

ASCI APR lecture *Causal Modelling*

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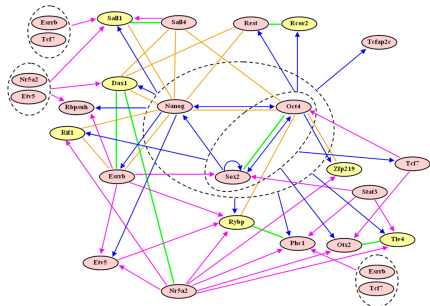
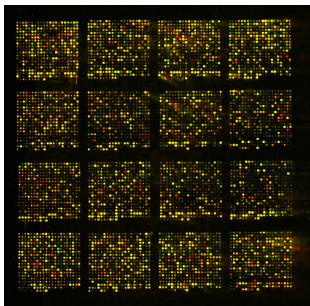
UNIVERSITY OF AMSTERDAM

April 17th, 2015

- 1 **Introduction**
- 2 Structural Causal Models
- 3 Causal Bayesian Networks
- 4 Back-door Criterion

Genetics:

how to infer gene regulatory networks from micro-array data?



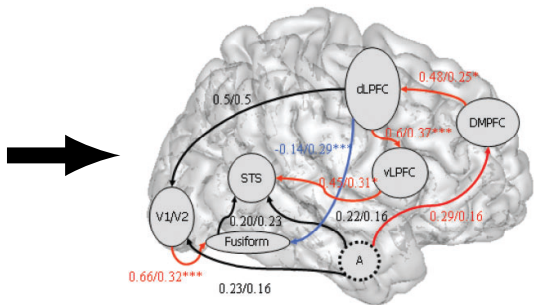
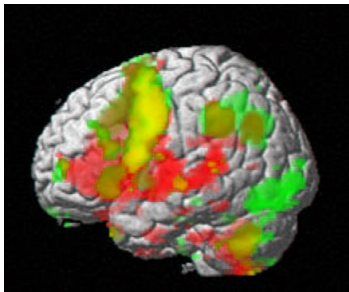
Social sciences:

does playing violent computer games cause aggressive behavior?



Neuroscience:

how to infer functional connectivity networks from fMRI data?



Economy:

Does austerity reduce national debt?



Causality is central notion in:

- reasoning
- science
- policy decisions
- . . .

What is the “logic” of cause and effect?

(We don't learn this at school!)

Question: give a definition of cause and effect.

The subject of *causality* has a long history in philosophy. For example, this is what Hume had to say about it:



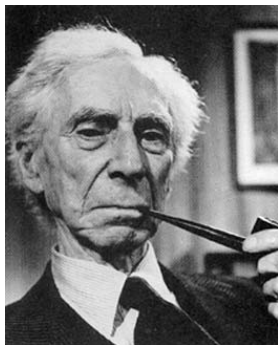
“Thus we remember to have seen that species of object we call *flame*, and to have felt that species of sensation we call *heat*. We likewise call to mind their constant conjunction in all past instances. Without any farther ceremony, we call the one *cause* and the other *effect*, and infer the existence of the one from that of the other.”

David Hume, *Treatise of Human Nature*

But: does the rooster's crow really cause the sun to rise?



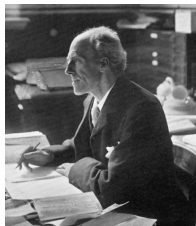
Some philosophers even proposed to abandon the concept of causality completely.



“All philosophers, of every school, imagine that causation is one of the fundamental axioms or postulates of science, yet, oddly enough, in advanced sciences such as gravitational astronomy, the word ‘cause’ never occurs. The law of causality, I believe, like much that passes muster among philosophers, is a relic of a bygone age, surviving, like the monarchy, only because it is erroneously supposed to do no harm.”

