

Functional convex ordering of stochastic processes : a constructive approach

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Definitions

Definition (Convex order, peacock)

(a) Two \mathbb{R}^d -valued random vectors $U, V \in L^1(\mathbb{P})$ are ordered w.r.t. convex order, denoted

$$U \leq_{cv} V$$

if, for every $\varphi : \mathbb{R}^d \rightarrow \mathbb{R}$, **convex**, for which the inequality has a sense [φ with linear growth is enough],

$$\mathbb{E} \varphi(U) \leq \mathbb{E} \varphi(V) \in (-\infty, +\infty].$$

(b) A stochastic process $(X_u)_{u \geq 0}$ is a **p.c.o.c.** (for “processus croissant pour l'ordre convexe”) if

$u \mapsto X_u$ is non-decreasing for the convex order.

- Then $\mathbb{E} U = \mathbb{E} V$ [$\varphi(x) = \pm x$] and, if both lie in L^2 [$\varphi(x) = x^2$]

$$\text{Var}(U) \leq \text{Var}(V).$$

Examples and motivation

- If $(X_t)_{t \geq 0}$ is a **martingale**, then $(X_t)_{t \geq 0}$ is a **p.c.o.c.**: let $0 \leq s \leq t$,

$$\mathbb{E} \varphi(X_s) = \mathbb{E} (\varphi(\mathbb{E}(X_t | X_s))) \underbrace{\leq}_{\text{Jensen}} \mathbb{E} (\mathbb{E}(\varphi(X_t) | X_s)) = \mathbb{E} \varphi(X_t).$$

- **Example: Gaussian distributions (centered)**: Let $Z \sim \mathcal{N}(0, I_q)$ on \mathbb{R}^q and let $A, B \in \mathbb{M}(d, q)$ be $d \times q$ matrices

$$BB^* - AA^* \geq 0 \implies AZ \leq_{cv} BZ$$

or equivalently $\mathcal{N}(0, AA^*) \leq_{cv} \mathcal{N}(0, BB^*)$.

- **Proof**: Let $Z_1, Z_2 \sim \mathcal{N}(0; I_q)$ be independent and set

$$X_1 = AZ_1, \quad X_2 = X_1 + (BB^* - AA^*)^{1/2} Z_2.$$

Then (X_1, X_2) is an \mathbb{R}^d -valued martingale and $X_2 \sim \mathcal{N}(0, BB^*)$.

- **Scalar case $d = q = 1$** : $|\sigma| \leq |\vartheta| \implies \mathcal{N}(0, \sigma^2) \leq_{cv} \mathcal{N}(0, \vartheta^2)$.
- **1D-proof**: $\varphi : \mathbb{R} \rightarrow \mathbb{R}$ convex and $Z \in L^1$, $Z \stackrel{d}{=} -Z$. Then, by **Jensen's \leq** ,
 $u \mapsto \mathbb{E} \varphi(uZ)$ is even, convex and attains its minimum $\varphi(0)$ at $u = 0$.

Hence $u \mapsto \mathbb{E} \varphi(uZ)$ is **non-decreasing on \mathbb{R}_+** and **non-increasing on \mathbb{R}_-** .

About the converse of “martingale \Rightarrow p.c.o.c.”

- **Strassen's Theorem (1965)**: $\mu \leq_{cv} \nu \iff \exists$ transition $P(x, dy)$ s.t.

$$\nu = \mu P \quad \text{and} \quad \forall x \in \mathbb{R}^d, \quad \int y P(x, dy) = x$$

- **Kellerer's Theorem (1972)**: X is a p.c.o.c \iff

There exists a martingale $(M_t)_{t \geq 0}$ such that $X_t \stackrel{d}{=} M_t, t \geq 0$,

i.e. X is a “1-martingale”.

- Both proofs are unfortunately **non-constructive**.
- In Hirsch, Roynette, Profeta & Yor's monography, many (many...) explicit “representations” of p.c.o.c. by true martingales.

A revival motivated by Finance...

