

In this numerical test, we use the 5-dimensional example from [Reisinger and Wittum, 2007].

Example 2: European option (cont.)

We would consider a European weighted basket put option for 1 year in our test, therefore, the payoff function g is given by

$$g(s) = \left(1 - \sum_{i=1}^5 w_i s_i \right)^+,$$

where $(w_1, w_2, w_3, w_4, w_5) = (38.1, 6.5, 5.7, 27.0, 22.7)$.

The reference price is given as 0.175866.

We use equal-partitioning and sorting the paths according to $\sum_{i=1}^5 w_i X_{t_p, i}^m$.

The regression basis is $p_k(x) = \left(\sum_{i=1}^5 w_i x_i \right)^{k-1}$ for $k = 1, \dots, K$.

| Test Case | Example | θ_1 | θ_2 | I | M | N | B | L | K |
|-----------|---------|------------|------------|---|----------|----|----------|---|---|
| AA | 2 | 0.5 | 0.5 | 4 | 2^{12} | 10 | 2^{2J} | - | 3 |
| AB | 2 | 0 | 1 | - | 2^{11} | 10 | 2^{2J} | - | 2 |

| J | $ Y_0 - y_0^{(\theta_1, \theta_2), R}(x_0) $ | | |
|----|--|-------------------------|-------------------------|
| | 0 | 1 | 2 |
| AA | 2.0321×10^{-3} | 2.2567×10^{-3} | 1.9883×10^{-3} |
| AB | 2.9314×10^{-3} | 1.8934×10^{-3} | 2.2151×10^{-4} |

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Thank You