Bertrand Russell, *On The Notion Of Cause*

Karl Pearson (one of the founders of modern statistics, well-known from his work on the *correlation coefficient*) writes:



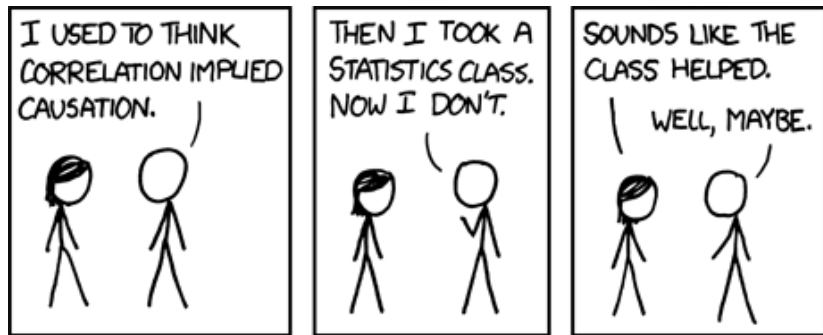
“Beyond such discarded fundamentals as ‘matter’ and ‘force’ lies still another fetish amidst the inscrutable arcana of even modern science, namely, the category of cause and effect.”

Karl Pearson, *The Grammar of Science*

Since then, many statisticians tried to avoid causal reasoning:

- “Considerations of causality should be treated as they have always been in statistics: preferably not at all.” (Terry Speed, former president of the Biometric Society).
- “It would be very healthy if more researchers abandon thinking of and using terms such as cause and effect.” (Prominent social scientist).

A modern philosopher on Causality



Randall Munroe, www.xkcd.org

A formal theory of causality?

Question

Can we formalize causal reasoning?

Please make Exercise 1...

Example (Simpson's paradox)

We collect data from a biobank (e.g., the EPD) to investigate the effectiveness of a new drug against a certain disease. It can happen that:

- 1 The probability of recovery is higher for patients that took the drug:

$$p(\text{recovery}|\text{drug}) > p(\text{recovery}|\text{no drug})$$

- 2 For *both male and female* patients, however, the relation is opposite:

$$p(\text{recovery}|\text{drug, male}) < p(\text{recovery}|\text{no drug, male})$$

$$p(\text{recovery}|\text{drug, female}) < p(\text{recovery}|\text{no drug, female})$$

Should we use this drug for treatment?

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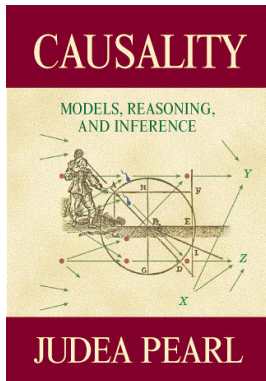
Note

Fancy classifiers, deep learning and big data do not help us here!

An important step forwards



Judea Pearl



ACM Turing Award 2011: “For fundamental contributions to artificial intelligence through the development of a calculus for probabilistic and causal reasoning.”

Pearl's contribution: the do-operator

- Probability theory has a semantics for dealing with *observations*: conditioning.
- Pearl extends probability calculus by introducing a new operator for describing *interventions*, the **do-operator**.

Example (Do-operator)

- $p(\text{lung cancer}|\text{smoke})$: the probability that somebody gets lung cancer, given (the observation) that the person smokes.
- $p(\text{lung cancer}|\text{do}(\text{smoke}))$: the probability that somebody gets lung cancer, when we *force* the person to smoke.

Resolution:

- Simpson's paradox is only paradoxical if we misinterpret $p(\text{recovery}|\text{drug})$ as $p(\text{recovery}|\text{do}(\text{drug}))$.
- We should prescribe the drug if $p(\text{recovery}|\text{do}(\text{drug})) > p(\text{recovery}|\text{do}(\text{no drug}))$.