- **A starter!** t being fixed, $\sigma \mapsto e^{\sigma W_t - \frac{\sigma^2 t}{2}}$ is a **p.c.o.c.** since

$$\forall \sigma > 0, \quad e^{\sigma W_t - \frac{\sigma^2 t}{2}} \stackrel{d}{=} e^{W_{\sigma^2 t} - \frac{\sigma^2 t}{2}} \quad (\rightarrow \sigma\text{-martingale}).$$

- Application to Black-Scholes model $S_t^\sigma = s_0 e^{\sigma W_t - \frac{\sigma^2 t}{2}}$. For every **convex payoff** function $\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$

$$\sigma \leq \sigma' \implies \mathbb{E} \varphi(S_t^\sigma) \leq \mathbb{E} \varphi(S_t^{\sigma'})$$

- Vanilla options: *Call* and *Put* options: $\varphi(S_T) = (S_T - K)^+$, $\varphi(S_T) = (K - S_T)^+$, etc.
- Path-dependent options (Asian paoffs). Let $\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ convex

$$\sigma \mapsto \text{Premium}(\sigma) = \mathbb{E} \left[\varphi \left(\frac{1}{T} \int_0^T \underbrace{s_0 e^{\sigma W_t - \frac{\sigma^2 t}{2}}}_{= S_t^\sigma} dt \right) \right] ?$$

- P. Carr et al. (2008): Non-decreasing in σ when $\varphi(x) = (x - K)^+$ (Asian Call).

- M. Yor (2010): $\sigma \mapsto \frac{1}{T} \int_0^T s_0 e^{\sigma W_t - \frac{\sigma^2 t}{2}} dt$ is a p.c.o.c.

(Hint: Representation using a a Brownian sheet).

- Yields bounds on the option prices of vanilla options.
- Extensions to American options (optimal stopping, P. 2016).

- ▷ This suggests many other (new or not so new) questions !
 - **Monotone** (non-decreasing) convex order : \exists drift $b!$ [Hajek, 1985].
 - Switch from BS to **local volatility models** i.e $\sigma = \sigma(x)$ (“**functional convex order**”) ? [El Karoui-Jeanblanc-Schreve, 1998].
(Discrete time) path-dependent payoff functions i.e.
“**path-dependent**” **convex order** ? [Brown, Rogers, Hobson 2001, Rüschenendorf, 2008].
 - “Fully” path-dependent convex order (twice functional...) [P.2016].
 - Bermuda options [Pham 2005, Rüschenendorf 2008], American options [P. 2016].
 - Jumpy risky asset dynamics for (X_t^σ) ? [Rüschenendorf-Bergenthum, 2007, P. 2016].
 - P.c.o.c. trough **Martingale Optimal Transport**.
[Beigelbock, Henry-Labordère et al, 2013, Tan, Touzi, Henry-Labordère 2015, Jourdain-P. 2020].

Aims and methods

- 1 Unify and generalize these results **with of focus on functional aspects (path-dependent payoffs)** (like Asian options) i.e. **functional convex order**.
- 2 Constraint: provide a **constructive** method of proof
 - based on **time discretization of continuous time martingale dynamics** (risky assets in Finance) .
 - using **numerical schemes that preserve the functional convex order** satisfied by the process under consideration. . .
 - to **avoid arbitrages**.
- 3 Apply the paradigm to various frameworks:
 - American style options,
 - jump diffusions,
 - stochastic integrals,
 - **McKean-Vlasov diffusions**,
 - **Volterra equations**,
 - etc.

Martingale (and scaled) Brownian diffusions

- Pre-order \preceq on $\mathcal{M}(d, q, \mathbb{R})$: let $A, B \in \mathbb{M}_{d,q}$.

$$A \preceq B \quad \text{if} \quad BB^* - AA^* \in \mathcal{S}^+(d, \mathbb{R}).$$

[If $d = q = 1$, $a \preceq b$ iff $|a| \leq |b|$]

- \preceq -Convexity: $\sigma : \mathbb{R}^d \rightarrow \mathbb{M}_{d,q}$ is \preceq -convex if

$\forall x, y \in \mathbb{R}^d, \lambda \in [0, 1]$, there exists $O_{\lambda,x}, O_{\lambda,y} \in O_d(\mathbb{R})$ such that

$$\sigma(\lambda x + (1 - \lambda)y) \preceq \lambda \sigma(x) O_{\lambda,x} + (1 - \lambda) \sigma(y) O_{\lambda,y}$$

i.e.

$$\sigma \sigma^*(\lambda x + (1 - \lambda)y) \leq (\lambda \sigma(x) O_{\lambda,x} + (1 - \lambda) \sigma(y) O_{\lambda,y}) (\lambda \sigma(x) O_{\lambda,x} + (1 - \lambda) \sigma(y) O_{\lambda,y})^*$$

- $d = q = 1$ with $O_{\lambda,x} = \text{sign}(x)$ this simply reads

$|\sigma|$ convex.

