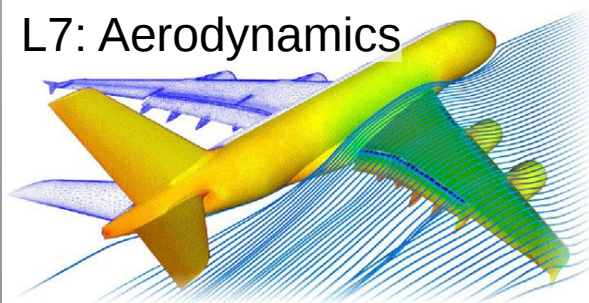
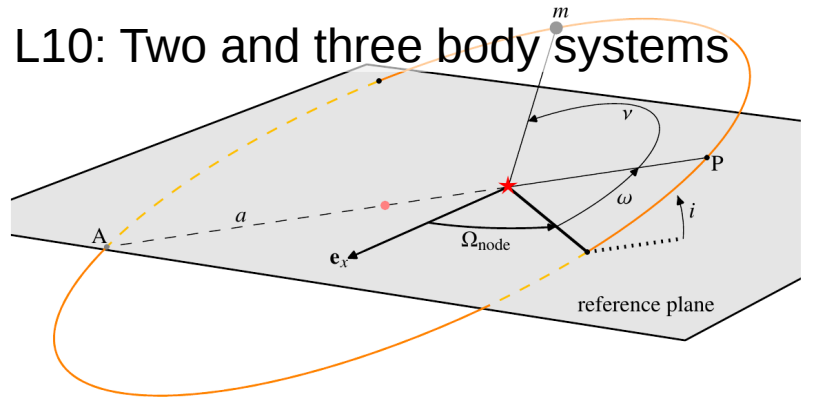


Part: II planet formation

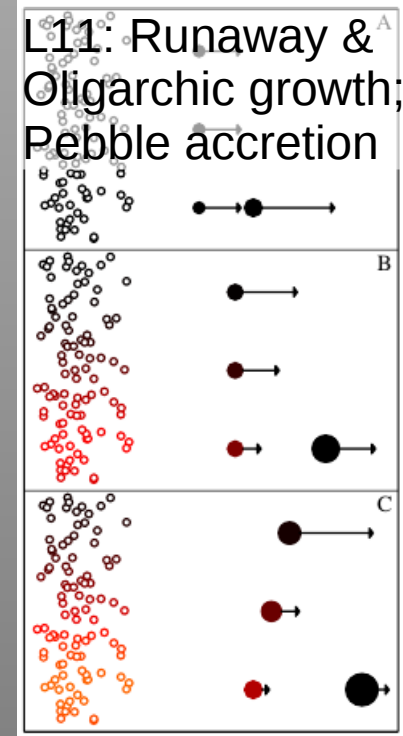
L7: Aerodynamics



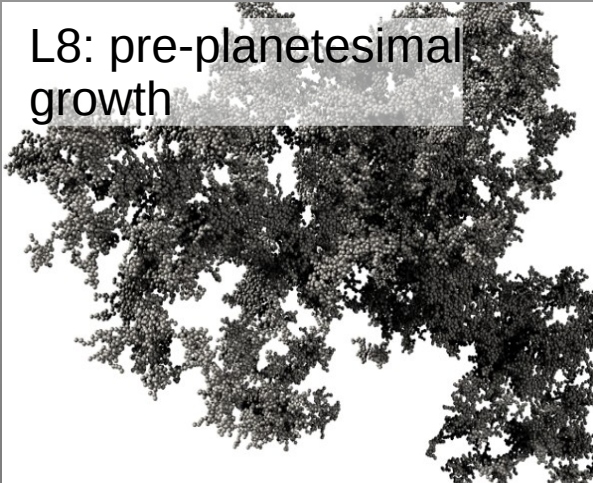
L10: Two and three body systems



L11: Runaway & Oligarchic growth; Pebble accretion



L8: pre-planetesimal growth



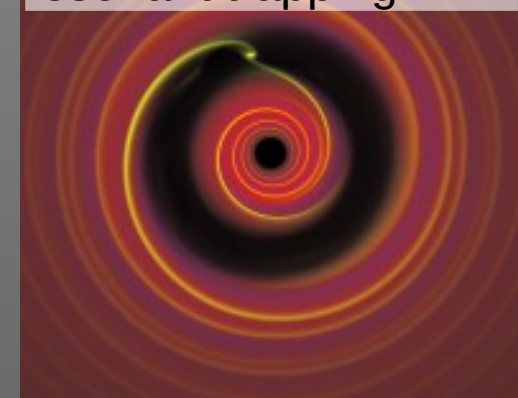
L9: Gravitational instability



L12: giant and terrestrial planet formation



L13: planet migration & resonant trapping



Read the lecture notes!

2.2 The 3-body problem

In the 3-body problem analytical (closed-form) solutions are no longer possible. A simplification of the 3-body problem is that of a massless particle being perturbed by a secondary (e.g. planet) that moves on a circular orbit around the primary (star). This is known as the circular, restricted 3-body problem CR₃BP. We will focus exclusively on this problem.

The equation of motion in a frame of reference rotating with angular frequency ω is:

$$\ddot{\mathbf{r}} = -\nabla\Phi - 2\boldsymbol{\omega} \times \dot{\mathbf{r}} - \boldsymbol{\omega} \times (\boldsymbol{\omega} \times \mathbf{r}) \quad (2.5)$$

In the CR₃BP we will of course choose $\boldsymbol{\omega} = n_p \mathbf{e}_z$ such that Φ – the gravitational potential – is time-independent in the rotating frame. Equation (2.5) can be integrated to give an integration constant J .*

$$J = \frac{1}{2}\dot{\mathbf{r}}^2 + \Phi - \frac{1}{2}(\boldsymbol{\omega} \times \mathbf{r})^2 \quad (2.6)$$

which is the *Jacobi energy*. In the 3-body problem it is the only integral of motion.

Exercise 2.2 Jacobi integral:

(a) Converting Equation (2.6) back to the inertial frame, show that:

$$J = E - \boldsymbol{\omega} \cdot \mathbf{l} = E - n_p l_z \quad (2.7)$$

where E and \mathbf{l} are the energy and angular momentum measured in the inertial frame. Hence, in the CR₃BP interactions will exchange E and \mathbf{l} , while J stays constant.

(b) Express J in orbital elements:

$$J = -\frac{Gm_*}{2a} - n_p \sqrt{Gm_* (1 - e^2) a} \cos i \quad (2.8)$$

where n_p is the mean motion of the secondary and the other symbols refer to the test particle. Written in the form of Equation (2.8) (or analogous) the Jacobi integral is called the *Tisserand relation*.

(c) Let $a = a_p + b$ with a_p the semimajor axis corresponding to n_p and consider the limits where $b/a_0 \ll 1$, $i \ll 1$ and $e \ll 1$. Show that in this case:

$$J \approx \frac{Gm_*}{a_p} \left(-\frac{3}{8} \frac{b^2}{a_p^2} + \frac{e^2 + i^2}{2} \right) \quad (2.9)$$

where we have discarded a constant term from J .

It is instructive to redefine the potential in Equation (2.5), incorporating the centrifugal term:[†]

$$\Phi_{\text{eff}} \equiv \Phi_1 + \Phi_2 - \frac{1}{2}n_p^2 r^2 = -\left[\frac{Gm_*}{r_1} + \frac{1}{2}n_p^2 r^2 \right] + \Phi_2 \quad (2.10)$$

where we used the identity $\frac{1}{2}\nabla^2 r^2 = r$. Consider the motion of the test particle in the vicinity of m_2 , see Figure 2.4, and express the potential in local coordinates (x, y) centered on m_2 . This amounts to expanding the inverse distance $1/r_1$ in terms of (the small) x and y .[‡]

* To see this, multiply Equation (2.5) by $\dot{\mathbf{r}}$ and write all terms as time-differentials (d/dt): $\frac{d}{dt}(\dot{\mathbf{r}}^2/2) = \dot{\mathbf{r}} \cdot \ddot{\mathbf{r}}$, $\frac{d\Phi}{dt} = \dot{\mathbf{r}} \cdot \nabla\Phi$, and $\frac{d}{dt}(\boldsymbol{\omega} \times \mathbf{r})^2/2 = [\boldsymbol{\omega} \times \boldsymbol{\omega} \times \mathbf{r}] \cdot \mathbf{r}$. Also, $\dot{\mathbf{r}} \cdot (2\boldsymbol{\omega} \times \dot{\mathbf{r}}) = 0$.

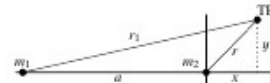


Figure 2.4: Definitions of x and y in Hill's approximation of the CR₃BP.

[†] In celestial mechanics text books it is customary to define Φ_{eff} with the opposite sign.

[‡] this becomes $r_1^{-1} \approx 1/a_2 - x/a_2^2 + x^2/a_2^3 - \frac{1}{2}y^2/a_2^3 - \frac{1}{2}z^2/a_2^3$. The leading (constant) term of the expansion can be discarded from Φ_{eff} as it is a potential function. In addition, in Equation (2.11) we assumed that $m_1 \gg m_2$ such that $Gm_1 \approx n_p^2 a_2^3$.

The result is (Hill's approximation):

$$\Phi_{\text{eff}} = -\frac{3}{2}n_p^2 x^2 + \frac{1}{2}n_p^2 z^2 - \frac{Gm_2}{r} \quad (2.11)$$

with which the Jacobi energy is written:

$$J = \frac{1}{2}\dot{\mathbf{r}}^2 + \Phi_{\text{eff}} \quad (2.12)$$

Contours of $\Phi_{\text{eff}}(x, y)$ are known as *zero velocity curves*; they define the region where a particle of a certain J can move, since $\Phi_{\text{eff}} = J - \frac{1}{2}\dot{\mathbf{r}}^2 \leq J$. Therefore, although the 3-body problem is not integrable, given J , we can constrain the regions where particles can be found. Figure 2.5 shows contours of constant Φ_{eff} with lighter contours having larger Φ_{eff} . The regions bounded by high Φ_{eff} (the darker contours) are therefore not accessible for low-energy particles (low J). In particular, the high Φ_{eff} zero velocity curves have a horseshoe shape and the corresponding orbits are referred to as *horseshoe orbits* as they make a U-turn. It must be emphasized however that in general particles do not follow the zero velocity contours as $\dot{\mathbf{r}}$ is a function of time. Figure 2.6 gives examples of particle trajectories obtained from integrating Hill's equation of motion. Three types of orbits can be seen:

- *Horseshoe orbits*, which make a U-turn (impact parameter $b \lesssim 1.7R_{\text{Hill}}$);
- *Hill-penetrating orbits*. They are strongly excited after they leave the Hill sphere ($1.7R_{\text{Hill}} \lesssim b \lesssim 2.5R_{\text{Hill}}$);
- *Circulating orbits*, which are only modestly excited. ($b \gtrsim 2.5R_{\text{Hill}}$).

Exercise 2.3 Hill's equations:

(a) Show that the equations of motion in Hill's approximation are:

$$\ddot{x} = -\frac{Gm_p}{r^3}x + 2n_p v_y + 3n_p^2 x \quad (2.13a)$$

$$\ddot{y} = -\frac{Gm_p}{r^3}y - 2n_p v_x \quad (2.13b)$$

where $r^2 = x^2 + y^2$ if we restrict the motion to the orbital plane.

(b) Show that zero eccentricity particles at distances far from the secondary obey $v_y = -\frac{3}{2}n_p x$ and $v_x = 0$. This (local) approximation of the Keplerian flow is known as the *shearing sheet*.

(c) Equilibrium points are points where $\ddot{\mathbf{r}} = \dot{\mathbf{r}} = 0$. Show that these *Lagrange points* are located at $(x, y) = (\pm R_{\text{Hill}}, 0)$ where R_{Hill} is the *Hill radius*:

$$R_{\text{Hill}} = a_p \left(\frac{m_p}{3m_*} \right)^{1/3} \quad (2.14)$$

(d) Are these stable or unstable equilibrium points?

(e) What is the Jacobi constant at the Lagrange point (J_L)? And what is the Jacobi constant far from the perturber (J_∞), assuming $e = 0$. What is the half-width x_{hs} of the corresponding horseshoe orbit?

From this section it is clear that particles that enter the Hill sphere do so at a velocity $\sim R_{\text{Hill}} n_p$ – the *Hill velocity*. This is therefore the minimum (relative) velocity at which the gravitational scattering takes

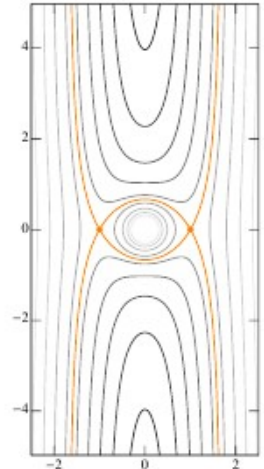


Figure 2.5: Zero velocity curves (contours of Φ_{eff}) in the $z = 0$ plane. Contours of larger Φ_{eff} are darker. The Lagrange equilibrium points L_1 and L_2 are indicated by circles. Distances are in units of Hill sphere. Curves are *not* orbits.

