

Introduction & links to previous problems

20th Winter School on Mathematical Finance

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1) Monge Transport for $X=Y$.

If $\pi = (\text{Id}, T) \# \mu \in \Pi(\mu, \nu)$ is a Monge coupling

then we can naturally consider "intermediate" measures

$$\mu_t := ((1-t)\text{Id} + tT) \# \mu \quad t \in [0, 1]$$

so that $\mu_0 = \mu$ & $\mu_1 = \nu$.

2) An easy way to construct a martingale $(M_t)_{t \in [0, 1]}$ with

$M_0 = 0$, $M_1 \sim \nu \in \mathcal{P}_1(\mathbb{R})$ centered is

$$M_t = \mathbb{E} \left[F_t^{-1}(\Phi(B_1)) \mid \mathcal{F}_t \right] \quad t \in [0, 1].$$

Note that $\Phi(B_1) \sim \text{Unif}[0, 1] \Rightarrow F_t^{-1}(\Phi(B_1)) \sim \nu$

$\Rightarrow M_0 = 0$, $M_1 = F_1^{-1}(\Phi(B_1)) \sim \nu$

& $M_t = F(t, B_t) \sim M_t$

$$M_t = \mathbb{E} \left[F_t^{-1}(\Phi(B_t + B_1 - B_t)) \mid \mathcal{F}_t \right]$$

$$= F(t, B_t)$$

$$F_t^{-1} \circ \Phi =: g$$

$$F(t, x) = \mathbb{E} \left[F_t^{-1}(\Phi(x + \sqrt{1-t} N)) \right] = \int \mathbb{P}_{1-t}(y) g(x+y) dy$$

implies a fbr of measures

3) Given τ which solves (SEP)(v) \mathbb{I} can define

$$L_t := \mathcal{L}(B_\tau | \mathcal{F}_{t+\tau}) \quad \text{so that now } L_0 \sim v$$

and $\tau = \inf \{ t \geq 0 : L_t \text{ is a dipole} \} = \inf \{ t \geq 0 : \text{Var}(L_t) = 0 \}$

L_t is a measure-valued martingale (i.e., $\int f(x) L_t(dx) =: M_t^f$ is any since $M_t^f = \mathbb{E}[f(B_\tau) | \mathcal{F}_{t+\tau}]$)

Note that $B_{t+\tau} = \int_x dL_t$

Elden '17 \rightarrow solve (SEP) via a Markov flow L_t looking at

$$g(t) = \frac{dL_t}{dt} \quad \text{which solve an SDE. See the paper for comparison with Bass.}$$

Lagrangian vs Eulerian points of view [technicalities aside] on $X = \mathbb{R}^n$

Consider particles moving according to a velocity field v :

(Lag.) $\frac{dX(t)}{dt} = v_t(X(t))$ describes the movement/position of a particle X .

We can also ask how does the density of particles evolve? $\nabla \cdot f \in \mathcal{G}(X)$ is the density of the f , then (Lag) is equivalent to

(Eul) $\frac{d\rho_t}{dt} + \nabla_x \cdot (\rho_t v_t) = 0$ (transport equation: continuity - conservation of mass eq.)

$$\int \varphi d(\nabla \cdot m) = - \int \nabla \varphi \cdot dm$$

for a vector-valued measure m .

For a smooth ρ, v in a Euclidean setting

$$\nabla \cdot (\rho v) = \sum_{i=1}^n \frac{\partial (\rho v_i)}{\partial x_i}$$

Kinetic energy of particle is given by $E(t) = \int_{\mathbb{R}^n} \rho_t(x) |v_t(x)|^2 dx$

\Rightarrow action A given by $A[\rho, v] = \int_0^1 E(t) dt$

"total effort to move particles using the velocity field v "

B-B formulation: $\inf_{(\rho, v) \in V(\mu, \nu)} A[\rho, v]$, where

$$V(\mu, \nu) = \left\{ (\rho, v) : \int \rho_0(x) dx = \mu(dx), \int \rho_1(x) dx = \nu(dx), \frac{\partial \rho_t}{\partial t} + \nabla \cdot (\rho_t v_t) = 0 \right. \\ \left. + \text{regularity} \right\}$$