Theorem (martingale case, P. 2016, Fadili-P. 2017, Jourdain-P. 2021)

Let $\sigma, \theta \in \mathcal{C}_{lin_x}([0, T] \times \mathbb{R}, \mathbb{M}_{d,q})$, $W^{(\sigma)}, W^{(\theta)}$ q -S.B.M.. Let $X^{(\sigma)}$ and $X^{(\theta)}$ be the unique weak solutions to

$$dX_t^{(\sigma)} = \sigma(t, X_t^{(\sigma)})dW_t^{(\sigma)}, \quad X_0^{(\sigma)} \in L^1$$

$$dX_t^{(\theta)} = \theta(t, X_t^{(\theta)})dW_t^{(\theta)}, \quad X_0^{(\theta)} \in L^1, \quad (W_t^{(\cdot)})_{t \in [0, T]} \text{ standard B.M.}$$

(a) If $X_0^{(\sigma)} \leq_{cv} X_0^{(\theta)}$ and

$$\left\{ \begin{array}{l} (i)_\sigma \quad \sigma(t, \cdot) : \mathbb{R}^d \rightarrow \mathbb{M}_{d,q} \text{ is } \preceq\text{-convex for every } t \in [0, T], \\ \text{or} \\ (i)_\theta \quad \theta(t, \cdot) : \mathbb{R}^d \rightarrow \mathbb{M}_{d,q} \text{ is } \preceq\text{-convex for every } t \in [0, T], \\ \text{and} \\ (ii) \quad \sigma(t, \cdot) \preceq \theta(t, \cdot) \text{ for every } t \in [0, T] \end{array} \right.$$

then, for every $F : \mathcal{C}([0, T], \mathbb{R}^d) \rightarrow \mathbb{R}$, *convex*, with $\|\cdot\|_{\text{sup}}$ -polynomial growth (hence $\|\cdot\|_{\text{sup}}$ -continuous)

$$x \mapsto \mathbb{E} F(X^{(\sigma), x}) \text{ is convex} \quad \text{and} \quad \mathbb{E} F(X^{(\sigma)}) \leq \mathbb{E} F(X^{(\theta)}).$$

The 1D case (martingale case)

Theorem (P. 2016)

Let $\sigma, \theta \in \mathcal{C}_{lin_x}([0, T] \times \mathbb{R}, \mathbb{R})$. Let $X^{(\sigma)}$ and $X^{(\theta)}$ be the unique *weak* solutions to

$$dX_t^{(\sigma)} = \sigma(t, X_t^{(\sigma)}) dW_t^{(\sigma)}, \quad X_0^{(\sigma)} \in L^1$$

$$dX_t^{(\theta)} = \theta(t, X_t^{(\theta)}) dW_t^{(\theta)}, \quad X_0^{(\theta)} \in L^1, \quad (W_t^{(\cdot)})_{t \in [0, T]} \text{ standard B.M.}$$

(a) If $X_0^{(\sigma)} \leq_{cv} X_0^{(\theta)}$ and

$$\left\{ \begin{array}{l} (i)_\sigma \quad |\sigma(t, \cdot)| : \mathbb{R} \rightarrow \mathbb{R}_+ \text{ is convex for every } t \in [0, T], \\ \text{or} \\ (i)_\theta \quad |\theta(t, \cdot)| : \mathbb{R} \rightarrow \mathbb{R}_+ \text{ is convex for every } t \in [0, T], \\ \text{and} \\ (ii) \quad |\sigma(t, \cdot)| \leq |\theta(t, \cdot)| \text{ for every } t \in [0, T] \end{array} \right.$$

then, for every $F : \mathcal{C}([0, T], \mathbb{R}) \rightarrow \mathbb{R}$, \preceq -convex, with $\|\cdot\|_{\text{sup-pol. growth}}$

$$x \mapsto \mathbb{E} F(X^{(\sigma), x}) \text{ is convex} \quad \text{and} \quad \mathbb{E} F(X^{(\sigma)}) \leq \mathbb{E} F(X^{(\theta)}).$$

Scaled/drifted martingale diffusions (extension to)

- The former theorems still hold true for

$$dX_t^{(\sigma)} = \alpha(t)(X_t^{(\sigma)} + \beta(t))dt + \sigma(t, X_t^{(\sigma)})dW_t^{(\sigma)},$$

$$dX_t^{(\theta)} = \alpha(t)(X_t^{(\theta)} + \beta(t))dt + \theta(t, X_t^{(\theta)})dW_t^{(\theta)},$$

where $\alpha(t) \in \mathbb{M}_{d,d}$ and $\beta(t) \in \mathbb{R}^d$ are Hölder continuous.