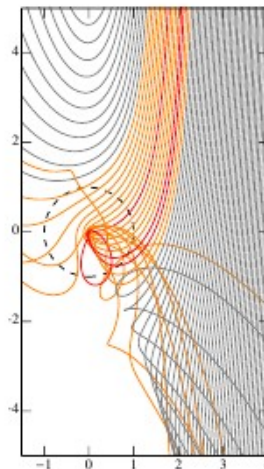
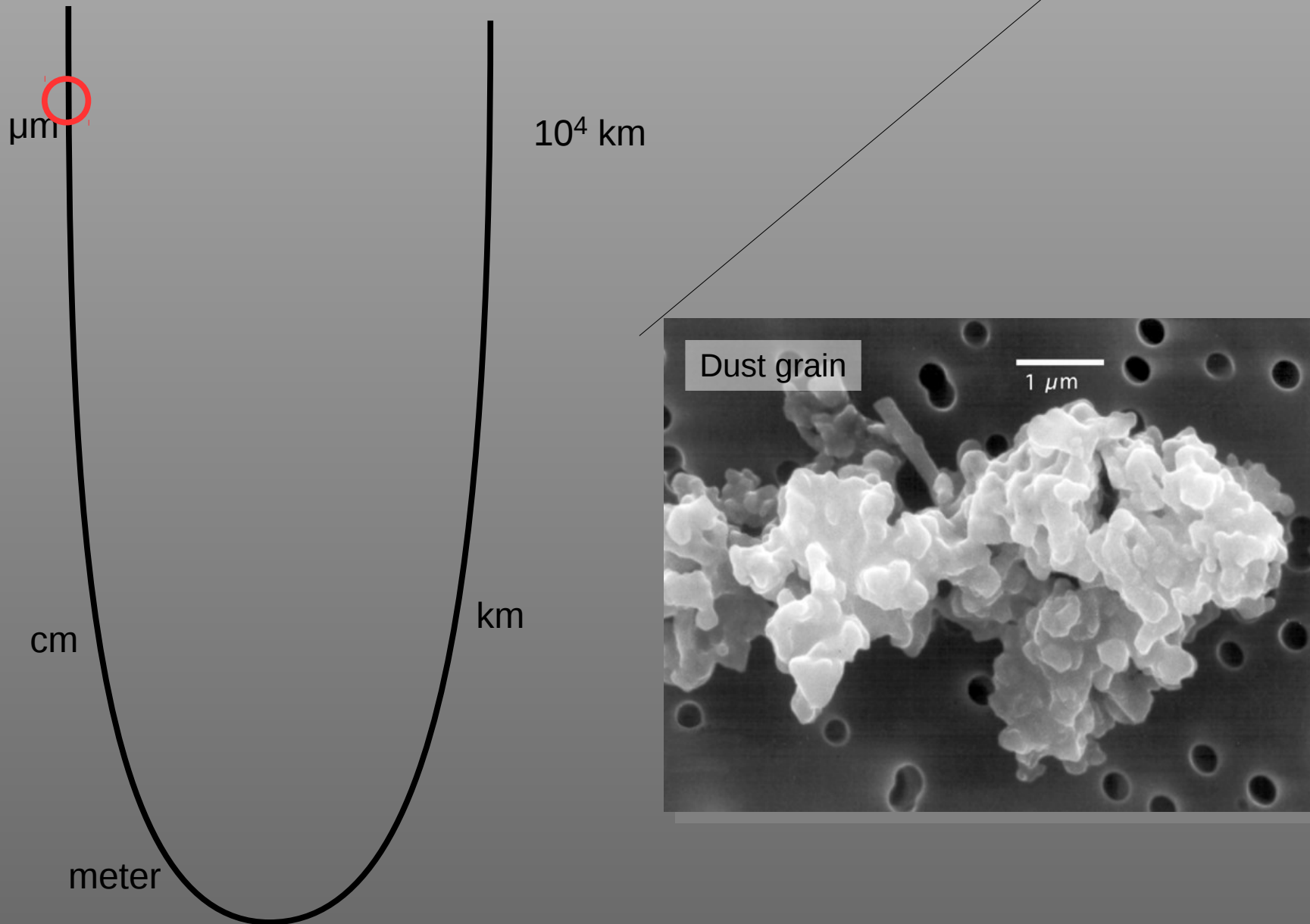
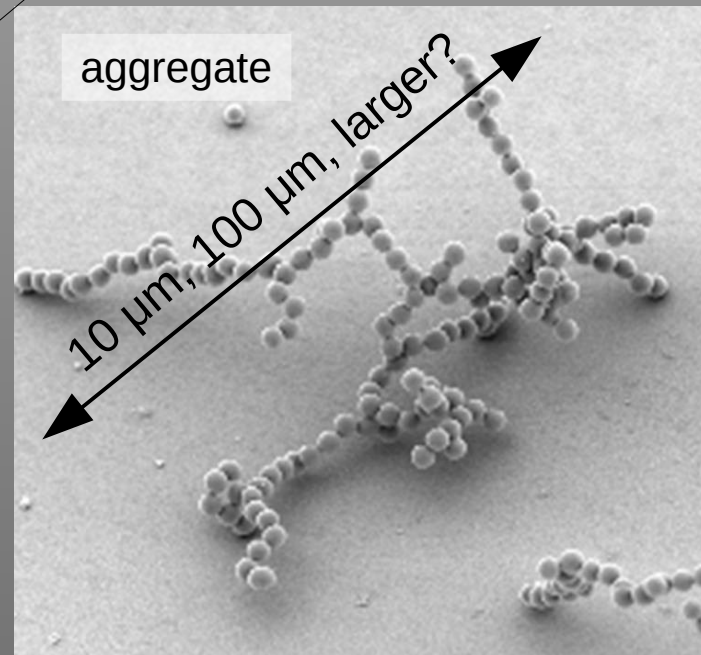
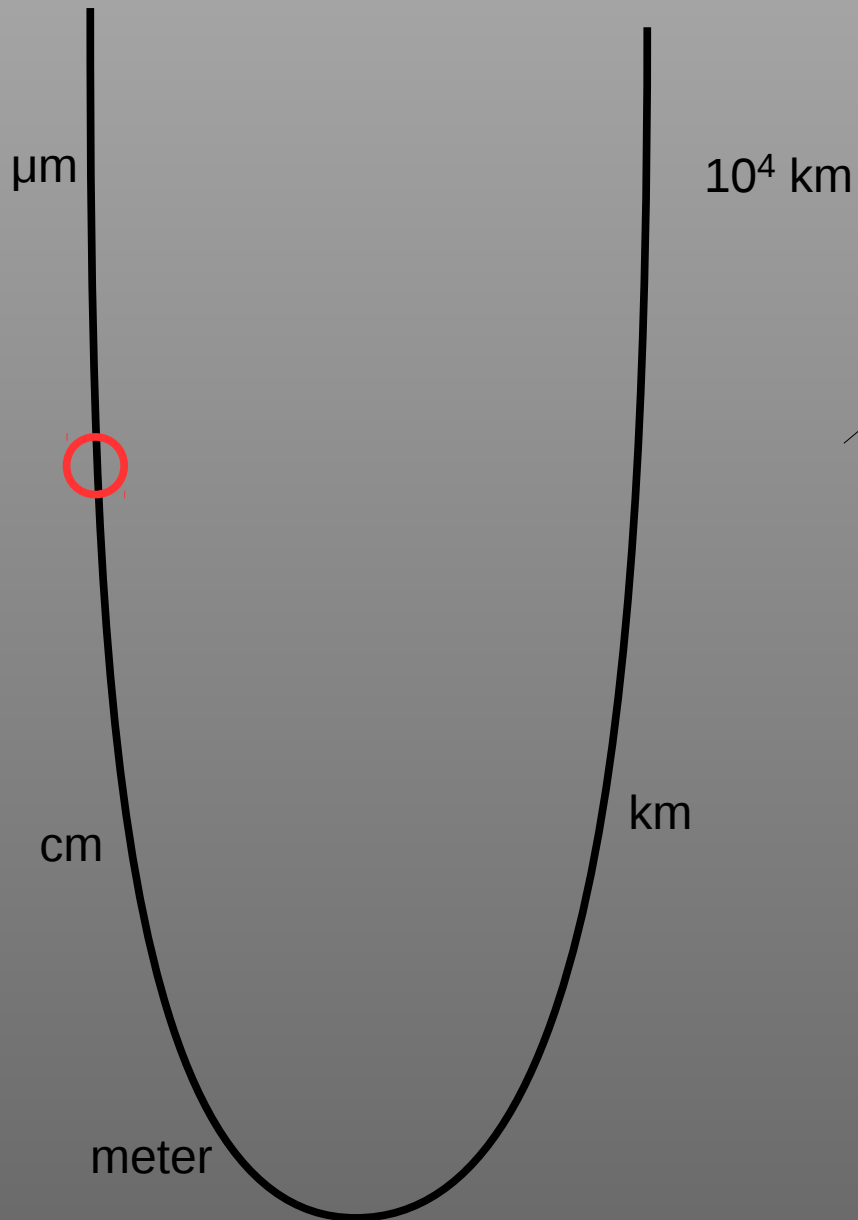


Figure 2.6: Examples of particle trajectories (initially on circulating orbits) in the CR₃BP, obtained by integrating Equation (2.13). Particles that enter the Hill sphere (dashed circle) are highlighted. Red streams hit the planet ($R < R_p = 5 \times 10^{-3} R_{\text{Hill}}$).

