

Towards a Computational Theory of Action, Causation and Power for Normative Reasoning

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This is a violation!

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by WHOM?

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are violations monitored and settled?

is legal remedy settled after violation?

This is a violation!

is legal remedy provided? —

- external views:
 - whether the norm is **effective** in guiding behaviour



reasoning about norms: reflecting on, evaluating, assessing, deciding upon norms
 by WHOM? HOW?

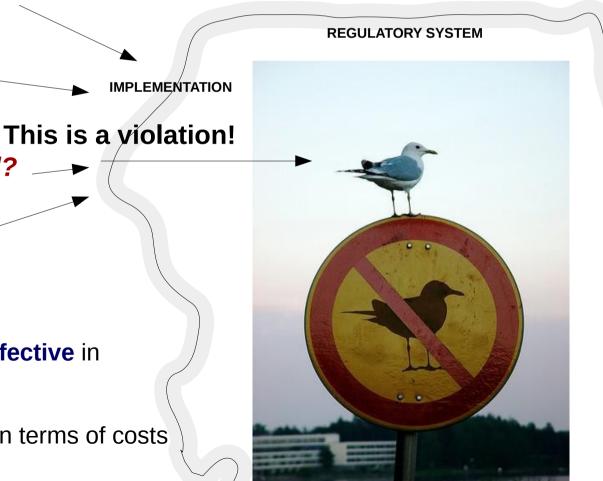
are violations monitored and settled?

is legal remedy settled after violation?

is legal remedy provided? __

is the implementation sustainable?

- external views:
 - whether the norm is **effective** in guiding behaviour
 - whether it is efficient in terms of costs



 reasoning about norms: reflecting on, evaluating, assessing, deciding upon norms

by WHOM? HOW? are violations monitored and settled? REGULATORY SYSTEM is legal remedy settled IMPLEMENTATION after violation? This is a violation! is legal remedy provided? → is the implementation sustainable? external views: whether the norm is **effective** in guiding behaviour

To effectively apply norms, we need a viable implementation!

Research context: Digital Market-Places (DMPs) infrastructures

legal norms

rules of "society"

DMP policy

rules of the "game"

these are about what ought to be (but may be violated)

agreements, contracts

ad-hoc rules set amongst "players"

transactions

"rules" of the infrastructure

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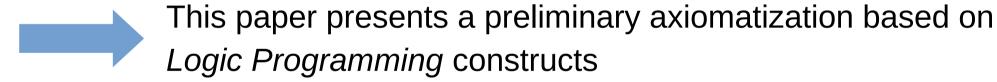
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operationalizing normative systems boils down to designing power structures distributed to computational actors.

Relevant concepts

- ACTION: event driven by an AGENT
- CAUSATION: mechanism producing consequences of events
- POWER: reification of CAUSATION associated to an ACTION



Why Logic Programming?

practical reasons

- tractability, scalability, programmability
- "general" logic framework (no specific modal logics)

strategic reasons

- general renewed interest towards LP
- rule-based interpretations of ML black boxes

Action

Actions: levels of abstraction

 The same event can be described at different levels of abstraction.