- Change of variable:

$$\tilde{X}_t^{(\sigma)} = e^{-\int_0^t \alpha(s)ds} (X_t^{(\sigma)} + \beta(t)).$$

- Finance:** spot interest rate $\alpha(t) = r(t)\mathbf{1}$ and $\beta(t) = 0$ since typical (risk-neutral) dynamics of traded assets read

$$dS_t = r(t)S_t dt + S_t \sigma(S_t, \omega) dW_t$$

- For more general drifts $b(t, x)$ when $d = q = 1$: functional version of Hajek's theorem: monotone functional convex order holds true if

$$\forall t \in [0, T], \quad b(t, \cdot) \text{ is convex.}$$

Strategy (constructive)

- Time discretization (preferably) accessible to simulation: typically the Euler scheme.
- Propagate convexity (marginal or pathwise)
- Propagate comparison (marginal or pathwise)
- Transfer by functional limit theorems “à la Jacod-Shiryaev”.

Step 1: discrete time ARCH models

- **ARCH dynamics:** Let $(Z_k)_{1 \leq k \leq n}$ be a sequence of **independent**, **symmetric** r.v. on $(\Omega, \mathcal{A}, \mathbb{P})$. Two ARCH models: $X_0, Y_0 \in L^1(\mathbb{P})$,

$$\begin{aligned} X_{k+1} &= X_k + \sigma_k(X_k) Z_{k+1}, \\ Y_{k+1} &= Y_k + \theta_k(Y_k) Z_{k+1}, \quad k = 0 : n-1, \end{aligned}$$

where $\sigma_k, \theta_k : \mathbb{R} \rightarrow \mathbb{R}$, $k = 0 : n-1$ have linear growth.

Proposition (Propagation result)

If $\sigma_k, k = 0 = n-1$ are \preceq -convex with linear growth,

$$X_0 = x \quad \text{and} \quad \forall k \in \{0, \dots, n-1\}, \quad \sigma_k \preceq \theta_k,$$

then, for every convex function $F : (\mathbb{R}^d)^{n+1} \rightarrow \mathbb{R}$ convex with linear growth

$$x \longmapsto \mathbb{E} F(x, X_1^x, \dots, X_n^x) \quad \text{is convex.}$$

Partial proof (marginal) with Gaussian white noise

- $Z_k \sim \mathcal{N}(0, I_q)$, $1 \leq k \leq n$.
- Let $f : \mathbb{R}^d \rightarrow \mathbb{R}$ be a convex function. Let $P_k^\sigma f(x) := \mathbb{E}f(x + \sigma_k(x)Z) = [\mathbb{E}f(x + uZ)]|_{u=\sigma_k(x)}$.
- Set $A \in \mathbb{M}_{d,q} \mapsto Qf(A) := \mathbb{E}f(x + AZ)$ is **right $O(d)$ -invariant**, **convex** and **\preceq -non-decreasing** by the starting example.
- Hence if $x, y \in \mathbb{R}^d$ and $\lambda \in [0, 1]$

$$\begin{aligned}
 P_k^\sigma f(\lambda x + (1 - \lambda)y) &= Qf(\sigma_k(\lambda x + (1 - \lambda)y)) \\
 &\leq Qf(\lambda \sigma_k(x) + (1 - \lambda)\sigma_k(y)) \\
 &\leq \lambda Qf(\sigma_k(x)) + (1 - \lambda)Qf(\sigma_k(y)) \\
 &= \lambda P_k^\sigma f(x) + (1 - \lambda)P_k^\sigma f(y).
 \end{aligned}$$

- Hence

$$x \mapsto \mathbb{E}f(X_n^x) = P_1^\sigma \circ \dots \circ P_n^\sigma f(x) \quad \text{is convex}$$

Theorem (Discrete time comparison result)

If all σ_k , $k = 0 : n - 1$ or all θ_k , $k = 0 : n - 1$ are \preceq -convex with linear growth,

$$X_0 \leq_{cv} Y_0 \quad \text{and} \quad \forall k \in \{0, \dots, n - 1\}, \quad \sigma_k \preceq \theta_k,$$

then

$$(X_0, \dots, X_n) \leq_{cv} (Y_0, \dots, Y_n).$$

Partial proof (marginal) with Gaussian white noise

- Backward induction on k .
- For $k = n$. Let $f : \mathbb{R}^d \rightarrow \mathbb{R}$ be a convex function.

$$P_n^\sigma f(x) = Qf(\sigma_n(x)) \leq Qf(\theta_n(x)) = P_n^\theta f(x)$$

by non-decreasing \preceq -monotony of Q .