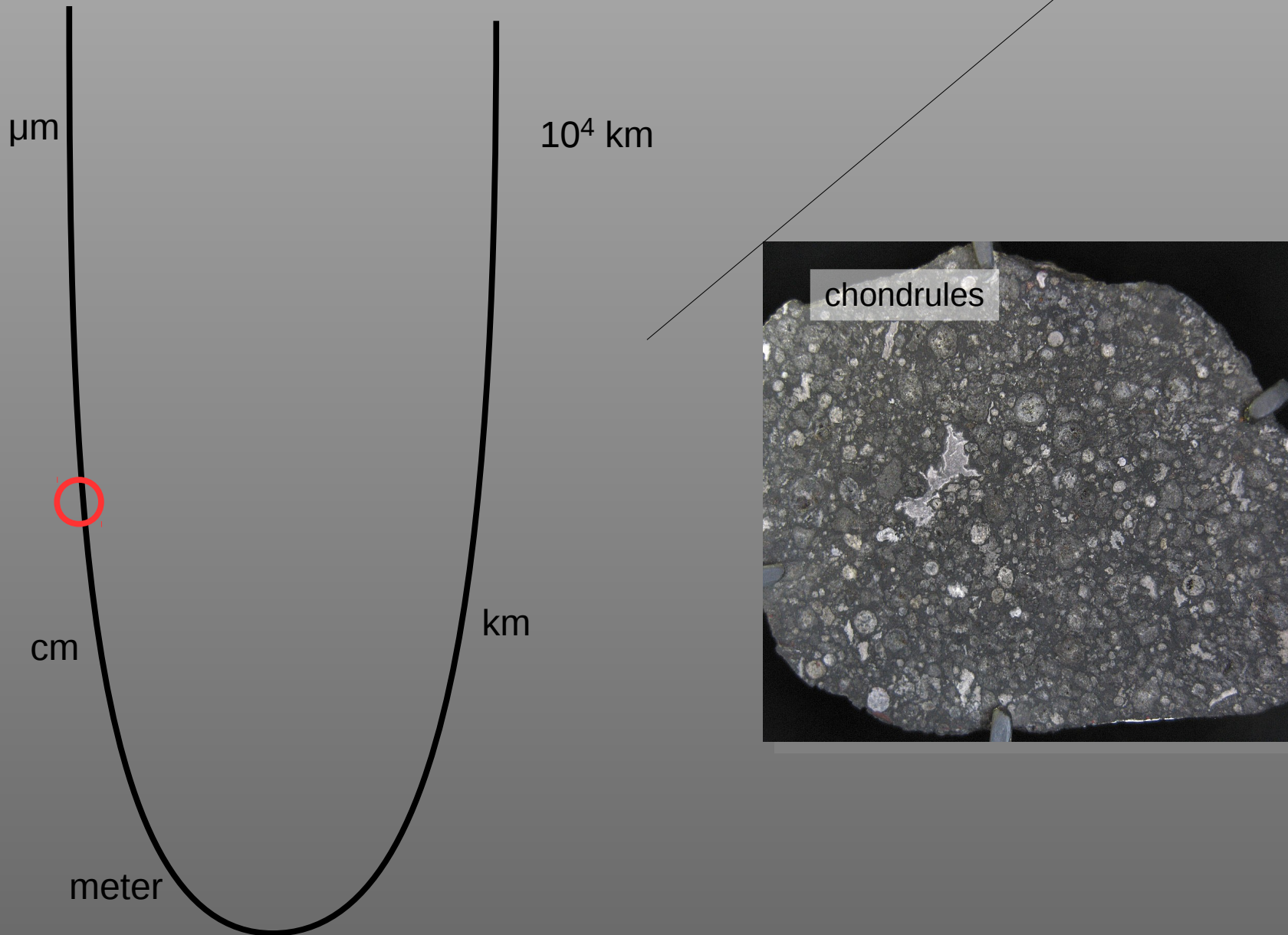
Planetary sizes



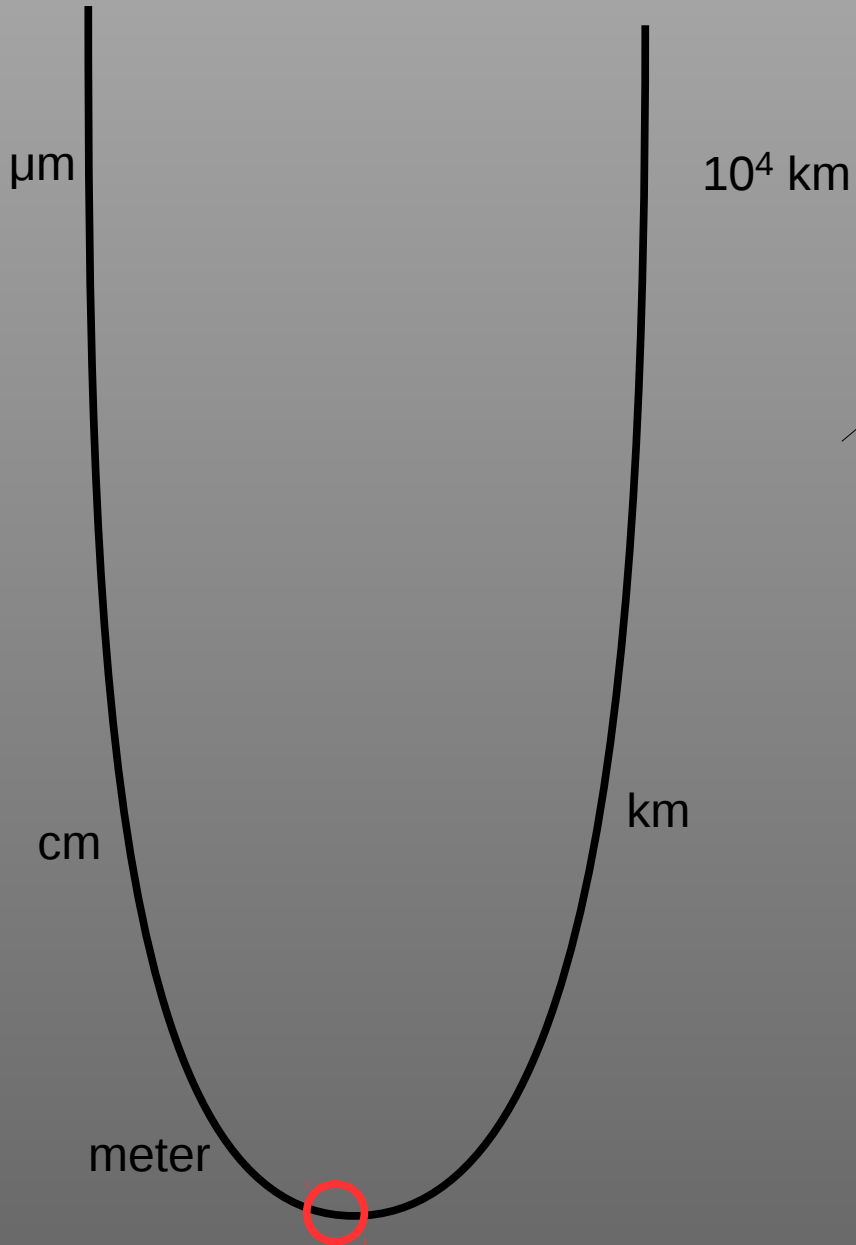
Planetary sizes



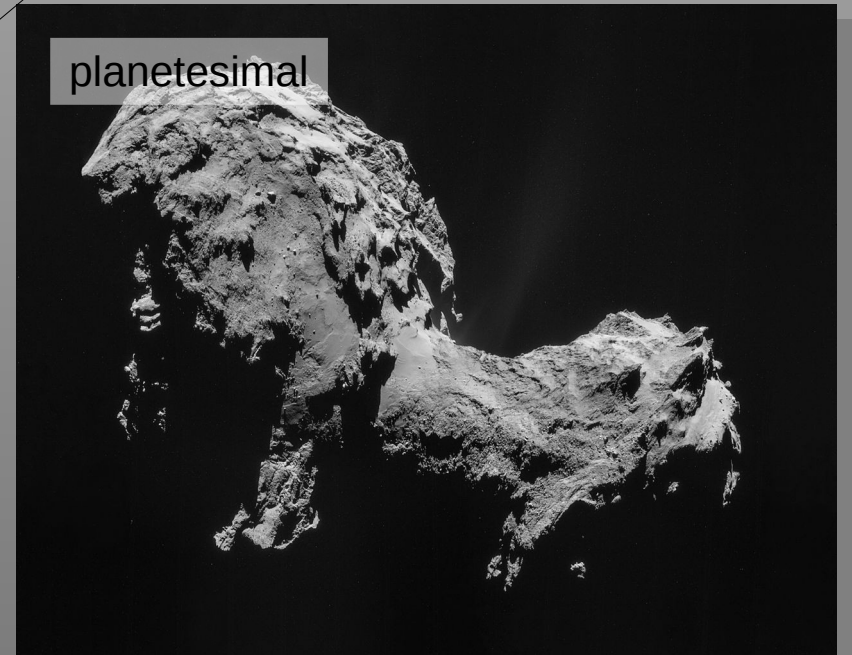
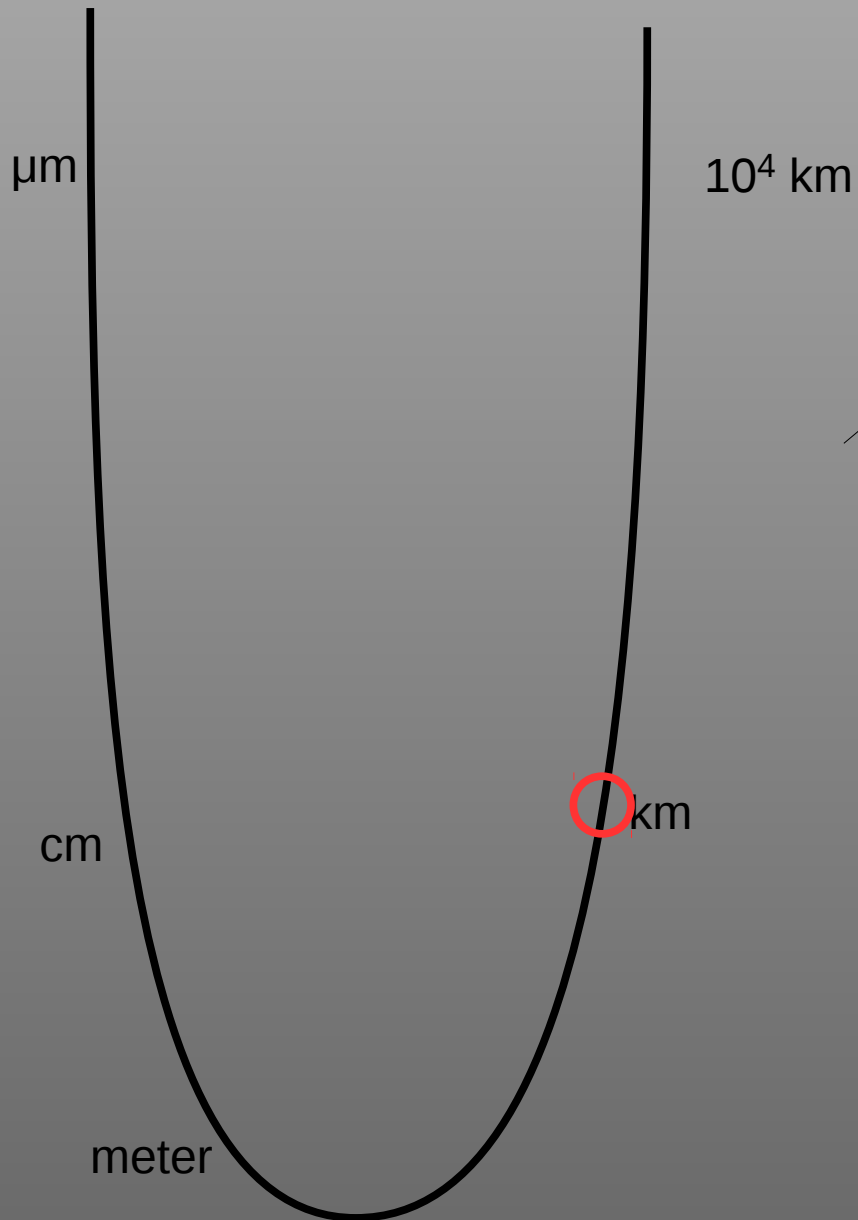
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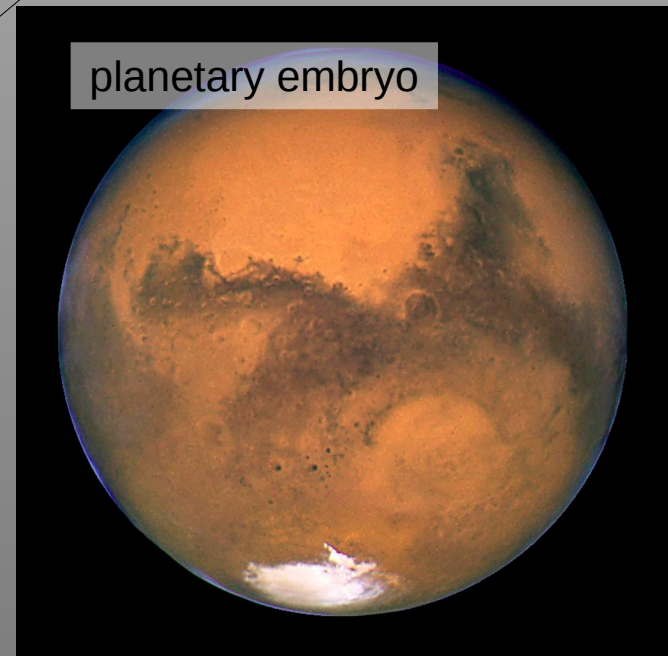
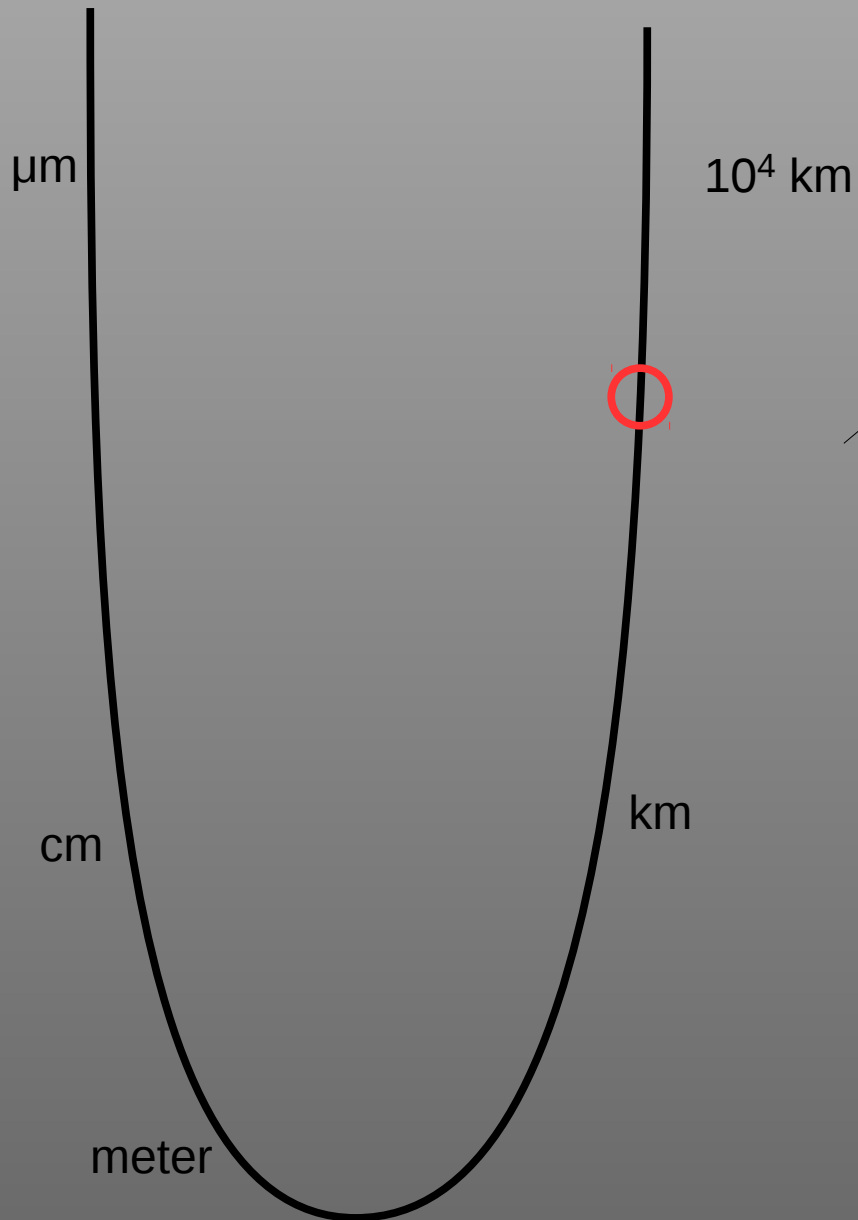
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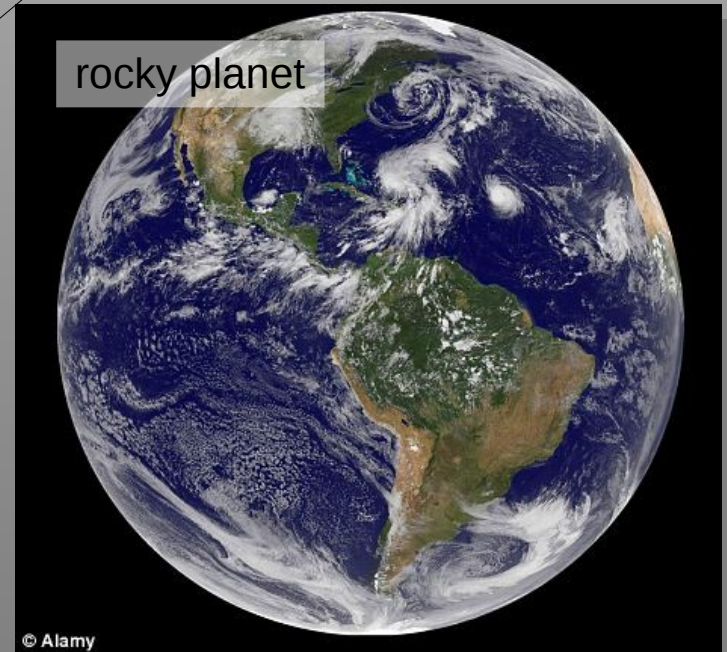
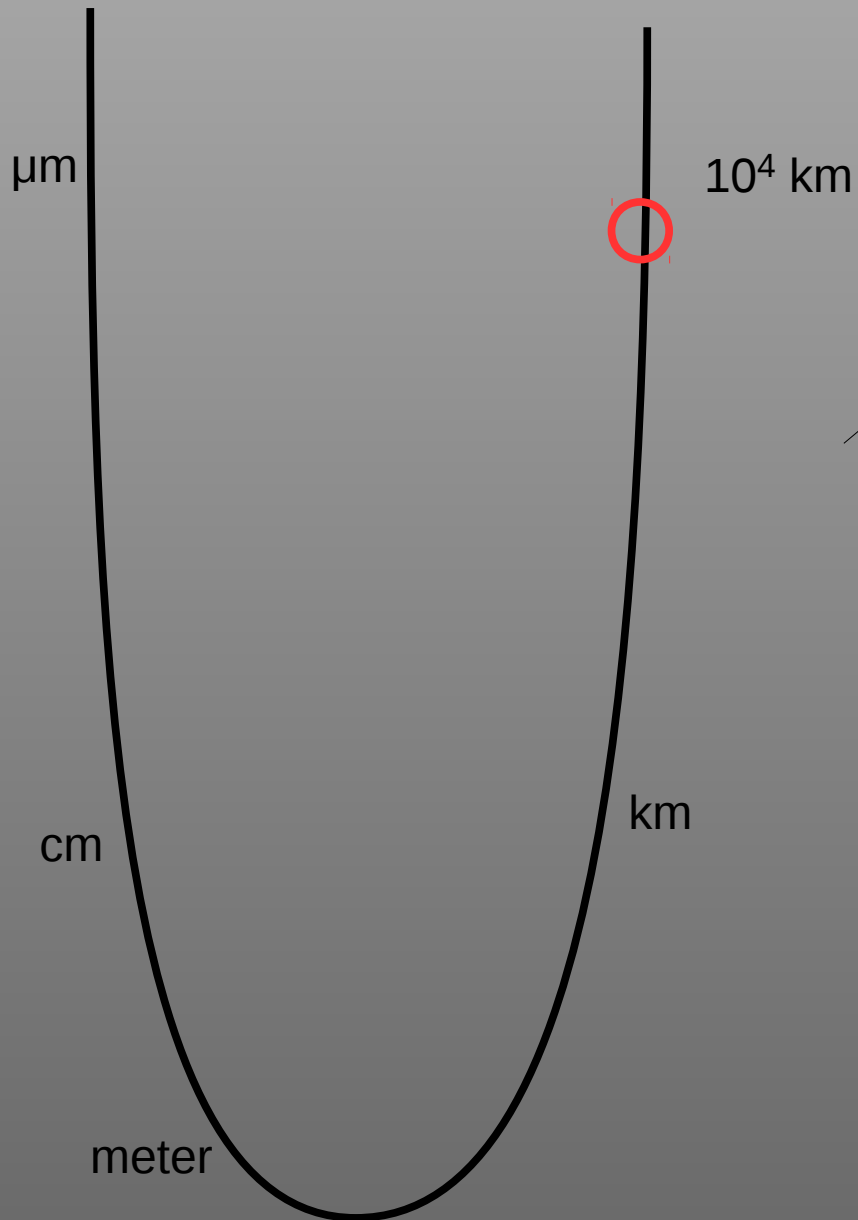
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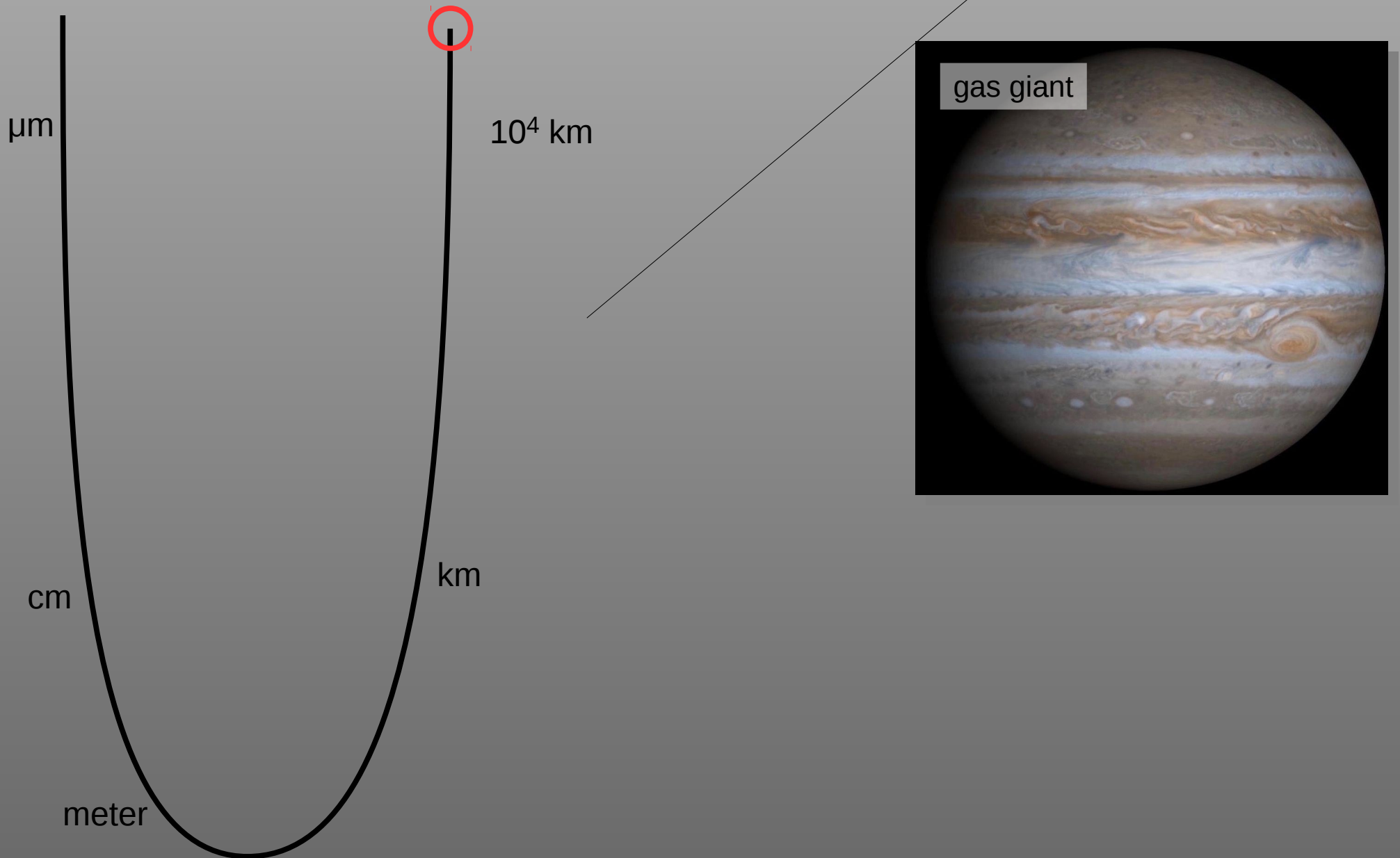
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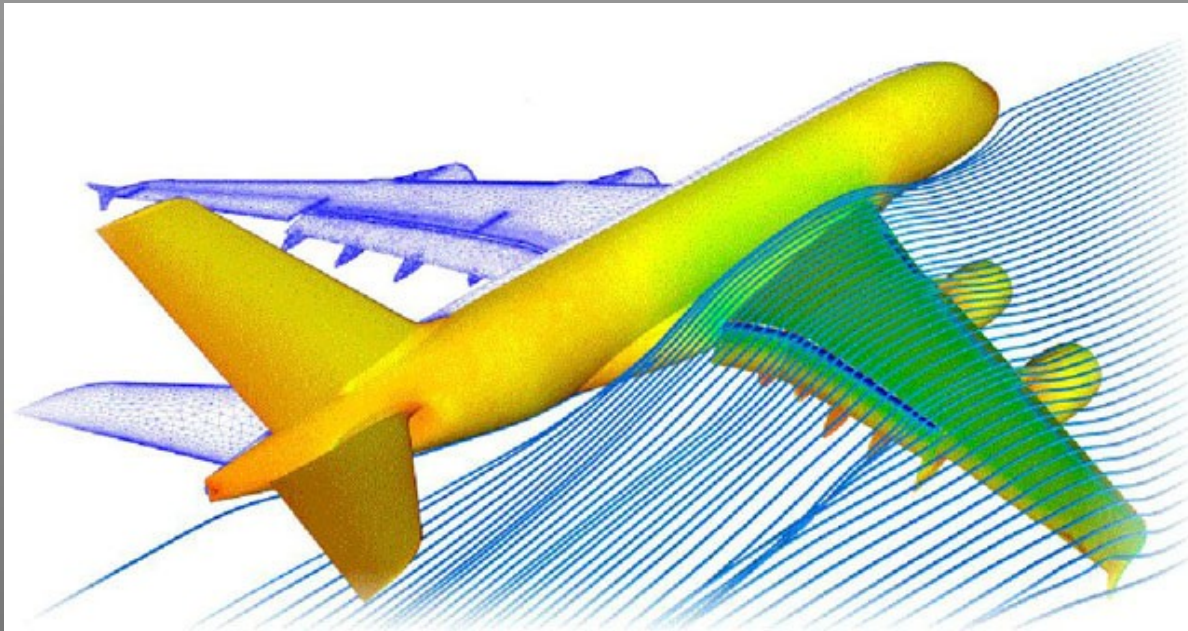
Planetary sizes