Brutus

stabbed

task/operation

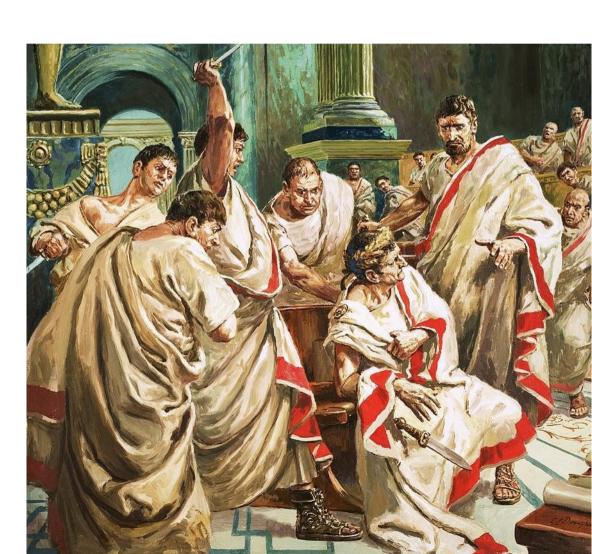
killed

outcome

murdered

intent

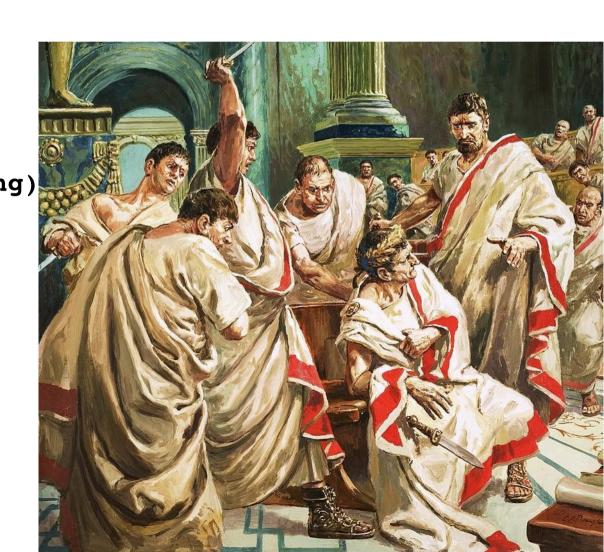
Caesar



Actions: characterizations

 By focusing on a certain action, we can recognize 3 characterizations:

procedural/Behavioural
performs(brutus, stabbing)
productive
brings(brutus, stabbed)
intentional
aims(brutus, stabbing)



Definition of actions

behavioural or procedural characterization
 does(brutus, stabbing) <-> performs(brutus, stabbing).

productive characterization (based on a default rule)
 does(brutus, killing) <*> brings(brutus, dead).

intentional or purposive characterization

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the paper presents several axioms linking the different characterizations...

"Default" mechanism <*>

• If an act has been completed, then performance has occurred:

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 performance is completed by default, unless it is known otherwise:

```
performs(brutus, stabbing), not neg(brings(brutus,
stabbed)) -> brings(brutus, stabbed).
```

strong negation

default negation

Perfect/imperfect actions

- Let us consider actions identified by a task description A and an outcome description R, related by the predicate actionResult/2
- The following qualifications of an action A can be defined as
 does(X, A), actionResult(A, R) and these other conditions:

```
- perfect action: brings(X, R)
```

- imperfect action: neg(brings(X, R))
- ongoing action: not(brings(X, R))
- Successful intention: aims(X, R), brings(X, R)
- failed intention: aims(X, R), neg(brings(X, R))
- ongoing attempt: aims(X, A), not(brings(X, R))

Negated actions

- Actions can be then defined *negatively*, or better, in terms of
 - failure, by relying on the idea of imperfection:

```
does(X, neg(A)) <-> imperfect(does(X, A)).
```

- omission, as not initiated execution:

```
neg(does(X, A)).
```

Reactive rules, represented e.g. in the form of a *event-condition-action* (ECA) rule, provide a primitive computational construct reifying symbolic causation:

```
performs(X, A) : initiates(A, R) => +R. % initiation of r performs(X, A) : terminates(A, R) => -R. % termination of r
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 Why ECA rules? What if we make explicit the temporal annotation and express causation as logical dependency?

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performs(X, A, T), initiates(A, R), neg(holds(R, T-1)) ->
holds(R,T).
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...wrong! Missing inertia and other properties, etc. we need to refer to *Event Calculus* or similar machinery!

Power

Power—of an agent x towards an object y to obtain a
consequence R (concerning y) by performing an action A—can be
seen as the reification of a causal mechanism:

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 The paper elaborates on related concepts as ability, susceptibility, negative power, etc.

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- Interference can be expressed in terms of power!

Structural interference

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- An action **IA** interferes with an action **A** if, when the first is performed, it inhibits the outcome usually expected for performing the second.
- Interference can be expressed in terms of power!

```
% structural interference (disabling, specified at event
level)
```

```
power(Z, power(X, Y, A, R), IA, neg)
<-> [ performs(Z, IA) => +neg(power(X, Y, A, R)). ]
```

Contingent interference

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• The paper presents our starting point for an axiomatization of power structures in a LP setting. Future work will refine and extend it to a wider number of institutional patterns (*ex-ante vs ex-post*, punishment vs reward-based enforcement, delegation, etc.) and concepts (recklessness, negligence, etc.).