- Assume $\underbrace{P_{k+1:n}^\sigma f}_{\text{convex}} \leq P_{k+1:n}^\theta f$.

$$A \in \mathbb{M}_{d,q} \mapsto Q(P_{k+1:n}^\sigma f)(A) \quad \text{is } \preceq\text{-non-decreasing}$$

so that

$$\begin{aligned} P_{k+1:n}^\sigma f(x) &= Q(P_{k+1:n}^\sigma f)(\sigma_k(x)) \stackrel{\downarrow}{\leq} Q(P_{k+1:n}^\sigma f)(\theta_k(x)) \\ &\leq Q(P_{k+1:n}^\theta f)(\theta_k(x)) \\ &= P_{k+1:n}^\theta f(x). \end{aligned}$$

- Hence

$$\mathbb{E} f(X_n^\sigma) = \mathbb{E} P_{1:n}^\sigma f(X_0) \leq \mathbb{E} P_{1:n}^\theta f(Y_0) \leq \mathbb{E} P_{1:n}^\theta f(Y_0) = \mathbb{E} f(X_n^\theta).$$

Functional approach

- Same strategy
- But entirely **backward**.

Step 2 of the proof: Back to continuous time

▷ **Euler scheme(s)**: Discrete time Euler scheme with step $\frac{T}{n}$, starting at x is an ARCH model. For $X^{(\sigma)}$: for $k = 0, \dots, n-1$,

$$\bar{X}_{t_{k+1}^n}^{(\sigma),n} = \bar{X}_{t_k^n}^{(\sigma),n} + \sigma(t_k^n, \bar{X}_{t_k^n}^{(\sigma),n})(W_{t_{k+1}^n} - W_{t_k^n}), \quad \bar{X}_0^{(\sigma),n} = x$$

Set

$$Z_k = W_{t_k^n} - W_{t_{k-1}^n}, \quad k = 1, \dots, n$$



discrete time setting applies

Remark. Linear growth of σ and θ , implies

$$\forall p > 0, \quad \sup_{n \geq 1} \left\| \sup_{t \in [0, T]} |\bar{X}_t^{(\sigma),n}| \right\|_p + \sup_{n \geq 1} \left\| \sup_{t \in [0, T]} |\bar{X}_t^{(\theta),n}| \right\|_p < +\infty.$$

From discrete to continuous time

▷ Interpolation ($n \geq 1$)

- *Piecewise affine interpolator* defined by

$$\forall x_{0:n} \in \mathbb{R}^{n+1}, \forall k = 0, \dots, n-1, \forall t \in [t_k^n, t_{k+1}^n], \quad .$$

$$i_n(x_{0:n})(t) = \frac{n}{T} ((t_{k+1}^n - t)x_k + (t - t_k^n)x_{k+1})$$

- $\tilde{X}^{(\sigma),n} := i_n((\bar{X}_{t_k^n}^{(\sigma),n})_{k=0:n}) =$ **piecewise affine Euler scheme.**

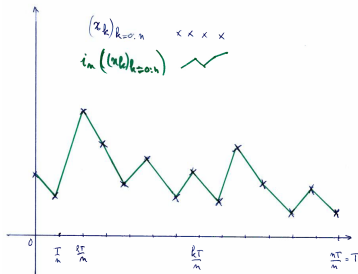


Figure: Interpolator

▷ Let $F : \mathcal{C}([0, T], \mathbb{R}) \rightarrow \mathbb{R}$ be a **convex functional** (with r -poly. growth).

$$\forall n \geq 1, \quad F_n : \mathbb{R}^{n+1} \ni x_{0:n} \mapsto F_n(x_{0:n}) := F(i_n(x_{0:n})).$$

- **Step 1 (Discrete time):** $F(\tilde{X}^{(\sigma),n}) = F_n((\tilde{X}_{t_k^n}^{(\sigma),n})_{k=0:n})$ and

$$F \text{ convex} \implies F_n \text{ convex}, \quad n \geq 1.$$

Discrete time result implies since $\sigma(t_k^n, \cdot) \leq \theta(t_k^n, \cdot)$.

$$\mathbb{E} F(\tilde{X}^{(\sigma),n}) = \mathbb{E} F_n((\tilde{X}_{t_k^n}^{(\sigma),n})_{k=0:n}) \leq \mathbb{E} F_n((\tilde{X}_{t_k^n}^{(\theta),n})_{k=0:n}) = \mathbb{E} F(\tilde{X}^{(\theta),n}).$$

- **Step 2 (Transfer):** See e.g. [Jacod-Shiryaev's book, 2nd edition, Theorem 3.39, p.551].

$$\tilde{X}^{(\sigma),n} \xrightarrow{\mathcal{L}(\|\cdot\|_{\text{sup}})} X^{(\sigma)} \quad \text{as } n \rightarrow \infty.$$

$$\mathbb{E} F(X^{(\sigma)}) = \lim_n \mathbb{E} F(\tilde{X}^{(\sigma),n}) \quad (\text{idem for } X^{(\theta)}).$$

The Euler scheme provides a simulable approximation

which preserves convex order.