Planetary sizes



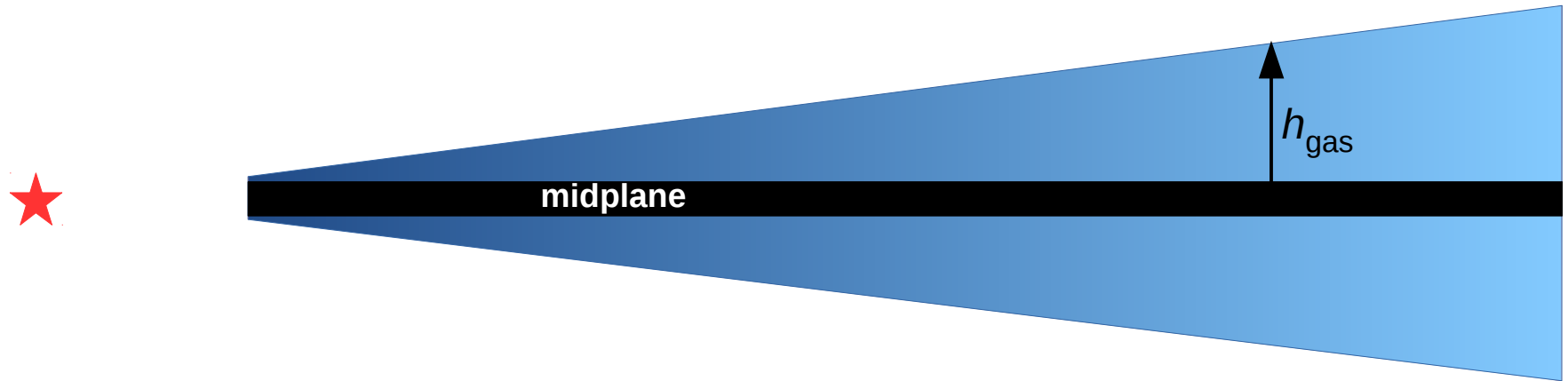
L7: Particle aerodynamics



Lecture 7: Particle Aerodynamics

- Intro particle sizes
- Disk review
 - MMSN, disk “headwind”
- Aerodynamics
 - gas drag laws, Reynolds numbers, stopping time, radial and azimuthal drift, orbital decay, meter-size problem, Brownian motion, random vs. systematic motions.
- Turbulence-induced velocities
 - Kolmogorov fully developed turbulence theory, large/small eddies
- Relative velocities
 - Turbulence, total

Review: the (idealized) gas disk



- **properties PPD:**

- *thin*, $h_{\text{gas}}/r \ll 1$, and *flared*

- scaleheight: $h_{\text{gas}} = c_s/\Omega_K$

- isothermal & pressure-supported in z

- *partly* pressure-supported in r

- gas rotates sub Keplerian: $u_{\text{gas}} \approx v_K - \eta v_K$

$$\rho_{\text{gas}}(z) = \frac{\Sigma_{\text{gas}}(r)}{\sqrt{2\pi} h_{\text{gas}}} \exp\left[-\frac{1}{2} \left(\frac{z}{h_{\text{gas}}}\right)^2\right]$$

$$g_{\text{hs}} = \frac{1}{\rho_{\text{gas}}} \frac{dP}{dr}$$

Minimum-mass solar nebula

(Weidenschilling 1977, Hayashi et al. 1985)

Assume power-laws:

$$\Sigma_{\text{gas}} = \Sigma_1 \left(\frac{r}{\text{AU}} \right)^{-p}, \quad T_{\text{gas}} = T_1 \left(\frac{r}{\text{AU}} \right)^{-q}$$

MMSN choices (Hayashi et al. 1985):

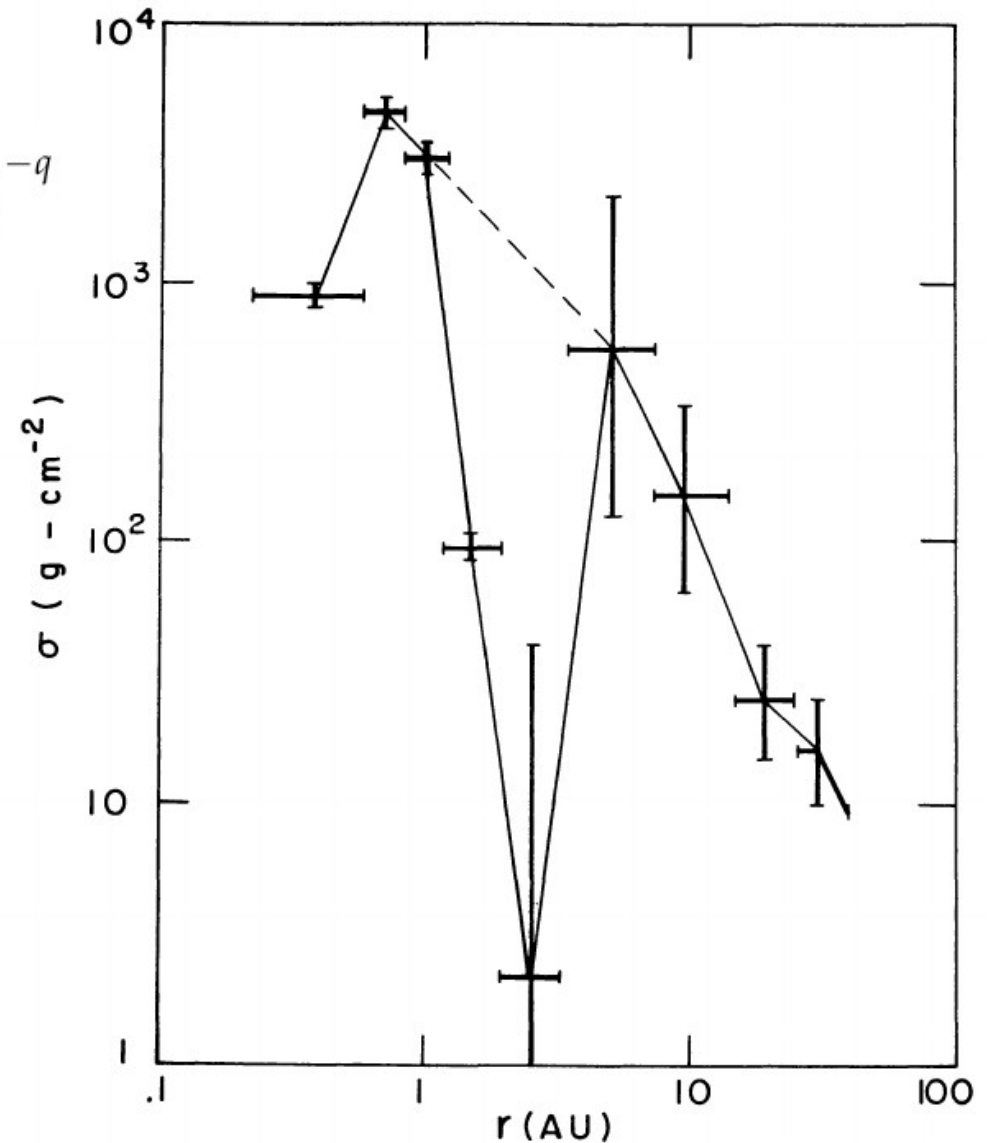
$$p = 1.5, \quad q = 0.5,$$

$$T_1 = 300 \text{ K}; \quad \Sigma_1 = 1700 \text{ g cm}^{-2}$$

Q: Criticism of MMSN model:

1.
2.

Other choices for $\Sigma(r)$, $T(r)$ possible and arguably physically (or observationally) more plausible!



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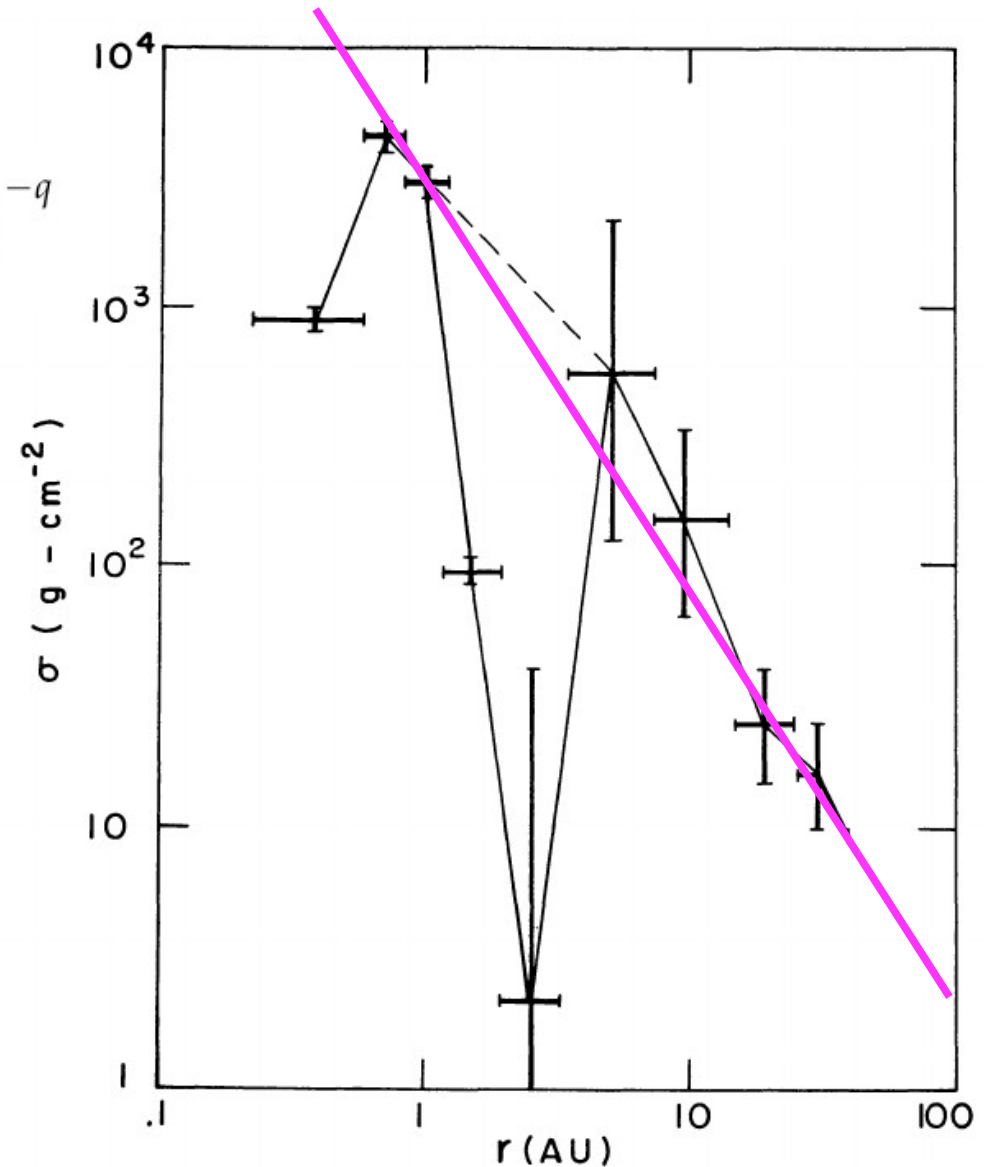
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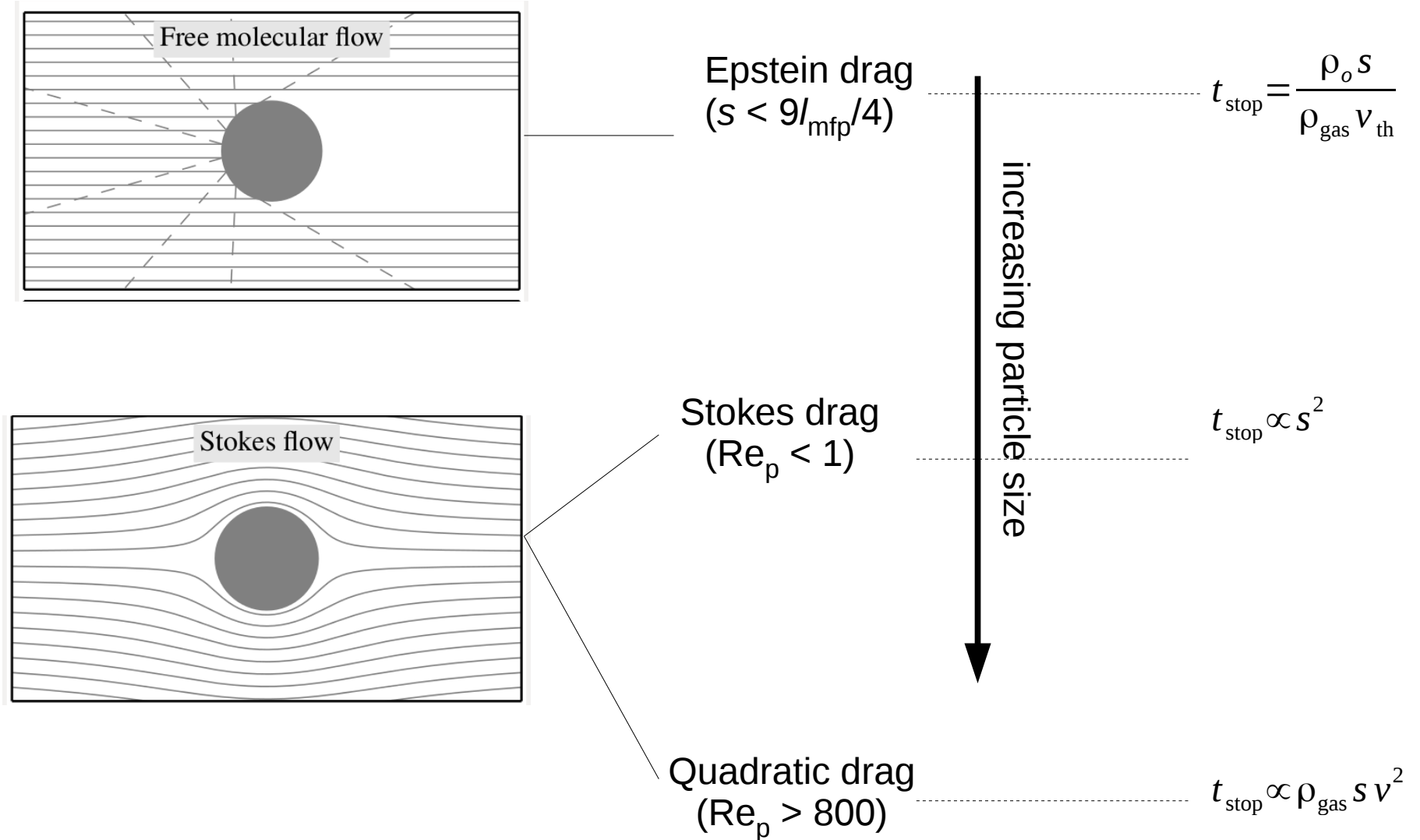
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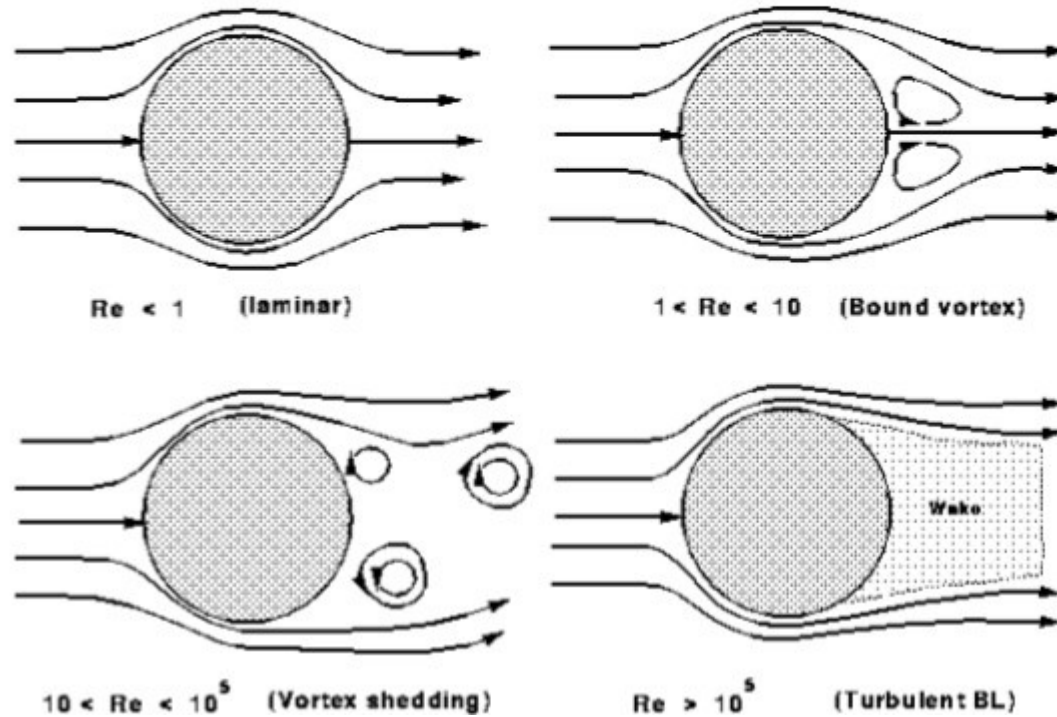
Blackboard

