VSEM: An open library for visual semantics representation

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Abstract

VSEM is an open library for visual semantics. Starting from a collection of tagged images, it is possible to automatically construct an image-based representation of concepts by using off-the-shelf VSEM functionalities. VSEM is entirely written in MATLAB and its object-oriented design allows a large flexibility and reusability. The software is accompanied by a website with supporting documentation and examples.

1 Introduction

In the last years we have seen great progress in the area of automated image analysis. Important advances, such as the introduction of local features for a robust description of the image content (see Mikolajczyk et al. (2005) for a systematic review) and the bag-of-visual-words method (BoVW) for a standard representation across multiple images (Sivic and Zisserman, 2003), have contributed to make image analysis ubiquitous, with applications ranging from robotics to biology, from medicine to photography.

In addition, the development of these key ideas has been strongly accelerated by both the introduction of very well defined challenges such as the popular object recognition task Pascal Visual Object Classes Challenge (Everingham et al., 2010), which have been attracting also a wide community of “outsiders” specialized in a variety of disciplines (e.g., machine learning, neural networks, graphical models and natural language processing), and by sharing effective, well documented implementations of cutting edge image analysis algorithms, such as OpenCV and VLFeat.

A comparable story can be told about automatic text analysis. The last decades have seen a long series of successes in the processing of large text corpora in order to extract more or less structured semantic knowledge. In particular, under the assumption that meaning can be captured by patterns of co-occurrences of words, distributional semantic models such as Latent Semantic Analysis (Landauer and Dumais, 1997) or Topic Models (Blei et al., 2003) have been shown to be very effective both in general semantic tasks such as approximating human intuitions about meaning, as well as in more application-driven tasks such as information retrieval, word disambiguation and query expansion (Turney and Pantel, 2010). And also in the case of automated text analysis, a wide range of method implementations are at the disposal of the scientific community.

Nowadays, given the parallel success of the two disciplines, there is growing interest in making the visual and textual channels interact for mutual benefit. If we look at the image analysis community, we discover that a surprisingly well established tradition of studies that exploit both channels of information have already been established. For example, there is a relatively extended amount of literature about enhancing the performance on visual tasks such as object recognition or image retrieval by replacing a purely image-based pipeline with hybrid methods augmented with textual information (Barnard et al., 2003; Farhadi et al., 2009; Berg et al., 2010; Farhadi et al., 2010; Kulkarni et al., 2011).

Unfortunately, the situation within automatic

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1Bag-of-visual-words model is a popular technique for image classification inspired by the traditional bag-of-words model in Information Retrieval. It represents an image with a histogram of frequency of visual words. Visual words are identified by clustering a large corpus of training features. See Szeliski (2010) chapter 14 for more details.

2http://opencv.org/

3http://www.vlfeat.org/

4See for example the annotated list of corpus-based computational linguistics resources at http://www-nlp.stanford.edu/links/statnlp.html.
text analysis is not so rosy. Despite the huge potential that automatically induced visual features could represent as a new source of perceptually grounded semantic knowledge, image-enhanced models of semantics developed so far (Feng and Lapata, 2010; Bruni et al., 2011; Leong and Mihalcea, 2011; Bergsma and Goebel, 2011; Bruni et al., 2012a; Bruni et al., 2012b) have only scratched this great potential and are still considered as proof-of-concept studies only.

One possible reason of this delay with respect to the image analysis community might be ascribed to the high entry barriers that NLP researchers adopting image analysis methods have to face. Although many of the image analysis toolkits are open source and well documented, they mainly address users within the same community and therefore their use is not as intuitive for others. The final goal of libraries such VLFeat and OpenCV is the representation and classification of images. Therefore, they naturally lack of a series of complementary functionalities that are necessary to bring the visual representation to the level of semantic concepts.

For these reasons, we present here VSEM, a novel toolkit which makes the extraction of image-based representations of concepts an easy task. VSEM is equipped with state-of-the-art algorithms, from low-level feature detection and description up to the BoVW representation of images, together with a set of new routines necessary to move from an image-wise to a concept-wise representation of the image content. In a nutshell, VSEM extracts visual information in an analogous way to how it is done for automatic text analysis. Thanks to BoVW, the image content is indeed discretized and visual units somehow comparable to words in text are produced (the visual words). In this way, from a corpus of images annotated with a set of concepts, it is possible to derive semantic vectors of co-occurrence counts of concepts and visual words. The obtained semantic vectors can be then utilized for typical semantic tasks, such as approximating the semantic relatedness of two concepts by a similarity function over the visual words representing them.