Pearl recognized that the rules of probability theory do not suffice for causal reasoning. He formulated three additional rules (the “do-calculus”):

❶ **Ignoring observations:**

$$p(y \mid \text{do}(x), w, z) = p(y \mid \text{do}(x), w) \quad \text{if } (Y \perp\!\!\!\perp Z \mid X, W)_{G_{\bar{X}}}$$

❷ **Action/observation exchange:**

$$p(y \mid \text{do}(x), \text{do}(z), w) = p(y \mid \text{do}(x), z, w) \quad \text{if } (Y \perp\!\!\!\perp Z \mid X, W)_{G_{\bar{X}, Z}}$$

❸ **Ignoring actions:**

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The do-calculus allows us to reason with (probabilistic) causal statements, given (partial) knowledge of the causal structure.

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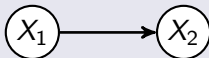
Causal graphs

- We can express the causal relationships between a set of variables X_1, \dots, X_N in terms of a directed graph, the **causal graph**.
- A directed edge $X_i \rightarrow X_j$ means that X_i is a **direct cause** of X_j (relative to X_1, \dots, X_N), i.e., not mediated via other variables X_1, \dots, X_N . X_i is called a **parent** of X_j , X_j is called a **child** of X_i .

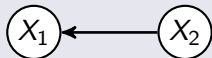
Example



X_1 and X_2 are unrelated



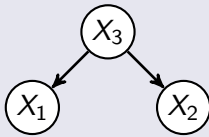
X_1 causes X_2



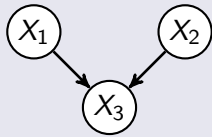
X_2 causes X_1



X_1 and X_2 cause each other



X_1 and X_2 have a common cause



X_1 and X_2 have a common effect

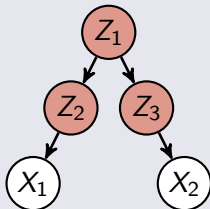
Causal graphs: ancestor relationships

- If $X_{i_1} \rightarrow X_{i_2} \rightarrow X_{i_3} \rightarrow \dots \rightarrow X_{i_n}$ then we say that X_{i_1} is an **ancestor** of X_{i_n} and X_{i_n} is a **descendant** of X_{i_1} .
- If Z is an unobserved common ancestor of X_i and X_j then we call Z a **confounder** of X_i and X_j .

Example



X_1 is ancestor of X_3



Z_1 confounds X_1 and X_2

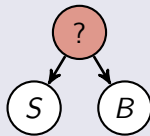
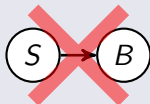
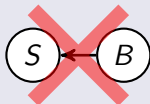


X_1 and X_2 are confounded

- A correlation between X , Y may be explained by direct causal relation $X \rightarrow Y$ or $Y \rightarrow X$, or a confounder, or a combination of these.
- Another explanation of a correlation is **selection bias**.

Example

- Significant correlation ($p = 0.008$) between human birth rate and number of stork populations in European countries [Matthews, 2000]
- Most people nowadays do not believe that storks deliver babies (nor that babies deliver storks)
- There must be some confounder explaining the correlation



Definition: causal feedback

A SCM incorporates **causal feedback** if its graph contains a **directed cycle**

$$X_{i_0} \rightarrow X_{i_1} \rightarrow \dots \rightarrow X_{i_n}, \quad X_{i_0} = X_{i_n}$$

If it does not contain such a directed cycle, the model is called **acyclic**.

Example

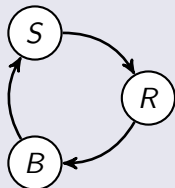


In economy, causal feedback is often present:

R: risks taken by bank;

B: imminent bankruptcy;

S: saved by the government.



Structural Causal Models: Definition

Can be traced back to S. Wright's *path diagrams* (1921) and Structural Equation Models in the social sciences.

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Definition (Pearl, 2000)

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- 2 N **structural equations**:

$$X_i = f_i(\mathbf{X}_{\text{pa}(i)}, E_i), \quad i = 1, \dots, N;$$

effect

causal mechanism

observed direct causes

noise

where the subsets $\text{pa}(i) \subseteq \{1, \dots, N\}$ define the **observed** direct causes of X_i (the **parents** of X_i),

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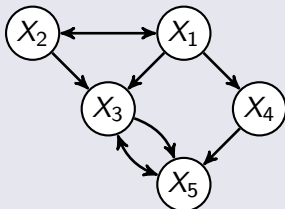
where the subsets $\text{pa}(i) \subseteq \{1, \dots, N\}$ define the **observed** direct causes of X_i (the **parents** of X_i),

- 3 a joint probability distribution $p(E_1, \dots, E_N)$ on latent variables.