- gas drag low & (dimensionless) stopping time, particle Reynolds number
Epstein/Stokes regimes
- headwind derivation ηv_K ;
formal derivation for drift velocities
orbital decay timescale
- Brownian motion
systematic vs. random motions

Drag regimes



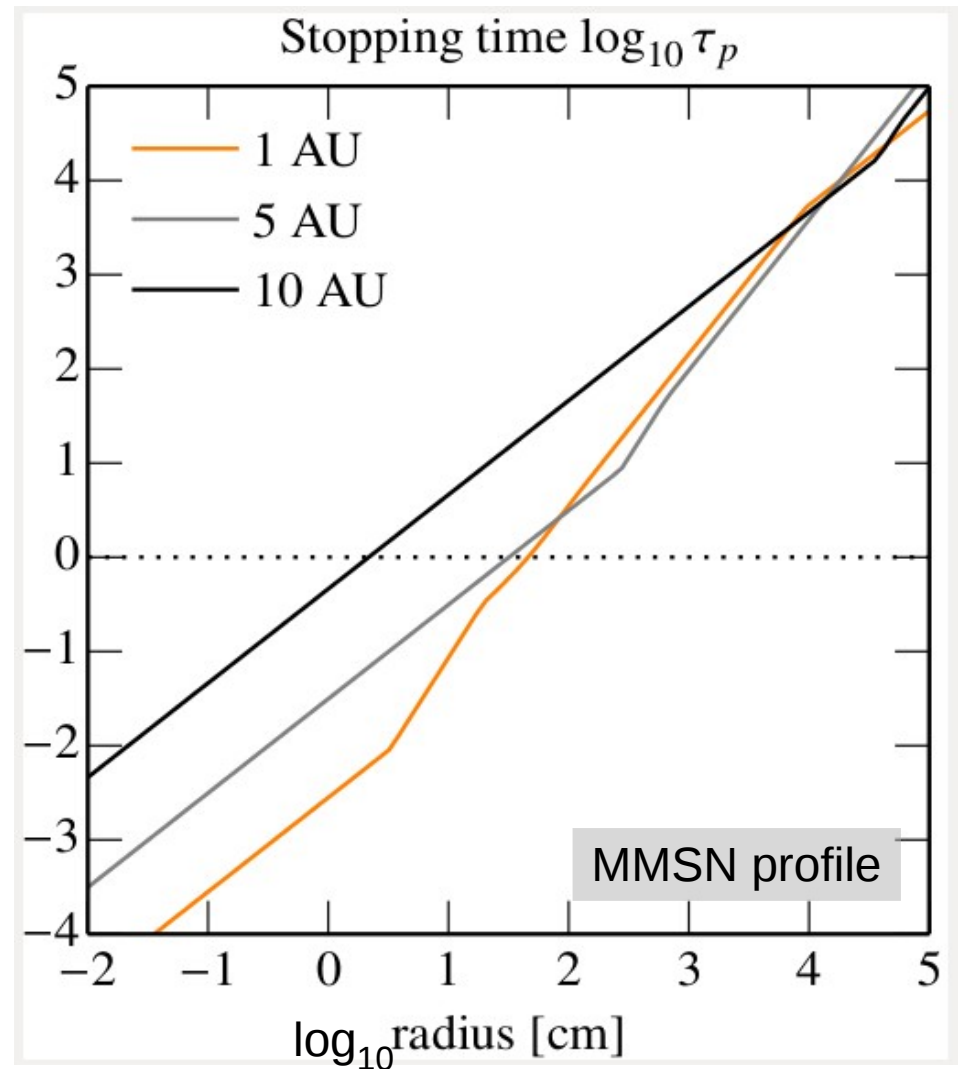
Gas drag/ Flow past sphere/cylinder



Dimensionless stopping time $\tau_p = t_{\text{stop}}\Omega_K$

Aerodynamical definition:

- pebble ($\tau_p < 1$)
- planetesimal ($\tau_p \gg 1$)

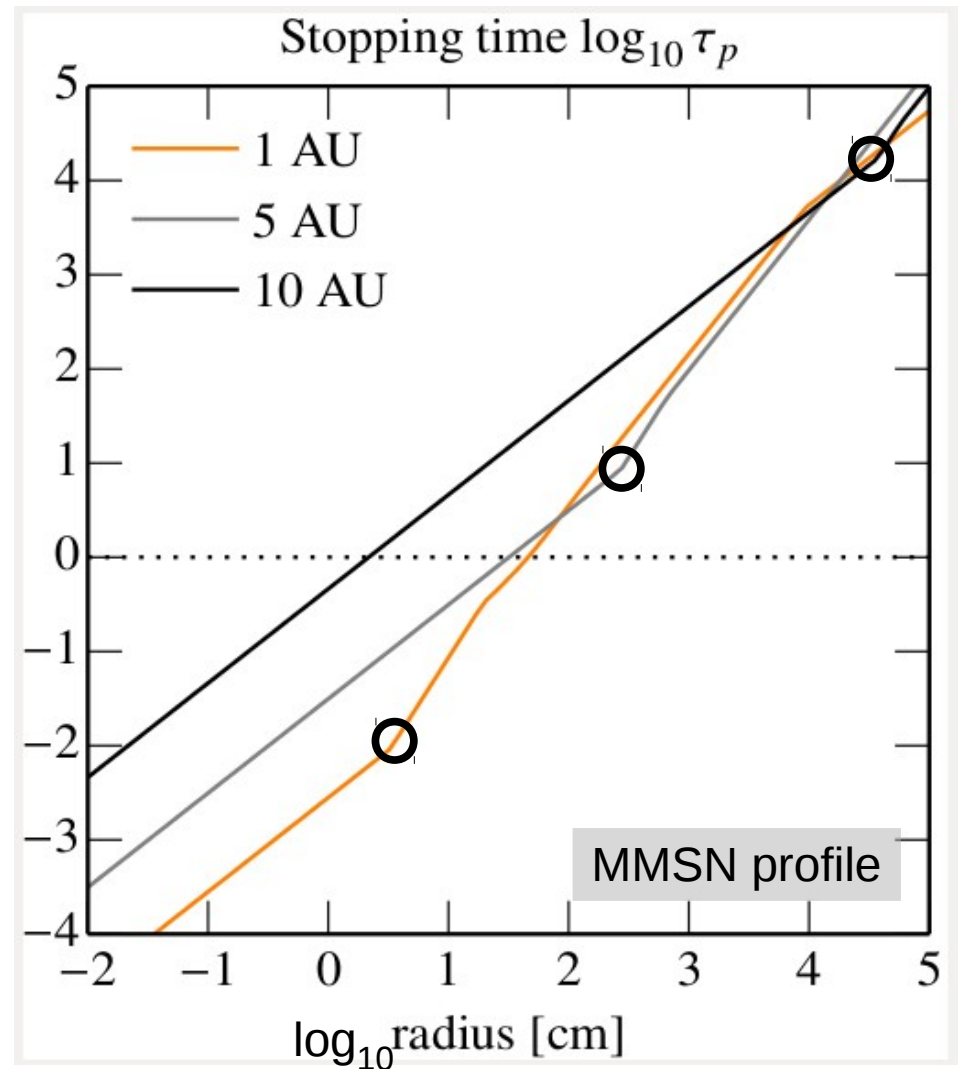


Dimensionless stopping time $\tau_p = t_{\text{stop}}\Omega_K$

Aerodynamical definition:

- pebble ($\tau_p < 1$)
- planetesimal ($\tau_p \gg 1$)

Q: why these inflections?



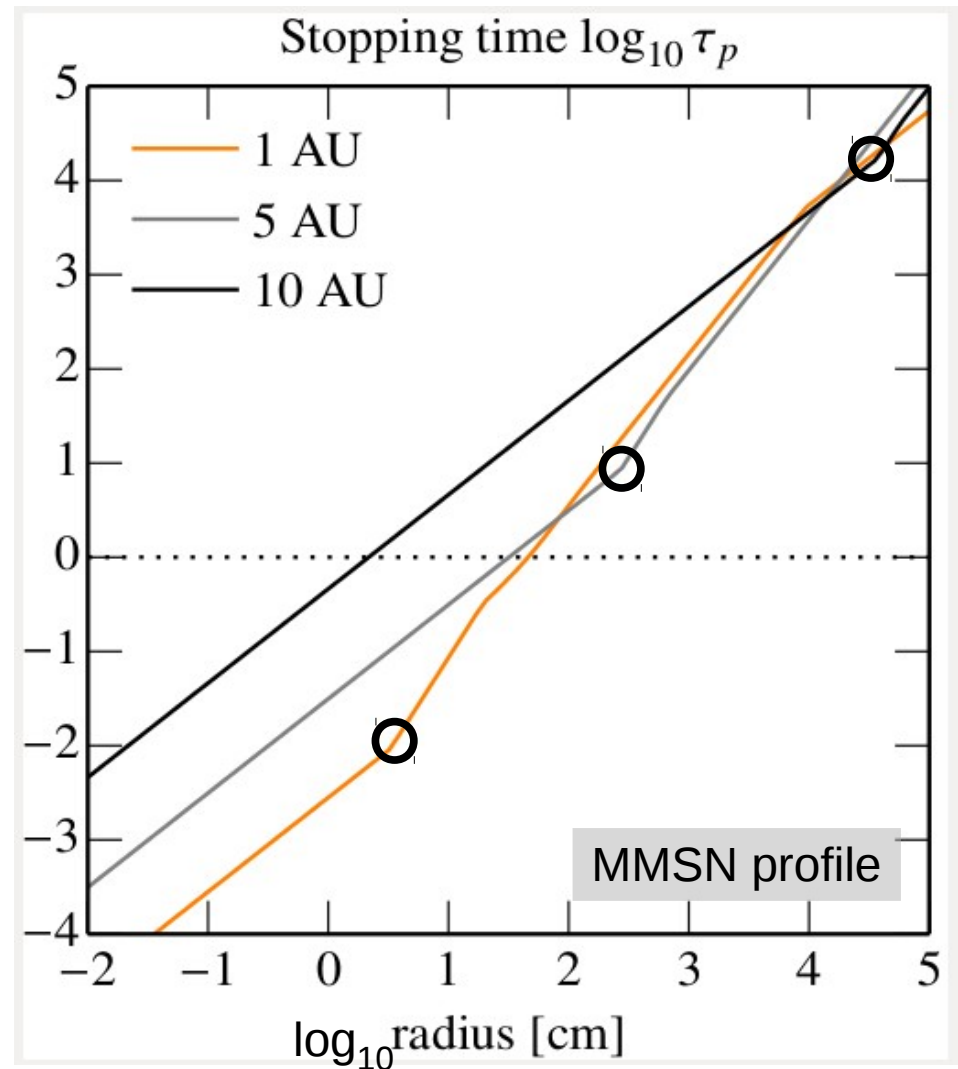
Dimensionless stopping time $\tau_p = t_{\text{stop}} \Omega_K$

Aerodynamical definition:

- pebble ($\tau_p < 1$)
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Q: why these inflections?

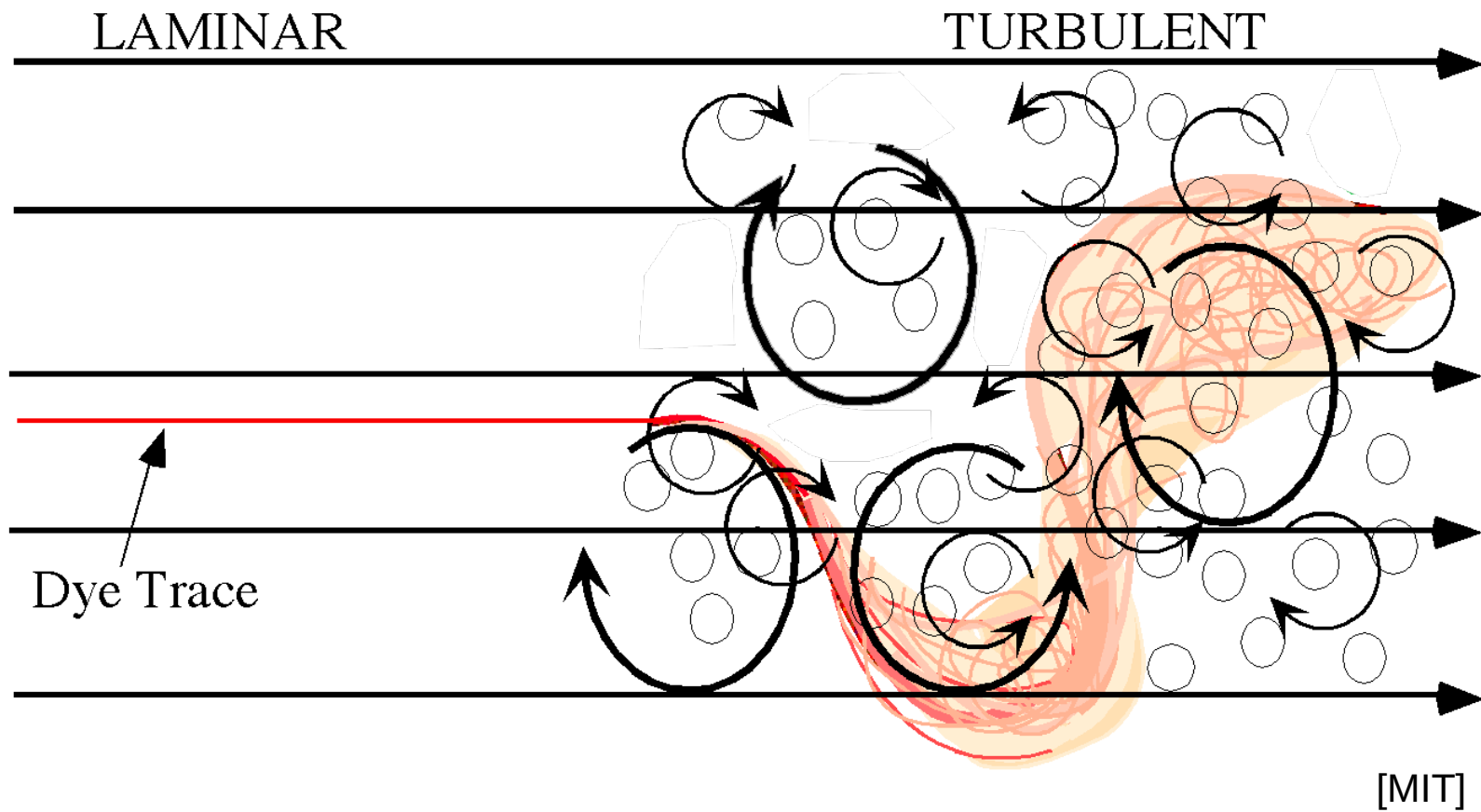
Q: what happens to t_{stop} when the gas disappears?