Importantly, the part of VSEM concerning image analysis is based on VLFeat functionalities, offering enhanced VSEM image analysis pipeline makes use of VLFeat functionalities (Vedaldi and Fulkerson, 2010). This guarantees that the image analysis underpinnings of the library be well maintained and state-of-the-art.

The rest of the paper is organized as follows. In Section 2 we introduce the procedure to obtain an image-based representation of a concept. Section 3 describes the VSEM structure. Section 4 shows how to install and run VSEM through an example that uses the Pascal VOC data set. Section 5 concludes summarizing the material and discussing further directions.

2 Background

As shown by Feng and Lapata (2010), Bruni et al. (2011) and Leong and Mihalcea (2011), it is possible to construct an image-based representation of a set of target concepts by starting from a collection of images depicting those concepts, encoding the image contents into low-level features (e.g., SIFT) and scaling up to a higher level representation, based on the well-established BoVW method to represent images. In addition, as shown by Bruni et al. (2012b), better representations can be extracted if the object depicting the concept is first localized in the image.

More in detail, the pipeline encapsulating the whole process mentioned above takes as input a collection of images together with their associated tags and optionally object location annotations. Its output is a set of concept representation vectors for individual tags. The following steps are involved: (i) extraction of local image features, (ii) visual vocabulary construction, (iii) encoding the local features in a BoVW histogram, (iv) including spatial information with spatial binning, (v) aggregation of visual words on a per-concept basis in order to obtain the co-occurrence counts for each concept and (vi) transforming the counts into association scores and/or reducing the dimensionality of the data. A brief description of the individual steps follows.
Local features  Local features are designed to find local image structures in a repeatable fashion and to represent them in robust ways that are invariant to typical image transformations, such as translation, rotation, scaling, and affine deformation. Local features constitute the basis of approaches developed to automatically recognize specific objects (Grauman and Leibe, 2011). The most popular local feature extraction method is the Scale Invariant Feature Transform (SIFT), introduced by Lowe (2004). VSEM uses the VLFeat implementation of SIFT.

Visual vocabulary  To obtain a BoVW representation of the image content, a large set of local features extracted from a large corpus of images are clustered. In this way the local feature space is divided into informative regions (visual words) and the collection of the obtained visual words is called visual vocabulary. $k$-means is the most commonly used clustering algorithm (Grauman and Leibe, 2011). In the special case of Fisher encoding (see below), the clustering of the features is performed with a Gaussian mixture model (GMM), see Perronnin et al. (2010). Figure 1 exemplifies a visual vocabulary construction pipeline. VSEM contains both the $k$-means and the GMM implementations.

Encoding  The encoding step maps the local features extracted from an image to the corresponding visual words of the previously created vocabulary. The most common encoding strategy is called hard quantization, which assigns each feature to the nearest visual word’s centroid (in Euclidean distance). Recently, more effective encoding methods have been introduced, among which the Fisher encoding (Perronnin et al., 2010) has been shown to outperform all the others (Chatfield et al., 2011). VSEM uses both the hard quantization and the Fisher encoding.

Spatial binning  A consolidated way of introducing spatial information in BoVW is the use of spatial histograms (Lazebnik et al., 2006). The main idea is to divide the image into several (spatial) regions, compute the encoding for each region and stack the resulting histograms. This technique is referred to as spatial binning and it is implemented in VSEM. Figure 2 exemplifies the BoVW pipeline for a single image, involving local features extraction, encoding and spatial binning.

Moreover, the input of spatial binning can be further refined by introducing localization. Three different types of localization are typically used: global, object, and surrounding. Global extracts visual information from the whole image and it is also the default option when the localization information is missing. Object extracts visual information from the object location only and the surrounding extracts visual information from outside the object location. Localization itself can either be done by humans (or ground truth annotation) but also by existing localization methods (Uijlings et al., 2013).