Thm [B-B] For $\mu, \nu \in \mathcal{P}_2(\mathbb{R}^n)$, $\mu, \nu \ll \text{Leb}$,

$$W_2^2(\mu, \nu) = \inf \left\{ A[\rho, v] : (\rho, v) \in V(\mu, \nu) \right\}$$

Some ideas for the proof:

$$W_2^2(\mu, \nu) = \inf \left\{ \int \rho_0(x) |T(x) - x|^2 dx : T \# \rho_0 = \rho_1 \right\}$$

$$\text{Given } (\rho, v) \in V(\mu, \nu), \text{ define } T_t \text{ via } \begin{cases} \frac{d}{dt} T_t(x) = v_t(T_t(x)) \\ T_0(x) = x \end{cases}$$

$$\Rightarrow \rho_t = T_t \# \rho_0$$

$$E(t) = \int \rho_t(x) |v_t(T_t(x))|^2 dx = \int \rho_0(x) \left| \frac{d}{dt} T_t(x) \right|^2 dx$$

$$\begin{aligned} \rightarrow A[\rho, v] &= \int_0^1 \int \rho_0(x) \left| \frac{d}{dt} T_t(x) \right|^2 dx dt \\ &= \int_{\mathbb{R}^n} \rho_0(x) \int_0^1 \left| \frac{d}{dt} T_t(x) \right|^2 dt dx \stackrel{\text{Jensen}}{\geq} \int \rho_0(x) \inf_{t \in [0,1]} \left| \frac{d}{dt} T_t(x) \right|^2 dx \\ &= \int \rho_0(x) |T_1(x) - x|^2 dx \geq W_2^2(\mu, \nu) \end{aligned}$$

with equality iff $\frac{d}{dt} T_t(x) \equiv \text{const} \Rightarrow v_t(T_t(x)) \text{ const.}$

i.e. optimal flow has particles moving at a constant speed.

This is achieved taking $T = \nabla \varphi$ the optimal Monge transport \leftarrow

letting $T_t := (1-t)\text{Id} + tT(x) \equiv \nabla \varphi_t(x)$

$\leftarrow V_t = \left(\frac{d}{dt} T_t\right) \circ T_t^{-1}$ / Recall $\nabla \varphi = \nabla \varphi_t^*$

$= (T - \text{Id}) \circ T_t^{-1}$ / clearly $V_t(T_t) = \frac{d}{dt} T_t$

$\int_{\mathcal{P}_t} f(V_t) \cdot dx = \int_{\mathcal{P}_0} f(V_t \circ T_t) \cdot dx$
 $= \int_{\mathcal{P}_0} f((T - \text{Id})) \cdot dx$

$\leftarrow \frac{d}{dt} T_t = (T - \text{Id})$ indep of t .

s. $E(t) = \int_{\mathcal{P}_0} |T(x) - x|^2 dx = W_2^2(\mu, \nu)$ indep of t . ▣

Rk Above we optimised over (ρ, ν) but among all ν compatible with the flow ρ via the cont. eq. we want to select the one with minimal energy $E(t) \Rightarrow$ it should be \perp to divergence-free vector fields \rightarrow should be a gradient in some sense

\Rightarrow this leads to seeing the [B-B] pt as a gradient flow on $\mathcal{P}_2(\mathbb{R}^n) \rightsquigarrow \mathcal{P}_2(X)$.

\Rightarrow the flows trace geodesics (compare with geodesics formula in Riemannian geometry)

Rk The final pt also has a dynamic reformulation.