Turbulence

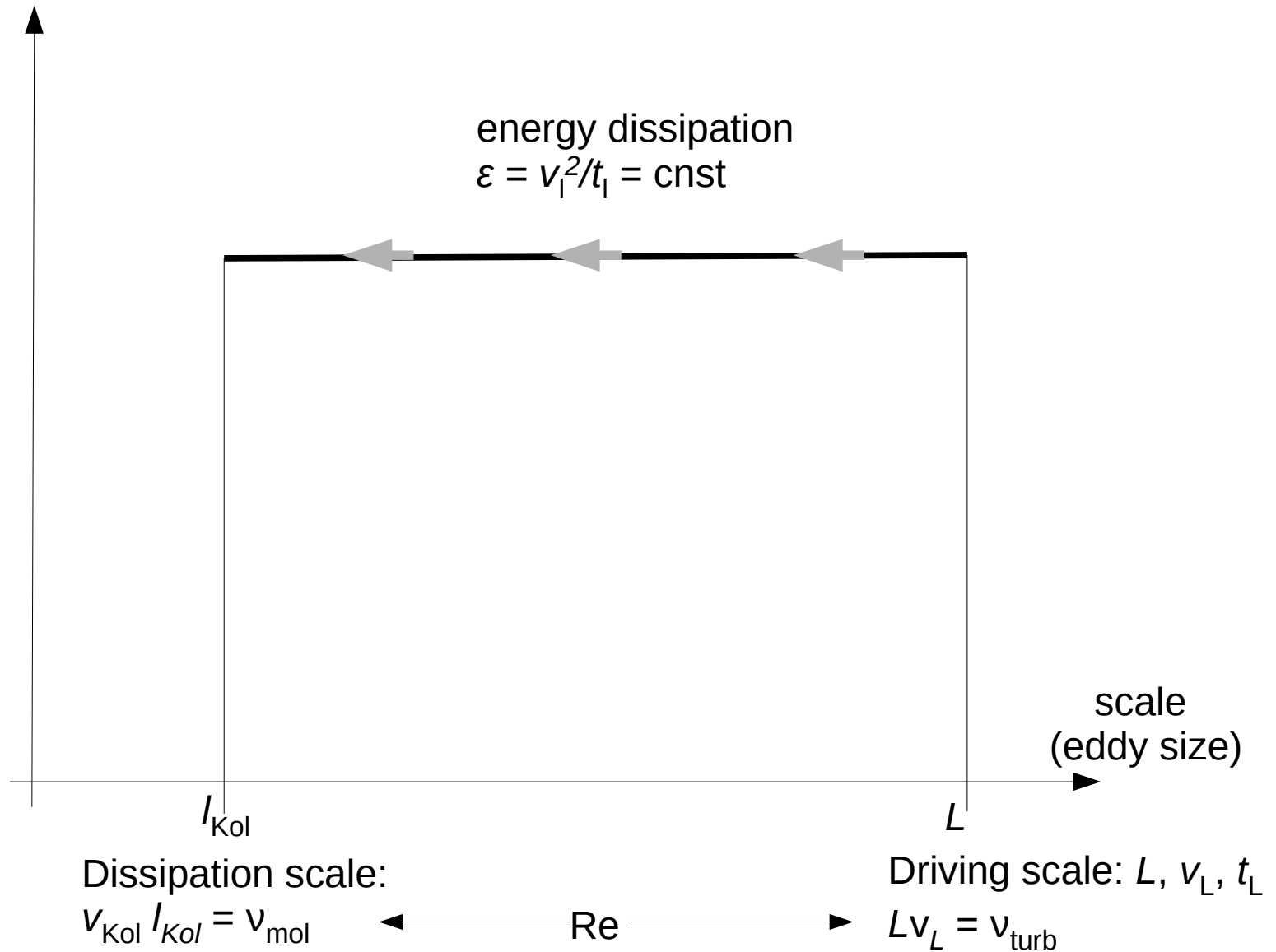


Eddies...



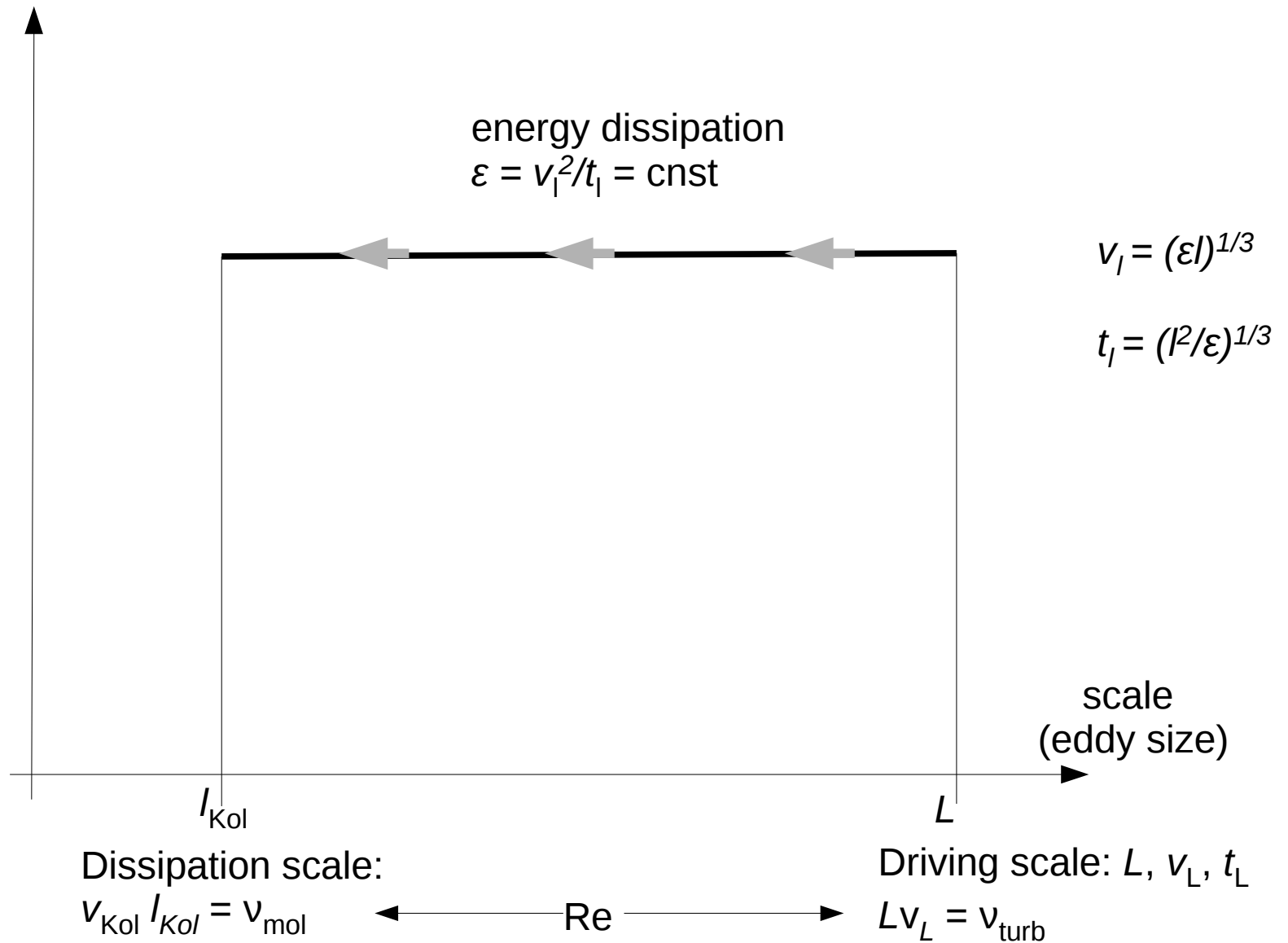
Fully developed turbulence

(Kolmogorov 1941)

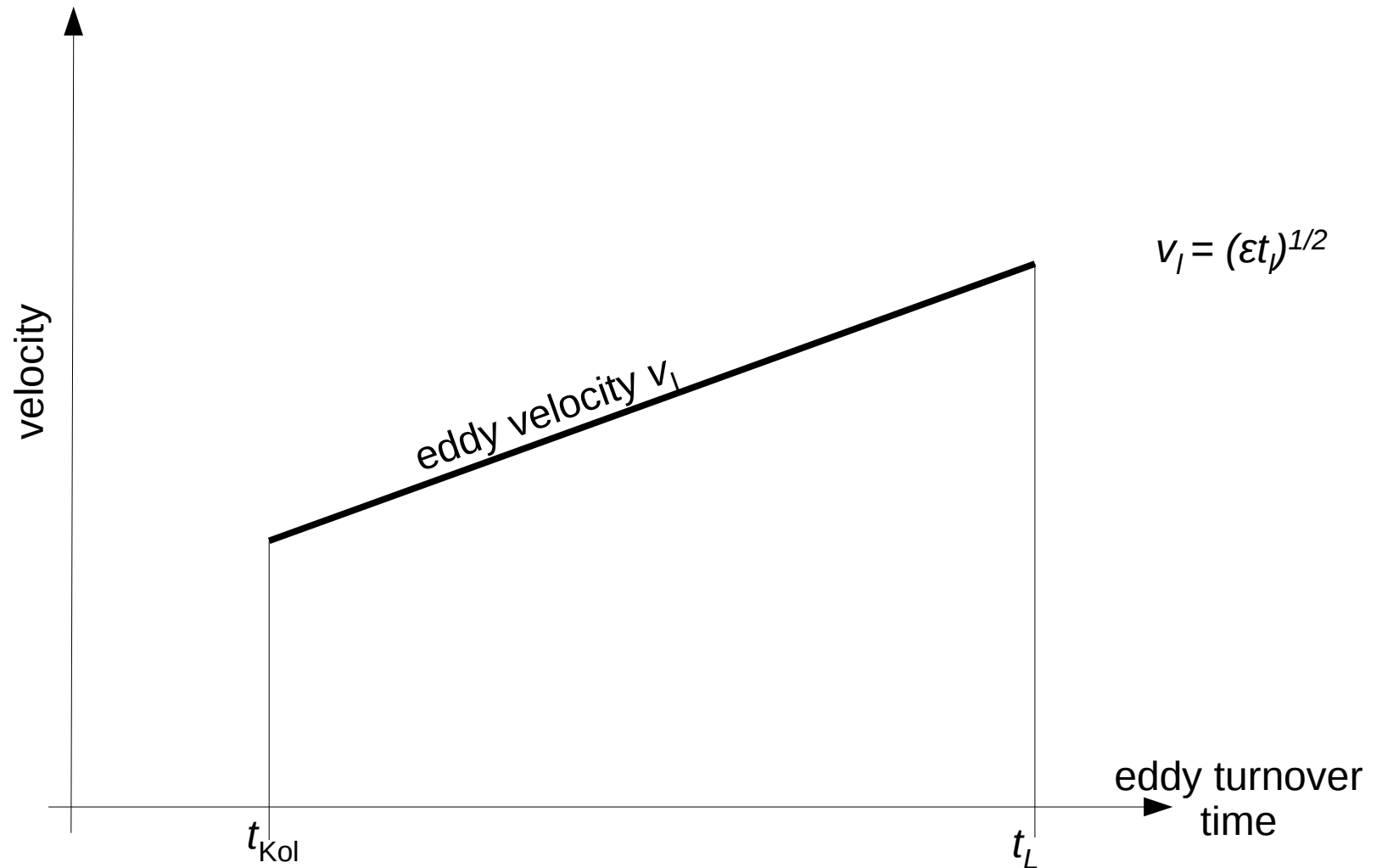


Fully developed turbulence

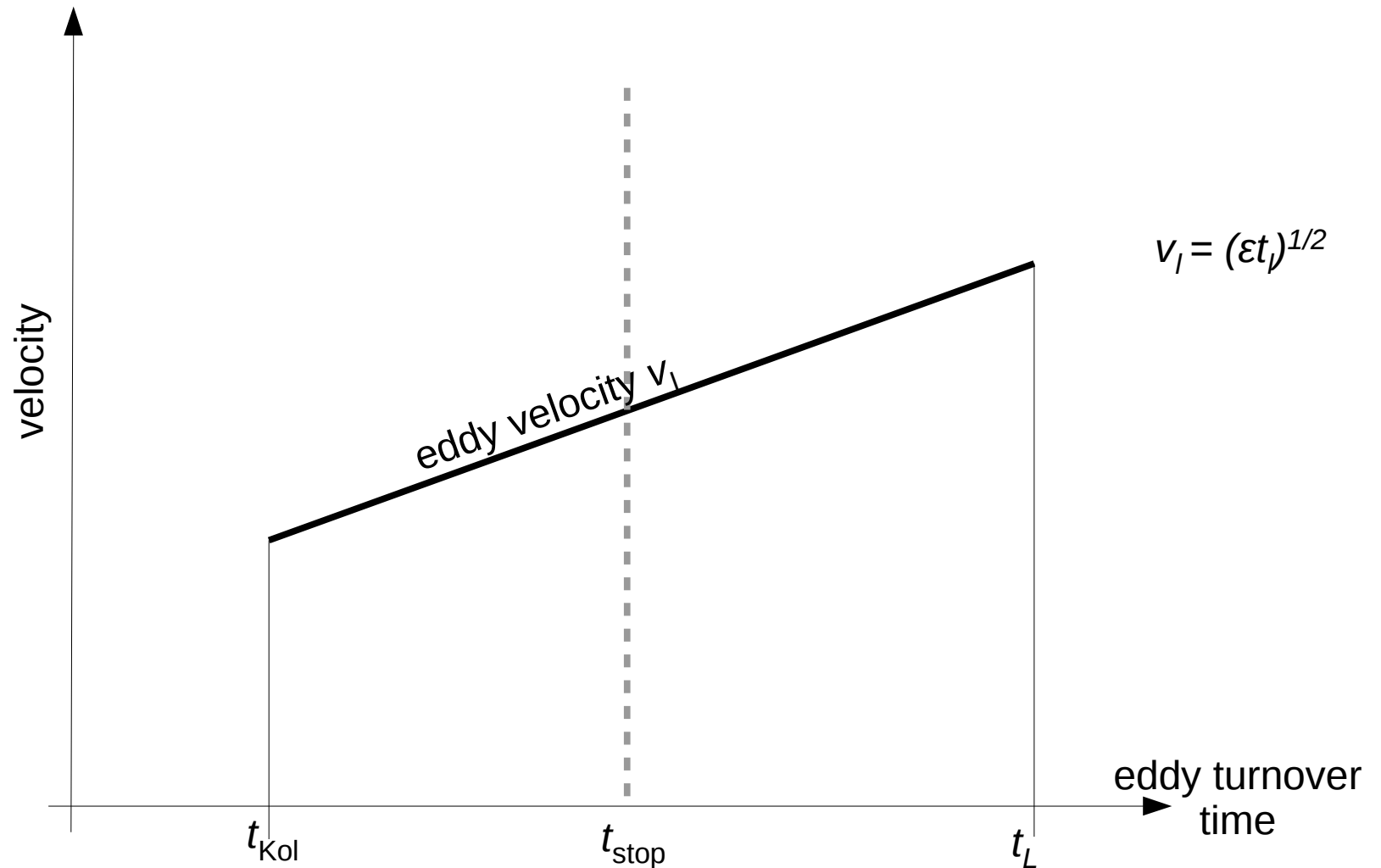
(Kolmogorov 1941)