Smooth σ & 1D

- Assume $\sigma : \mathbb{R} \rightarrow \mathbb{R}_+$ C^2 , Lipschitz ($\|\sigma'\|_\infty < +\infty$).
- True Euler operator, $Z \sim \mathcal{N}(0, 1)$:

$$Pf(x) = \mathbb{E} f(x + \sqrt{h}\sigma(x)Z)$$

- Assume w.l.g. $f : \mathbb{R}^d \rightarrow \mathbb{R}$ C^2 and convex

$$\begin{aligned} (Pf)''(x) &= \mathbb{E} [f''(x + \sqrt{h}\sigma(x)Z)(1 + \sqrt{h}\sigma'(x)Z)^2] \\ &\quad + \sqrt{h}\sigma'(x)\mathbb{E} [f'(x + \sqrt{h}\sigma(x)Z)Z] \\ &= \mathbb{E} [f''(x + \sqrt{h}\sigma(x)Z)(1 + \sqrt{h}\sigma'(x)Z)^2] \\ &\quad + h\sigma\sigma''(x)\mathbb{E} [f''(x + \sqrt{h}\sigma(x)Z)] \quad \text{Stein I.P.} \\ &= \mathbb{E} \left[f''(x + \sqrt{h}\sigma(x)Z) \underbrace{((1 + \sqrt{h}\sigma'(x)Z)^2 + h\sigma\sigma''(x))}_{\text{always } \geq 0 \forall Z(\omega)??} \right] \end{aligned}$$

- No ! But... If we **truncate** : $Z \rightsquigarrow Z^h = Z\mathbf{1}_{\{|Z| \leq A_h\}}$, then

- Then, the same Stein-I.P. transform yields

$$(P^h f)''(x) = \mathbb{E} \left[f''(x + \sqrt{h}\sigma(x)Z^h) \underbrace{\left((1 + \sqrt{h}\sigma'(x)Z^h)^2 + h(1 - e^{-(A_h^2 - (Z^h)^2)^+}) \right)}_{\text{always } \geq 0 \ \forall Z^h(\omega)??} \sigma\sigma''(x) \right]$$

- YES !!** If $A_h = A/\sqrt{h}$ with $A < \frac{1}{\|\sigma'\|_\infty}$ for h small enough, provided

$$\sup_{x \in \mathbb{R}} \frac{\sigma(\sigma'')^-}{|\sigma'|} < +\infty \quad (\implies \text{Ok if } \sigma \text{ convex!})$$

- Truncated Euler scheme with time step $h = T/n$** does converge (almost) “as usual” toward the diffusion as $n \rightarrow \infty$.
- Similar results for monotone convex ordering for **diffusions sharing the same convex drift**.
- Applications to local volatility models (like CEV) extending results by El Karoui-Jeanblanc-Shreve to continuous time path-dependent options.
- Extension to **directionally convex functionals F** (see also Rüsendorf & Bergenthum but ... a with restrictions).

Extensions

This provides as systematic approach which successfully works with

- Jump diffusion models,
- Path-dependent American style options,
- BSDE (without “ Z ” in the driver),
- ...

McKean-Vlasov diffusions:

- The *MKV* dynamics

$$(E) \equiv dX_t = b(t, X_t, \mu_t)dW_t + \sigma(t, X_t, \mu_t)dW_t, \quad t \in [0, T]$$

with $\mu_t = \mathcal{L}(X_t)$, $W = (W_t)_{t \in [0, T]}$ a standard B.M. and

$b, \sigma : [0, T] \times \mathbb{R} \times \mathcal{P}_p(\mathbb{R}) \rightarrow \mathbb{R}$ are continuous satisfying

(Lip) $\equiv b(t, \cdot, \cdot), \sigma(t, \cdot, \cdot)$ is $(|\cdot|, \mathcal{W}_p)$ -Lipschitz, uniformly in $t \in [0, T]$.

$$\begin{aligned} \text{Wasserstein distance: } \mathcal{W}_p^p(\mu, \nu) &= \inf \left\{ \int |x - y|^p m(dx, dy), m(dx, \mathbb{R}^d) = \mu, m(\mathbb{R}^d, dy) = \nu \right\}. \\ & \left(= \sup \left\{ \int f d\mu - \int f d\nu, [f]_{\text{Lip}} \leq 1 \right\} \text{ when } p = 1 \right). \end{aligned}$$

- Under this assumption a strong solution exists for this equation.
- “Scaled” Martingality “requires” a drift term

$$b(t, X_t, \mu_t) = \alpha(t)(X_t + \beta(t, \mathbb{E} X_t))$$

$\alpha(t), \beta(t, \xi)$ Hölder continuous in t , β Lipschitz in ξ , uniformly in t .
(From now on all zero for convenience. . .)