Example

i	$\text{pa}(i)$	$X_i = f_i(\mathbf{X}_{\text{pa}(i)}, E_i)$
1	\emptyset	$X_1 = f_1(E_1)$
2	\emptyset	$X_2 = f_2(E_2)$
3	$\{1, 2\}$	$X_3 = f_3(X_1, X_2, E_3)$
4	$\{1\}$	$X_4 = f_4(X_1, E_4)$
5	$\{3, 4\}$	$X_5 = f_5(X_3, X_4, E_5)$

$$p(E_1, \dots, E_5) = p(E_1, E_2)p(E_3, E_5)p(E_4)$$



- **Directed arrows** (from X_j to X_i if $j \in \text{pa}(i)$) correspond with functional dependences and are interpreted as **direct causal relations**.
- **Bidirected arrows** between noise variables indicate statistical **dependences** between noise variables.
- Usually, noise variables are not depicted explicitly.

Modeling interventions in a SCM

For a *causal* model, we need to specify how we model *interventions*.

Interventions in SCMs

An **intervention** $\text{do}(\mathbf{X}_I = \boldsymbol{\xi}_I)$ on a set of variables \mathbf{X}_I with $I \subseteq \{1, \dots, N\}$, forcing them to attain the value $\boldsymbol{\xi}_I$, changes the structural equations as follows:

Original SCM \mathcal{M} :

$$X_i = f_i(\mathbf{X}_{\text{pa}(i)}, E_i) \quad \forall i \in I$$

$$X_j = f_j(\mathbf{X}_{\text{pa}(j)}, E_j) \quad \forall j \notin I$$

$$p(\mathbf{E}) = \dots$$

Intervened SCM $\mathcal{M}_{\boldsymbol{\xi}_I}$:

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- Interpretation: overriding default causal mechanisms that normally would determine the values of the intervened variables.
- In the graph of \mathcal{M} , the effect of the intervention is to remove all incoming arrows of intervened variables $\{X_i\}_{i \in I}$.

Example

Observational (no intervention):

Structural causal model \mathcal{M} :

$$X_1 = f_1(E_1)$$

$$X_2 = f_2(E_2)$$

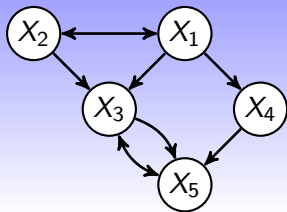
$$X_3 = f_3(X_1, X_2, E_3)$$

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$$p(E_1, \dots, E_5) = p(E_1, E_2)p(E_3, E_5)p(E_4)$$

Causal graph $\mathcal{G}_{\mathcal{M}}$:



Example

Intervention $\text{do}(X_1 = \xi_1)$:

Structural causal model \mathcal{M}_{ξ_1} :

$$X_1 = \xi_1$$

$$X_2 = f_2(E_2)$$

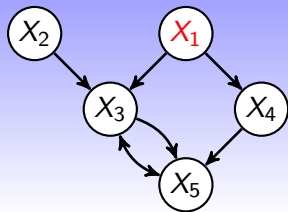
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Causal graph $\mathcal{G}_{\mathcal{M}_{\xi_1}}$:



Example

Intervention $\text{do}(X_3 = \xi_3)$:

Structural causal model \mathcal{M}_{ξ_3} :

$$X_1 = f_1(E_1)$$

$$X_2 = f_2(E_2)$$

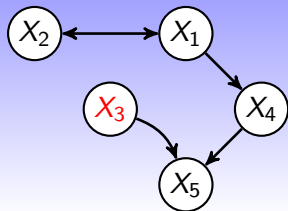
$$X_3 = \xi_3$$

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Causal graph $\mathcal{G}_{\mathcal{M}_{\xi_3}}$:



Please make Exercise 2...

