

Inverse of a Multivector

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The problem

A Clifford algebra is generally not a division ring , i.e., every non-zero multivector need not be invertible.

The natural question then is: **How to detect invertible elements?**

This is the question we try to address.

Applications of the results

We will discuss basis free formulas for the inverse of multivectors in Clifford algebras with $n \leq 6$.

1) Solving linear equations:

$$AX = B$$

2) Robotics, computer vision, control theory, stability analysis, model reduction, image and signal processing:

$$\text{Sylvester equation: } AX + XB = C$$

$$\text{Lyapunov equation: } AX + XA^H = C$$

References: Dmitry Shirokov, *Advances in Applied Clifford Algebras*, 31 (2021), 70, 19 pp

The results

$$n = 1, \quad U^{-1} = \frac{\hat{U}}{U\hat{U}}$$

$$n = 2, \quad U^{-1} = \frac{\hat{\tilde{U}}}{U\hat{\tilde{U}}}$$

$$n = 3, \quad U^{-1} = \frac{\tilde{U}\hat{U}\hat{\tilde{U}}}{U\tilde{U}\hat{U}\hat{\tilde{U}}}$$

$$n = 4, \quad U^{-1} = \frac{\tilde{U}(\hat{U}\hat{\tilde{U}})^\Delta}{U\tilde{U}(\hat{U}\hat{\tilde{U}})^\Delta}$$

$$n = 5, \quad U^{-1} = \frac{\tilde{U}(\hat{U}\hat{\tilde{U}})^\Delta (U\tilde{U}(\hat{U}\hat{\tilde{U}})^\Delta)^\Delta}{U\tilde{U}(\hat{U}\hat{\tilde{U}})^\Delta (U\tilde{U}(\hat{U}\hat{\tilde{U}})^\Delta)^\Delta}$$

$$n = 6, \quad U^{-1} = \frac{\left(\frac{1}{3}\tilde{U}\hat{U}\hat{\tilde{U}}(\hat{U}\hat{\tilde{U}}U\tilde{U})^\Delta + \frac{2}{3}\tilde{U}((\hat{U}\hat{\tilde{U}})^\Delta((\hat{U}\hat{\tilde{U}})^\Delta(U\tilde{U})^\Delta)^\Delta)^\Delta \right)}{U\left(\frac{1}{3}\tilde{U}\hat{U}\hat{\tilde{U}}(\hat{U}\hat{\tilde{U}}U\tilde{U})^\Delta + \frac{2}{3}\tilde{U}((\hat{U}\hat{\tilde{U}})^\Delta((\hat{U}\hat{\tilde{U}})^\Delta(U\tilde{U})^\Delta)^\Delta)^\Delta \right)}$$

$$\text{where } U^\Delta := \sum_{k=0,1,2,3 \bmod 8} \langle U \rangle_k - \sum_{k=4,5,6,7 \bmod 8} \langle U \rangle_k$$

Big picture: Why do the results work?

Inspiration: Structure of inverses in complex numbers, quaternions, split complex numbers, their representations.

We come up with required notions to generalize the problem to “bigger” Clifford algebras.

Essence: multiply a multivector with its suitably chosen conjugates as to eliminate non-zero grades.
Keep doing that until you eliminate all non-zero grades.

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Thank you for your attention!

See you at my poster!