Understanding *MKV*

- **Vlasov framework ($p = 1$).** If σ has the following linear representation in μ

$$\sigma(x, \mu) = \int_{\mathbb{R}} \sigma(x, \xi) \mu(d\xi).$$

- **Non linear framework.** E.g.

$$\sigma(x, \mu) = \varphi_0 \left(\int_{\mathbb{R}} \sigma(x, \xi) \mu(d\xi) \right).$$

MKV propagates convex order

Theorem (Liu-P., 2019)

Let $\sigma, \theta \in Lip([0, T] \times \mathbb{R} \times \mathcal{P}_p(\mathbb{R}), \mathbb{R}^d)$, $p \geq 2$. Let $X^{(\sigma)}$ and $X^{(\theta)}$ be the unique solutions to

$$dX_t = \sigma(t, X_t, \mu_t) dW_t, \quad X_0 \in L^p$$

$$dY_t = \theta(t, Y_t, \nu_t) dW_t, \quad Y_0 \in L^p \quad \text{with } (W_t^{(\cdot)})_{t \in [0, T]} \text{ standard B.M.}$$

$$\text{If } \begin{cases} (i)_\sigma & \sigma(t, x, \mu) \text{ is } x\text{-}\preceq\text{-convex and } \mu\text{-}\uparrow_{cv} \text{ for every } t \in [0, T], \\ & \text{or} \\ (i)_\theta & \theta(t, x, \mu) \text{ is } x\text{-}\preceq\text{-convex and } \mu\text{-}\uparrow_{cv} \text{ for every } t \in [0, T], \\ & \text{and} \\ (ii) & \sigma(t, x, \mu) \preceq \theta(t, x, \mu) \quad [|\sigma(t, x, \mu)| \leq |\theta(t, x, \mu)| \text{ if } d = 1] \end{cases}$$

and $X_0 \leq_{cv} Y_0$, then, for every $F : \mathcal{C}([0, T], \mathbb{R}) \rightarrow \mathbb{R}$, convex with $\|\cdot\|_{\text{sup}}$ -polynomial growth,

$$x \mapsto \mathbb{E} F(X^x) \text{ is convex (if } X_0 = x \text{ and } (i)_\sigma \text{ holds) and } \mathbb{E} F(X) \leq \mathbb{E} F(Y).$$

Specificity of the proof

- The “regular” Euler scheme is again the main tool . . . although not simulatable.
- Specificity for **convexity propagation**: two steps
 - Forward “marginal ” approach necessary prior to
 - a **backward “functional”** approach.

Non-Markovian dynamics: Volterra equations (Jourdain-P. '22))

- Let $(X_t)_{t \in [0, T]}$ be a solution to the scaled stochastic Volterra equation

$$X_t = X_0 + \int_0^t K(t, s)(\alpha(s) + \beta(s)X_s) ds + \int_0^t K(t, s)\sigma(s, X_s) dW_s, \quad t \in [0, T]$$

where the **non-negative** kernel $(K(t, s))_{0 \leq s \leq t \leq T}$ is measurable and integrable, $\sigma : [0, T] \times \mathbb{R}^d \rightarrow \mathbb{M}_{d, q}$ and $(W_t)_{t \in [0, T]}$ is a standard q -dimensional Brownian motion.

- Such a process is centered, (\mathcal{F}_t^W) -adapted but is not a martingale (not even a semi-martingale, in general).