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Definition: Confounder

A **confounder** is an unobserved variable that is an ancestor of at least two endogenous variables (a “hidden common cause”).

Absence of confounders implies **causal sufficiency**.

Definition: Causal Sufficiency

If all noise variables in an SCM are jointly independent, i.e., if the joint probability distribution $p(\mathbf{E})$ of the noise variables factorizes:

$$p(\mathbf{E}) = \prod_{i=1}^N p(E_i)$$

then we say that the variables \mathbf{X} are **causally sufficient**.

Definition

An SCM \mathcal{M} is called **Markovian** if

- 1 it is acyclic (“no causal feedback”);
- 2 it is causally sufficient (“no hidden common causes”).

Its causal graph is a **Directed Acyclic Graph (DAG)**.

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- Markovian SCMs are easier to handle than non-Markovian SCMs; this is why we will focus on these for the rest of this talk.
- Non-Markovian SCMs are an active research topic, and the theory for these cases is far from complete.
- Markovian SCMs are related to Causal Bayesian networks.

Definition: Bayesian Network

A **Bayesian network** is a pair (\mathcal{G}, p) where:

- \mathcal{G} is a Directed Acyclic Graph
- p is a probability distribution on the nodes X_1, \dots, X_N of \mathcal{G} such that

$$p(X_1, \dots, X_N) = \prod_{i=1}^N p(X_i \mid \mathbf{x}_{\text{pa}(i)})$$

where $\text{pa}(i)$ are the parents of X_i in \mathcal{G} .

Definition: Causal Bayesian Network

A Bayesian Network is **causal** if:

- Arrows correspond with direct causal relations
- After an intervention $\text{do}(\mathbf{X}_I = \xi_I)$, the incoming arrows on \mathbf{X}_I are removed and the probability distribution becomes:

$$p(X_1, \dots, X_N \mid \text{do}(\mathbf{X}_I = \xi_I)) = \prod_{\substack{i=1 \\ i \notin I}}^N p(X_i \mid \mathbf{X}_{\text{pa}(i)}) \prod_{i \in I} \mathbf{1}_{[X_i = \xi_i]}$$

Theorem: Causal Markov Condition

Any probability distribution induced by a Markovian SCM \mathcal{M} can be factorized as:

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The proof proceeds by marginalization over the noise variables \mathbf{E} :

$$\begin{aligned} p(\mathbf{X}) &= \int p(\mathbf{X}, \mathbf{E}) d\mathbf{E} = \int \left(\prod_{i=1}^N \delta(\mathbf{X}_i - f_i(\mathbf{X}_{\text{pa}(i)}, E_i)) \right) \left(\prod_{i=1}^N p(E_i) \right) d\mathbf{E} \\ &\stackrel{*}{=} \prod_{i=1}^N \int \delta(\mathbf{X}_i - f_i(\mathbf{X}_{\text{pa}(i)}, E_i)) p(E_i) dE_i = \prod_{i=1}^N p(\mathbf{X}_i \mid \mathbf{X}_{\text{pa}(i)}) \end{aligned}$$

where we used the acyclicity in the step marked with a *.

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- Each Markovian SCM induces a Causal Bayesian network.
- Conversely, for any given Causal Bayesian network, one can construct an equivalent Markovian SCM.
- SCMs are more general than Causal Bayesian Networks (can deal with confounders, feedback, allow us to define counterfactuals).

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- In general, however, $p(Y | \text{do}(X)) \neq p(Y | X)$.
- How to estimate $p(Y | \text{do}(X))$ from data?

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Example



$p(Y|X) = p(Y|\text{do}(X))$
identifiable



$p(Y|X) \neq p(Y|\text{do}(X))$
not identifiable

- Given enough modeling assumptions, the effects of interventions can sometimes be inferred from observational data alone!