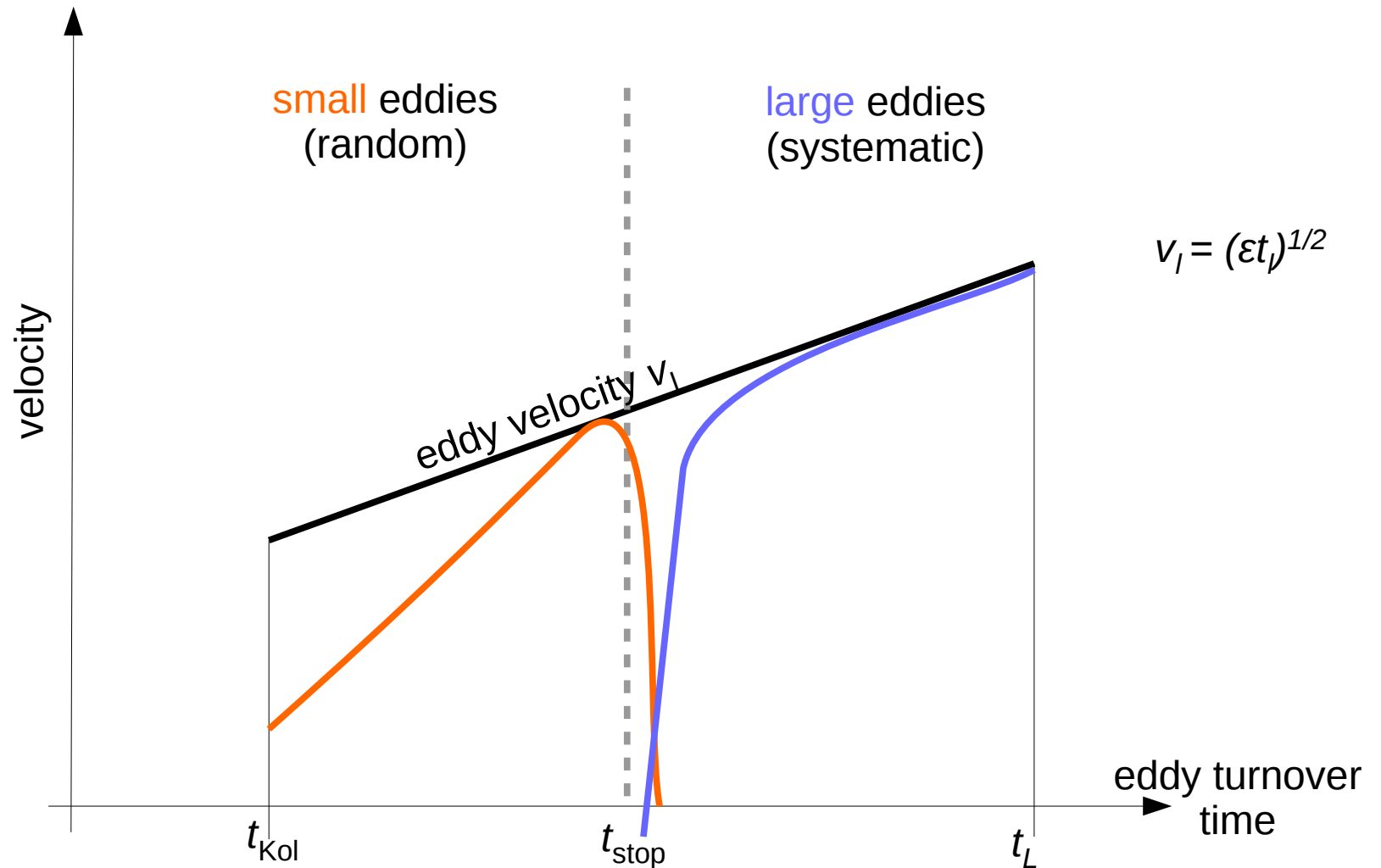
Fully developed turbulence



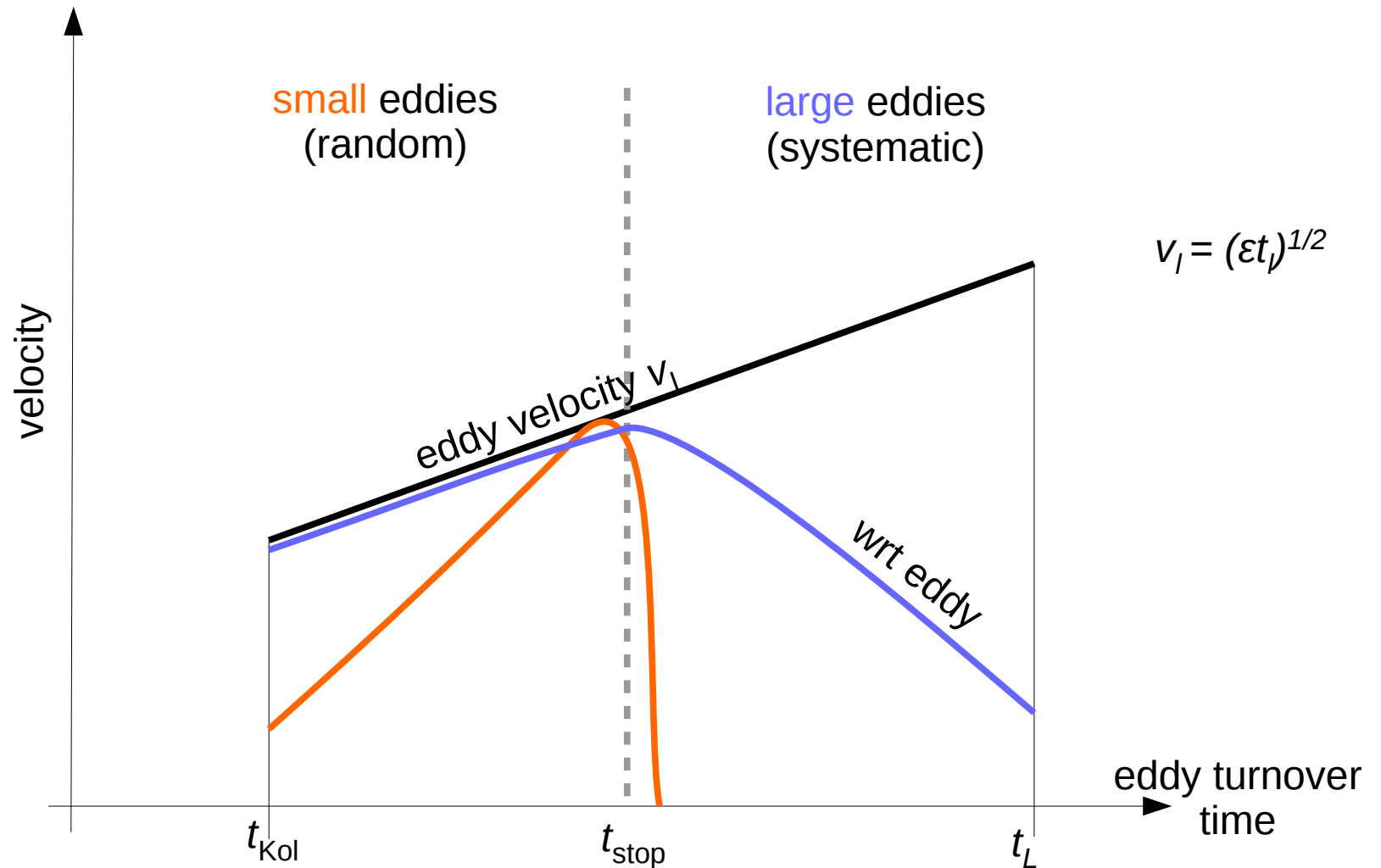
Fully developed turbulence



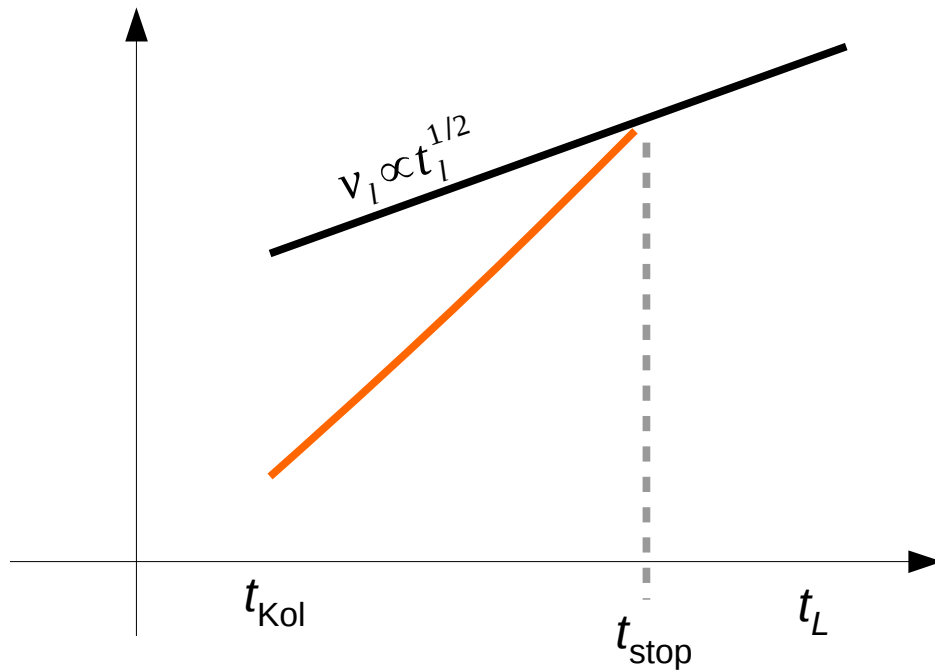
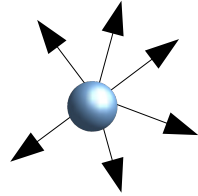
Fully developed turbulence



Fully developed turbulence



Small eddies: Random kicks



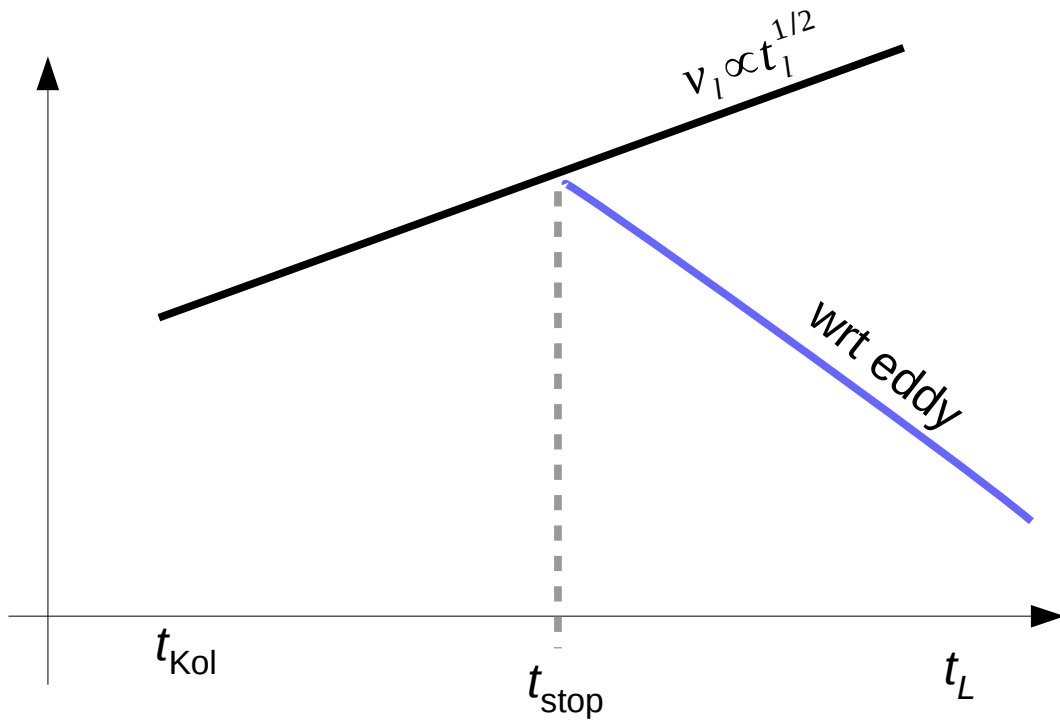
Small eddies: $t_1 < t_{\text{stop}}$

Eddy kicks a particle by $v_1 \sim v_1 t_1/t_{\text{stop}}$ in a *random* direction

The particle “remembers” $N = t_{\text{stop}}/t_1$ of these kicks

$$\rightarrow v_{\text{ran}} = N^{1/2} v_1 = (t_1/t_{\text{stop}})^{1/2} v_1$$

Large eddies: drift



Large eddies: $t_1 > t_{\text{stop}}$

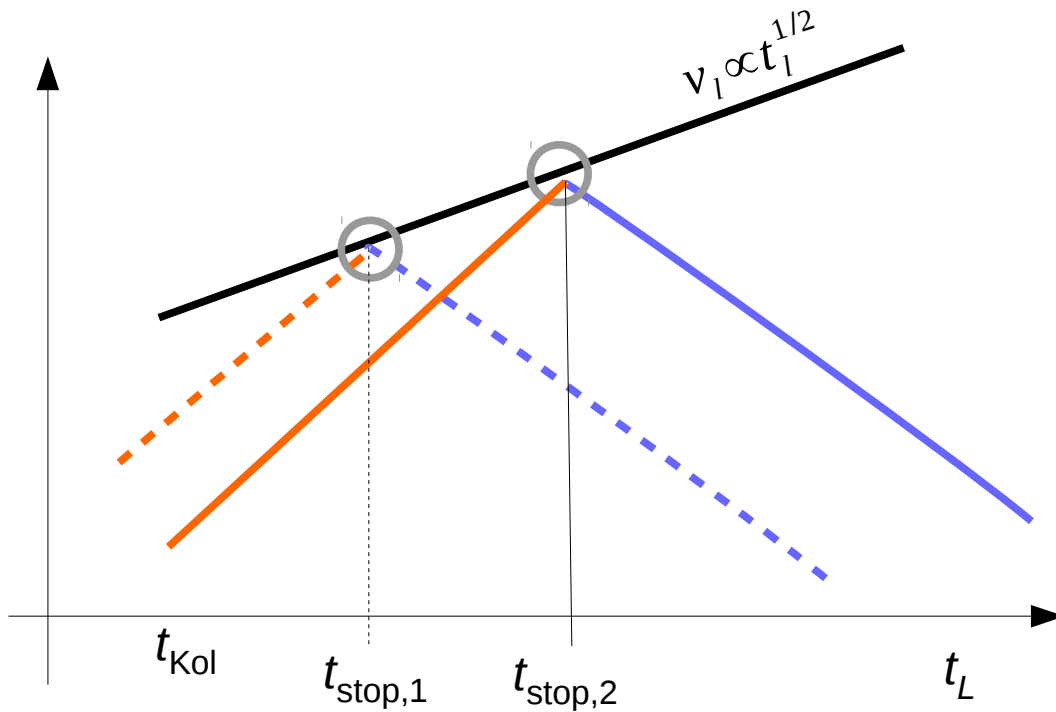
Particles obtain eddy velocity v_1

Experience pressure forces $g_1 \sim v_1/t_1$ [Weidenschilling 1984]