For localization, VSEM uses annotated object locations (in the format of bounding boxes) of the target object.

Aggregation  Since each concept is represented by multiple images, an aggregation function for pooling the visual word occurrences across images has to be defined. As far as we know, the sum function has been the only function utilized so far. An example for the aggregation step is sketched in Figure 3. VSEM offers an implementation of the sum function.
Transformations Once the concept-representing visual vectors are built, two types of transformation can be performed over them to refine their raw visual word counts: association scores and dimensionality reduction. So far, the vectors that we have obtained represent co-occurrence counts of visual words with concepts. The goal of association scores is to distinguish interesting co-occurrences from those that are due to chance. In order to do this, VSEM implements two versions of mutual information (pointwise and local), see Evert (2005).

On the other hand, dimensionality reduction leads to matrices that are smaller and easier to work with. Moreover, some techniques are able to smooth the matrices and uncover latent dimensions. Common dimensionality reduction methods are singular value decomposition (Manning et al., 2008), non-negative matrix factorization (Lee and Seung, 2001) and neural networks (Hinton and Salakhutdinov, 2006). VSEM implements the singular value decomposition method.

3 Framework design

VSEM offers a friendly implementation of the pipeline described in Section 2. The framework is organized into five parts, which correspond to an equal number of MATLAB packages and it is written in object-oriented programming to encourage reusability. A description of the packages follows.

- datasets This package contains the code that manages the image data sets. As an example of how to write a wrapper for a given data set, the Pascal VOC wrapper is implemented (PascalDataset). To use a new image data set two solutions are possible: either write a new class which extends GenericDataset or use directly PascalDataset after having rearranged the new data as described in help PascalDataset.

- vision This package contains the code for extracting the bag-of-visual-words representation of images. In the majority of cases, it can be used as a “black box” by the user. Nevertheless, if the user wants to add new functionalities such as new features or encodings, this is possible by simply extending the corresponding generic classes.

- concepts This is the package that deals with the construction of the image-based representation of concepts. concepts it the most important package of VSEM. It applies the image analysis methods to obtain the BoVW representation of the image data and then aggregates visual word counts concept-wise. The transformations utilities are contained in its helpers sub-package.

- benchmarks This package contains the code for benchmarking. Currently there are two benchmarks implemented: a semantic similarity benchmark () and a semantic categorization benchmark (). The two benchmarking classes are CategorizationBenchmark and SimilarityBenchmark. They both extend the abstract class GenericBenchmark.

- helpers This package contains supporting functions and classes. There is a general helpers with functionalities shared across packages and several package specific helpers.

4 Getting started

Installation VSEM can be easily installed by running the file vsemSetup.m. Moreover, pascalDatasetSetup.m can be run to download and place the popular dataset, integrating it in the current pipeline.
Documentation All the MATLAB commands of VSEM are self documented (e.g. `help vsem`) and an HTML version of the MATLAB command documentation is available from the VSEM website.

The Pascal VOC demo The Pascal VOC demo provides a comprehensive example of the workings of VSEM. From the demo file `pascalVQDemo.m`, multiple configurations are accessible. Additional settings are available and documented for each function, class or package in the toolbox (see Documentation).

Running the demo file executes the following lines of code and returns as output `ConceptSpace`, which contains the visual concept representations for the Pascal data set.

```matlab
% Create a matlab structure with the whole set of images in the Pascal dataset along with their annotation
dataset = datasets.VsemDataset(
    configuration.imagesPath,'annotationFolder',configuration.annotationPath);

% Initiate the class that handles the extraction of visual features.
featureExtractor = vision.features.PhowFeatureExtractor();

% Create the visual vocabulary
vocabulary = KmeansVocabulary.trainVocabulary(dataset, featureExtractor);

% Calculate semantic vectors
conceptSpace = conceptExtractor.extractConcepts(dataset, histogramExtractor);

% Compute pointwise mutual information
conceptSpace = conceptSpace.reweight();

% Conclude the demo, computing the similarity of correlation
measures of the 190 possible pairs of concepts from the Pascal dataset against a gold standard
[similarityScore, p-value] = similarityBenchmark.computeBenchmark(conceptSpace,similarityExtractor);
```

5 Conclusions

References