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- Can we find a condition which tells us when a causal effect $p(Y | \text{do}(X))$ is identifiable?
- A sufficient condition is provided by Pearl's **Back-door criterion**. To state this, we first need some graph theoretical terminology.

Some graph-theoretical notions

Definition: path, directed path, ancestor and collider

Let \mathcal{G} be a graph with directed (\leftarrow , \rightarrow) and bidirected (\leftrightarrow) edges.

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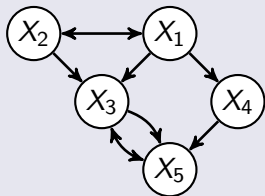
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Example



The sequence $X_1 \rightarrow X_3 \leftarrow X_1$ is not a path.

The sequence $X_1 \leftrightarrow X_2 \rightarrow X_3$ is a path.

X_1 , X_2 , X_3 and X_4 are ancestors of X_5 .

The path $X_3 \rightarrow X_5 \leftarrow X_4$ contains a collider X_5 .

The path $X_1 \leftrightarrow X_2 \rightarrow X_3$ contains no collider.

Definition: blocking paths

Let \mathcal{G} be a graph with directed and bidirected edges. Given a path p between nodes X and Y in \mathcal{G} , and a set of nodes $S \subseteq \mathcal{G} \setminus \{X, Y\}$, we say that S **blocks** p if p contains

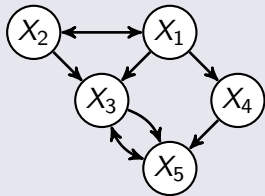
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$X_3 \rightarrow X_5 \leftarrow X_4$ is blocked by \emptyset .

$X_3 \rightarrow X_5 \leftarrow X_4$ is blocked by $\{X_1\}$.

$X_3 \rightarrow X_5 \leftarrow X_4$ is not blocked by $\{X_5\}$.

$X_3 \leftarrow X_2 \leftrightarrow X_1 \rightarrow X_4$ is blocked by $\{X_1\}$.

$X_3 \leftarrow X_2 \leftrightarrow X_1 \rightarrow X_4$ is not blocked by $\{X_5\}$.

- In the Markovian case, by using truncated factorization, we can show:

$$p(Y \mid \text{do}(X), \mathbf{X}_{\text{pa}(X)}) = p(Y \mid X, \mathbf{X}_{\text{pa}(X)})$$

and therefore:

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The Back-door Criterion

Theorem: Back-door criterion

A set S of nodes is “admissible” or “sufficient” for **adjustment** if

- 1 no element of S is a descendant of X
- 2 the elements of S block all **back-door paths** $X \leftarrow \dots Y$ and $X \leftrightarrow \dots Y$ (paths between X and Y with an arrow pointing to X).

In that case,

$$p(Y \mid \text{do}(X)) = \int p(Y \mid X, \mathbf{x}_S) p(\mathbf{x}_S) d\mathbf{x}_S$$

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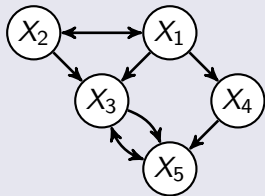
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Example



$\{X_1\}$ is sufficient for adjustment to find the causal effect of X_4 on X_5 .

$\{X_1\}$ is sufficient for adjustment to find the causal effect of X_2 on X_5 .

No set is sufficient for adjustment to find the causal effect of X_3 on X_5 .

Please make Exercise 3...

Statistics, (most of) Machine Learning

- About **associations** (correlation between smoking and lung cancer)
- Models the **distribution** of the data
- Predicting by **conditioning** (if we know that somebody smokes, what is the probability that he/she will get lung cancer?)

Causality

- About **causation** (smoking causes lung cancer)
- Models the **mechanism** that generates the data
- Predicting results of **interventions** (if we force somebody to smoke, what is the probability that he/she will get lung cancer?)

Observing \neq intervening: $p(Y | X) \neq p(Y | \text{do}(X))$

Thank you for your attention!



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