→ drift velocity: $v_{\text{sys}} \sim g_1 t_{\text{stop}}$

with respect to eddy

Relative velocity

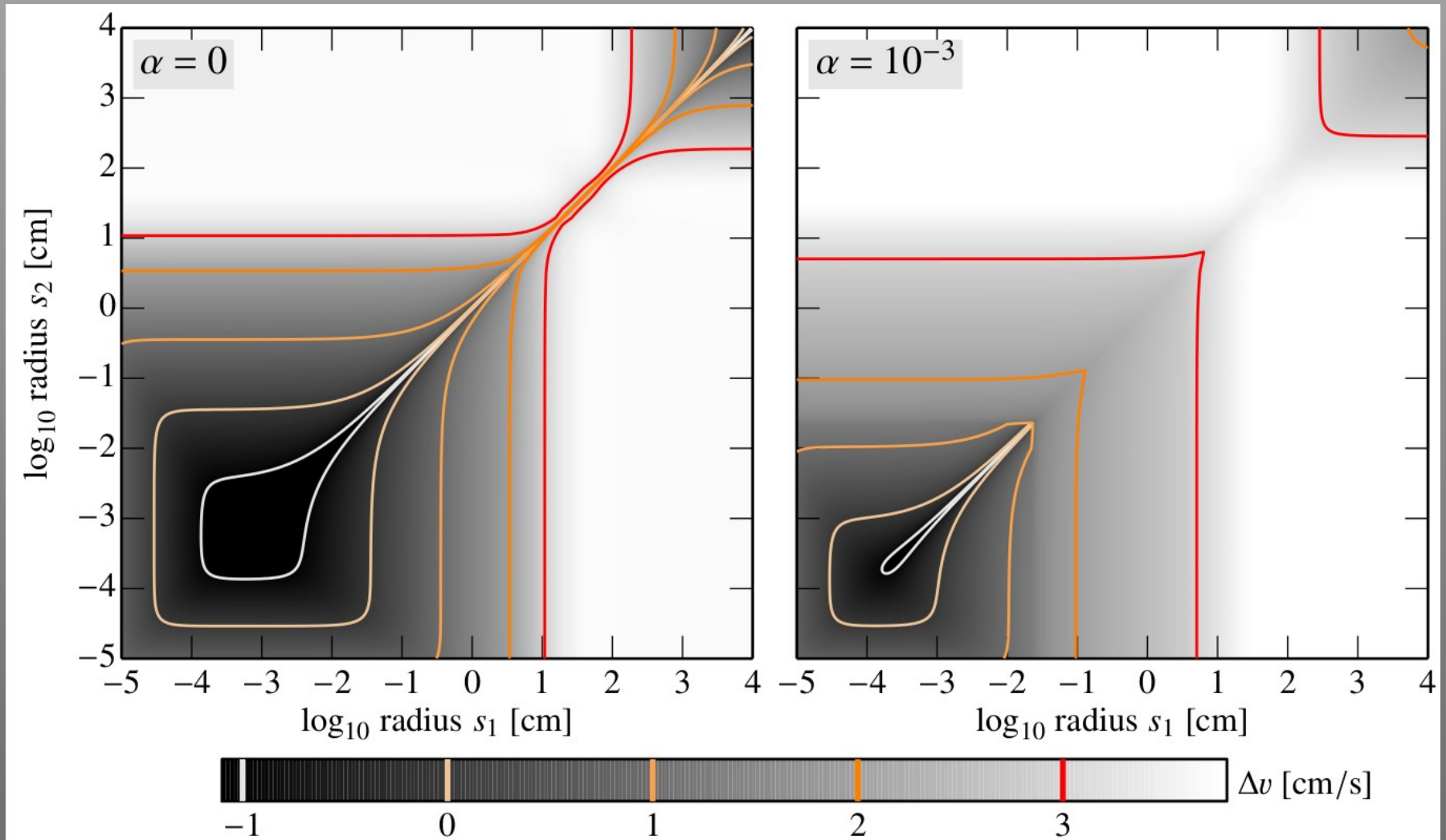


Large eddies (systematic):
→ *subtract* velocities
(vanish equal t_{stop})

Small eddies (random):
→ *add* velocities

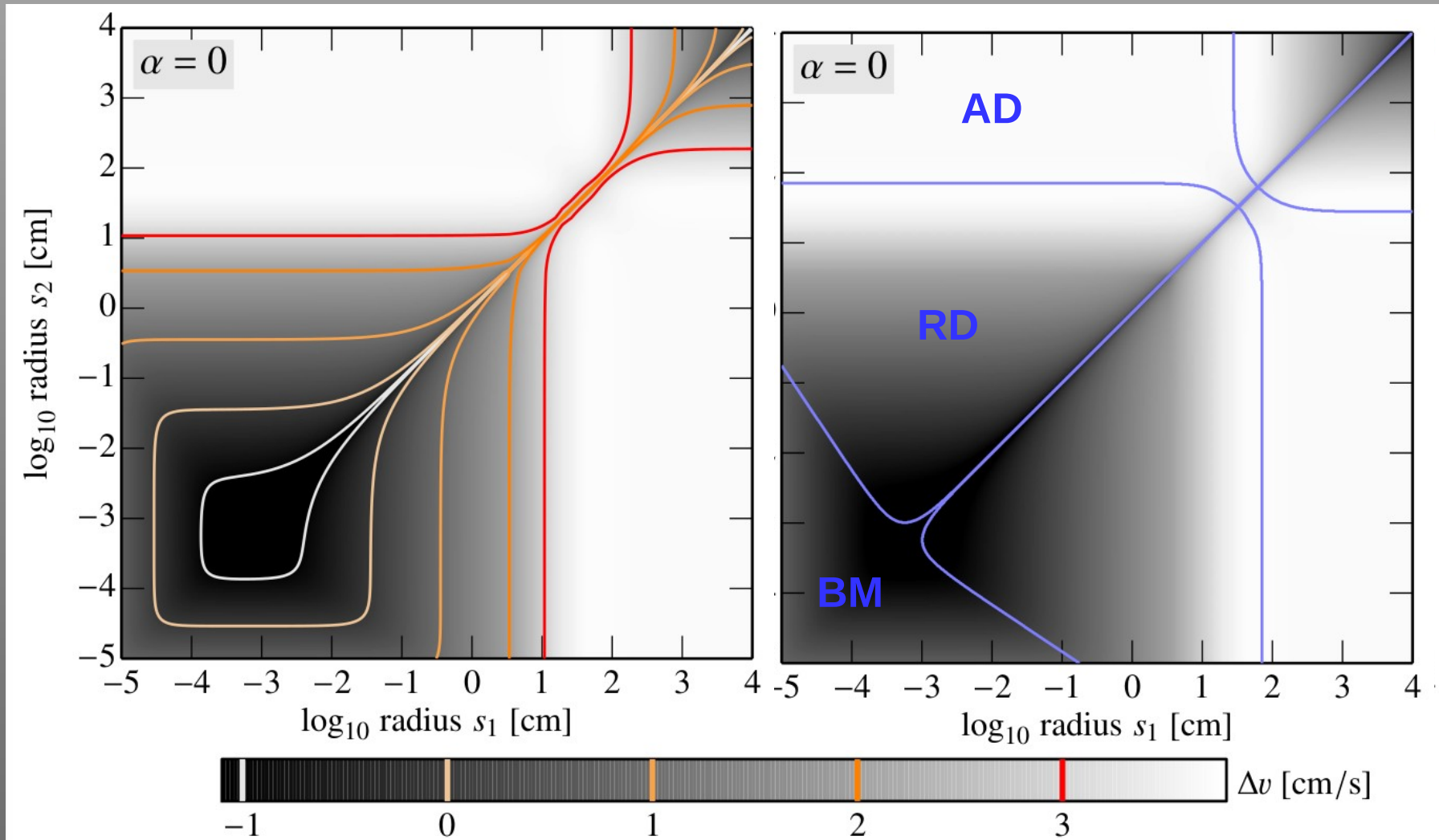
Relative velocities:

(Brownian motion, rad+azi drift, turbulence)



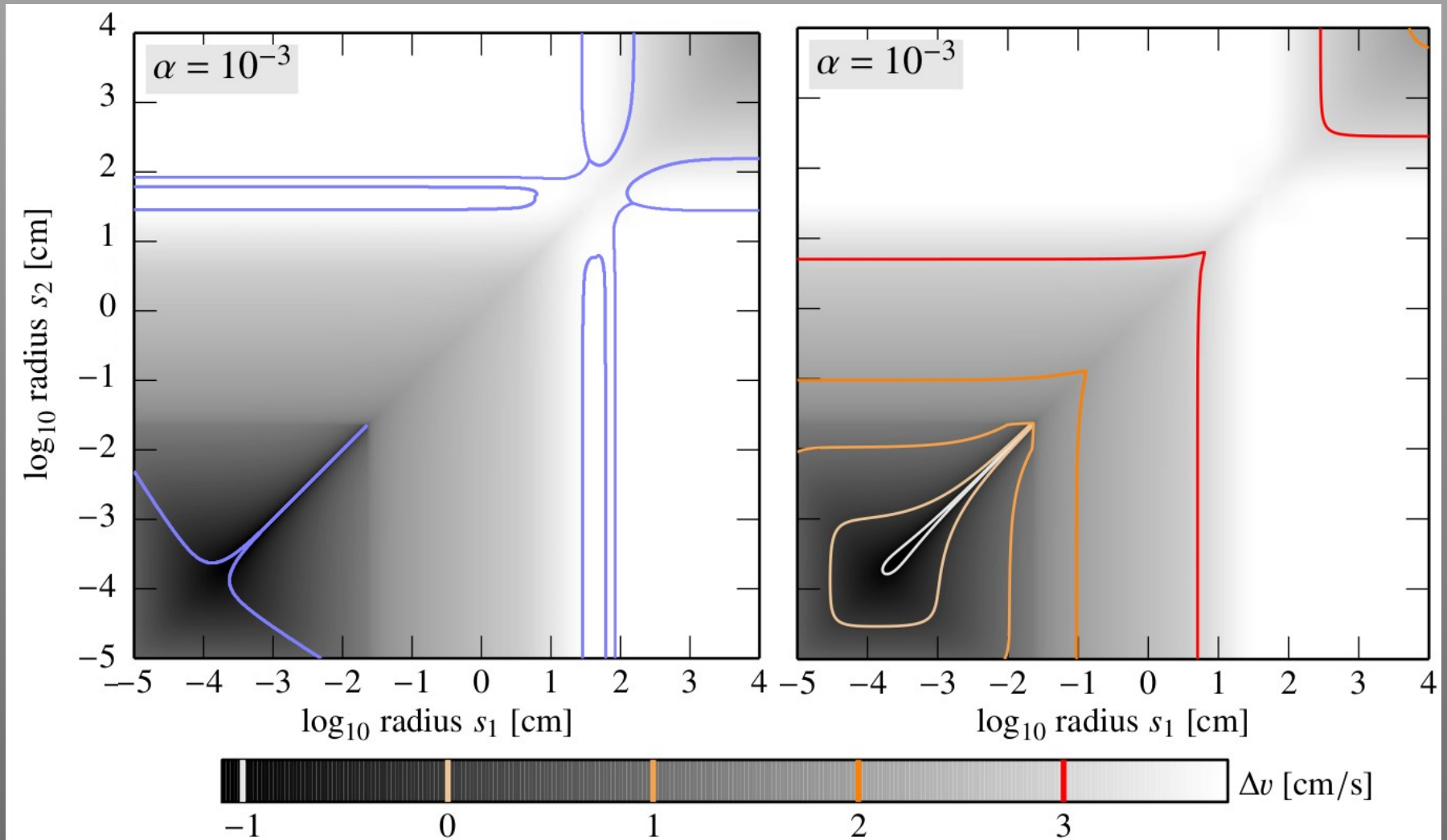
Relative velocities:

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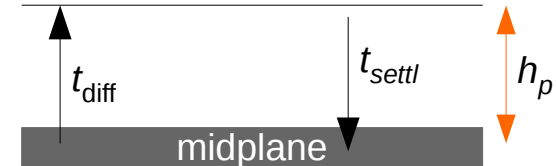
Exercise 1.2 (HW)

Exercise 1.2 particle scale height: When disks are turbulent, particles will diffuse along with the gas. A popular model for the turbulent viscosity is the [Shakura & Sunyaev \(1973\) alpha-model](#), which parameterizes the turbulent viscosity as $\nu_T = \alpha c_s h_{\text{gas}}$. When particles are small ($\tau_p < 1$) this is also the particles diffusivity D_p . The definition of D_p is such that [particles move a distance \$\sqrt{D_p t}\$ in time \$t\$.](#)

(a) Find the equilibrium distance h_p : the height where the settling timescale (from h_p to the midplane) equals the time to diffuse the particles from the midplane to h_p . Express the result in terms of α and τ_p .

(b) Naively, when $\tau_p \rightarrow 0$, one obtains $h_p > h_{\text{gas}}$. Why is this result incorrect?

“random walk”;
distance = rms
average



Exercise 1.3

Exercise 1.3– individual drift velocities: These two equations allow us to solve for the two unknowns (v_r and v_ϕ). But we can greatly simplify the procedure by using that v_r , v_ϕ , and the disk headwind ηv_K (see Equation (1.2)) are small with respect to the Keplerian velocity v_K . Expressions as $(u_{\text{gas}} + v_\phi)^2$ can then be approximated as $u_{\text{gas}}^2 + 2u_{\text{gas}}v_\phi$. In the same gist, $u_{\text{gas}}^2 = (1 - \eta)^2 v_K^2 \approx (1 - 2\eta)v_K^2$, and $d/dt(u_{\text{gas}} + v_\phi) \approx dv_K/dt$. This linearization allows the expressions to be put in matrix form:

$$\mathbf{A} \begin{pmatrix} v_r \\ v_\phi \end{pmatrix} = \mathbf{b}. \quad (1.10)$$

where \mathbf{A} is a 2x2 matrix and \mathbf{b} a 2x1 vector. Inverting this system of equations, show that the radial drift velocity becomes:

$$v_r = -2\eta v_K \frac{\tau_p}{1 + \tau_p^2} \quad (1.11)$$

and the azimuthal velocity:

$$v_\phi = \eta v_K \frac{\tau_p^2}{1 + \tau_p^2}. \quad (1.12)$$

(remark again that v_r , v_ϕ are with respect to the gas velocity.)

1. Force balance
2. Angular momentum loss

Warning:

v_r , v_ϕ are here defined relative to the gas velocity (!) and are therefore small w.r.t. to v_K and u_{gas} .
 v_K = Keplerian velocity
 $u_{\text{gas}} = (1-\eta) =$ sub-Keplerian vel. gas

This is not necessary; plain substitution is easier

Exercise 1.4 (HW)

Exercise 1.4 turbulent velocities: Consider driving scales of $t_L = 1 \text{ yr}$, $c_s = 1 \text{ km s}^{-1}$ and a turbulence Mach number of ≈ 0.1 , so that $v_L = 0.1c_s$. Take a Reynolds number of $\text{Re} = 10^8$.

(a) What are the values at the inertial scale, ℓ_{Kol} , t_{Kol} , and v_{Kol} ?

(b) Given the toy model for the velocity excitation of particles above, as summarized in Figure 1.6, we can derive expressions for the relative velocities of particles. For example, for two particles of stopping times $t_{s1} \leq t_{s2} \leq t_{\text{Kol}}$ (where $t_{s1} = t_{\text{stop}}$ of particle #1 and t_{s2} of #2) all eddies are large (top panel). In that case, argue that the relative velocity becomes $\Delta v \sim |t_{s2} - t_{s1}|v_{\text{Kol}}/t_{\text{Kol}}$. (The minus sign is important: the velocity will vanish for $t_{s1} = t_{s2}$. Why?).

(c) In the case where the largest particle (2) has a stopping time in the inertial range, $t_{\text{Kol}} \leq t_{s2} \leq t_L$, argue that the relative velocity becomes $\Delta v \sim v_L \sqrt{t_{s2}/t_L}$. Why does this expression not depend on t_{s1} ?

(d) If both particles are large, $t_L < t_{s1} < t_{s2}$, argue that it is the particle of the shortest stopping time that determines the relative motions and give Δv .

(e) Between a very small particle ($t_{s1} < t_{\text{Kol}}$) and a very big one ($t_{s2} > t_L$) the relative collision velocity is $\Delta v \sim v_L$. Why?

Give order-of-magnitude expressions!
(no numerical prefactors)