Prop If C is convex on \mathbb{R}^n then C -concave functions are equivalent to all viscosity solutions of the H-J eq.

$$\frac{\partial u}{\partial t} + C^*(Du) = 0 \quad \text{at } t=1$$

(or $t \geq 1$)

\Rightarrow Thm Let $C: \mathbb{R}^n \rightarrow \mathbb{R}_+$ be convex & superlinear. Then

$$\mathcal{D}(\mu, \nu) = \sup \left\{ \int \varphi(1, \cdot) d\nu - \int \varphi(0, \cdot) d\mu : \varphi: [0,1] \times \mathbb{R}^n \rightarrow \mathbb{R} \right\}$$

$$\text{solves } \begin{cases} \frac{\partial \psi}{\partial t} + c^*(\nabla_x \psi) = 0 \\ \psi(0, \cdot) \in C_b(\mathbb{R}^n) \end{cases}$$

This leads to a short proof of BB (via FR is the proof)

Displacement Interpolation

Go back to the idea above that a dr. plan T defines a flow via T_t .

Consider instead of $\mathbb{P}(\mu, \nu)$, the problem of

$$\mathbb{P}^{\text{diff}}(\mu, \nu) = \inf \left\{ \int_{\mathcal{X}} C((T_t x)_{0 \leq t \leq 1}) \mu(dx) : \begin{array}{l} T_0 = \text{Id}, T_1 \# \mu = \nu, \\ t \mapsto T_t x \text{ } C^1 \text{ (say)} \end{array} \right\}$$

When does \mathbb{P}^{diff} & \mathbb{P} yield the same value & transport $T = T_1$?

A sufficient condition is that $c(x, y) = \inf \{ C((z_t)_{t \in [0,1]}) : z_0 = x, z_1 = y \}$

If we have a nice diff structure then consider $C((z_t)) = \int_0^1 c(\dot{z}_t) dt$

ex $C((z_t)) = \int_0^1 \underbrace{|\dot{z}_t|^p}_{c(\dot{z}_t)} dt \text{ on } \mathbb{R}^n \Rightarrow c(x, y) = |x - y|^p, \quad p \geq 1$
 $\Rightarrow c(x, y)$ via Jensen

$C((z_t)) = \int_0^1 \|\dot{z}_t\|^p dt$ on a smooth complete \mathbb{R} -manifold $M \Rightarrow c(x, y) = d(x, y)^p, \quad p \geq 1$
 \hookrightarrow (2) minimally geodesics with arc length parametrization.
 \hookrightarrow optimal trajectory is straight line $z_t = x + t(y-x), \quad t \in [0, 1]$.

Then Intermediate optimality: $\mu, \nu \ll \text{Leb}, \quad c(x, y) = |x - y|^p, \quad p \geq 1$

$$T(x) = x - t \nabla c^*(\nabla \psi(x)) \quad \& \quad T_t = \text{Id} + t \cdot T \\ = x - t \nabla c^*(\nabla \psi)$$

$(\text{Id}, T) \# \mu$ is optimal & $\Pi(\mu, \nu)$ and

$$(\mathbb{D}, T_t) \# \mu \text{ is } \leftarrow \text{---} \mathbb{N}(\mu, T_t \# \mu) \text{ and}$$

$$(\overline{T}_t, \overline{T}) \# \mu \text{ ---} \leftarrow \mathbb{N}(\overline{T}_t \# \mu, \overline{T}).$$

$Q \subseteq \mathcal{P}(X)$ is convex iff $\forall \mu, \nu \in Q \quad t\mu + (1-t)\nu \in Q$

is displacement convex
(McCann) iff $\forall \mu, \nu \in Q \quad \mathcal{S}_t \in Q$

$$\mathcal{S}_t := T_t \# \mu$$

As it turns out a lot of important functionals $F: \mathcal{P}(X) \rightarrow \mathbb{R}$ are displacement convex (i.e., $t \mapsto F(\mathcal{S}_t)$ is convex)

Thm

If $U(x) \geq 0$ & $r \mapsto rU(r^{-n})$ is convex and increasing on $(0, \infty)$

then $U(\rho) = \int U(\rho(x)) dx$ is displacement convex

(internal energy) e.g. $U(x) = r|x|^\alpha$ (or ρ -tilde with density d .)

If $V: \mathbb{R}^n \rightarrow \mathbb{R} \cup \{\infty\}$ is convex then $V(\rho) = \int V d\rho$ is displacement convex
(potential energy)