Theorem (convex propagation)

Assume

$$\forall t \in [0, T], \quad x \mapsto \sigma(t, x) \text{ is } \preceq\text{-convex}$$

then, for every convex functional $F : \mathcal{C}([0, T], \mathbb{R}^d) \rightarrow \mathbb{R}$ with $\|\cdot\|_{\text{sup-pol.growth}}$

$$x \mapsto \mathbb{E} F(X^x) \quad \text{is convex.}$$

Functional convex ordering

- Let

$$Y_t = Y_0 + \int_0^t K(t,s)(\alpha(s) + \beta(s)Y_s)ds + \int_0^t K(t,s)\theta(s, Y_s)dW_s, \quad t \in [0, T]$$

Theorem (convex ordering)

If

$$\left\{ \begin{array}{l} (i)_\sigma \quad \sigma(t, x) \text{ is } x\text{-}\preceq\text{-convex for every } t \in [0, T], \\ \text{or} \\ (i)_\theta \quad \theta(t, x) \text{ is } x\text{-}\preceq\text{-convex for every } t \in [0, T], \\ \text{and} \\ (ii) \quad \sigma(t, x) \preceq \theta(t, x) \quad [|\sigma(t, x)| \leq |\theta(t, x)| \text{ if } d = 1] \end{array} \right.$$

and $X_0 \leq_{cv} Y_0$, then, for every $F : \mathcal{C}([0, T], \mathbb{R}) \rightarrow \mathbb{R}$, convex with $\|\cdot\|_{\text{sup}}$ -polynomial growth,

$$\mathbb{E} F(X) \leq \mathbb{E} F(Y)$$

Methods of proof

- ($\alpha = \beta = 0$ for simplicity).
- We consider its **Euler scheme** with time step $\frac{T}{n}$ ($t_k = \frac{kT}{n}$):

$$\bar{X}_{t_k} = X_0 + \sum_{\ell=0}^{k-1} \sigma(t_\ell, \bar{X}_{t_\ell}) \int_{t_\ell}^{t_{\ell+1}} K(t_k, s) dW_s, \quad \bar{X}_0 = X_0.$$

- Not enough due to lack of Markovianity since \bar{X}_{t_k} is not (in general) a function of $(\bar{X}_{t_{k-1}}, (W_s - W_{t_{k-1}})_{s \in [t_{k-1}, t_k]})$.
- **Markovianization**: introduce for $k \in \{1, \dots, n\}$, $(X_{t_\ell}^k)_{0 \leq \ell \leq k}$ starting from $X_0^k = X_0$ and evolving inductively according to

$$X_{t_{\ell+1}}^k = X_{t_\ell}^k + \sigma(t_\ell, \bar{X}_{t_\ell}) \int_{t_\ell}^{t_{\ell+1}} K(t_k, s) dW_s, \quad 0 \leq \ell \leq k-1,$$

so that $\bar{X}_{t_k} = X_{t_k}^k$ for $k \in \{1, \dots, n\}$ and $X^n = \bar{X}$.

- “Extend” the backward propagation proof to functionals

$$F((X_{t_\ell}^n)_{\ell=0:n}, \dots, (X_{t_\ell}^k)_{\ell=0:k}, \dots, (X_{t_\ell}^1)_{\ell=0:1}).$$

- Transfer to continuous time by letting $n \rightarrow \infty$ (using e.g. Richard et al. '20). □
- Extension to (one-dimensional) non-decreasing convex ordering when the drift b is \preceq -convex.

Applications to Vix options in rough Heston model

- Let us consider the auxiliary variance process in the **quadratic rough Heston model** (see Gatheral-Jusselin-Rosenbaum '20):

$$V_t = a(Z_t - b)^2 + c \quad \text{with} \quad a, b, c \geq 0$$

and, for $H \in (0, 1/2)$,

$$Z_t = Z_0 + \int_0^t (t-s)^{H-\frac{1}{2}} \lambda(f(s) - Z_s) ds + \sigma \int_0^t (t-s)^{H-\frac{1}{2}} \sqrt{a(Z_s - b)^2 + c} dW_s.$$

- $z \mapsto \sqrt{a(z - b)^2 + c}$ is **convex and Lipschitz**.
- Let $(Z_t^\sigma)_{t \geq 0}$ be its unique strong solution and V^σ the resulting squared volatility.
- For $\sigma \in (0, \tilde{\sigma}]$, one has $(Z_t^\sigma)_{t \in [0, T]} \leq_{cv} (Z_t^{\tilde{\sigma}})_{t \in [0, T]}$.
- Convexity of $L^2(dt)$ norm and (again) of $z \mapsto \sqrt{a(z - b)^2 + c}$ imply that

$$\mathbb{E} \left(\sqrt{\frac{1}{T} \int_0^T V_t^\sigma dt} \right) \leq \mathbb{E} \left(\sqrt{\frac{1}{T} \int_0^T V_t^{\tilde{\sigma}} dt} \right).$$







This is in fact a **paradigm**:

Propagate convex order
in discrete then transfer to continuous
time
is easier




(if you know functional limit theorems for the dynamics under
consideration)

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