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January 2013 Winter School @ Lunteren

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Chapter 4: Portfolio Choice under CPT

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1 Formulation of CPT Portfolio Choice Model

- 2 Divide and Conquer
- 3 Solutions to GPP and LPP
- 4 Grand Solution
- 5 Continuous Time and Time Inconsistency

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6 Summary and Further Readings

7 Final Words

-Formulation of CPT Portfolio Choice Model

Section 1

Formulation of CPT Portfolio Choice Model



Formulation of CPT Portfolio Choice Model

Model Primitives

- Present date t = 0 and a future date t = 1
- Randomness described by $(\Omega, \mathcal{F}, \mathbf{P})$ at t = 1
- An atomless pricing kernel ρ̃ so that any future payoff X̃ is evaluated as E[ρ̃X̃] at present

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- An agent with
 - initial endowment x_0 at t = 0
 - preference specified by CPT
 - ... wants to choose future consumption (wealth) \tilde{c}

-Formulation of CPT Portfolio Choice Model

Portfolio Choice/Consumption Model under CPT

The model

$$\begin{split} \underset{\tilde{c}}{\text{Max}} & V(\tilde{c}) = \int_{0}^{\infty} w_{+} \left(\mathbf{P} \left(u_{+} \left((\tilde{c} - \tilde{B})^{+} \right) > x \right) \right) dx \\ & - \int_{0}^{\infty} w_{-} \left(\mathbf{P} \left(u_{-} \left((\tilde{c} - \tilde{B})^{-} \right) > x \right) \right) dx \\ \text{subject to} & E[\tilde{\rho}\tilde{c}] \leq x_{0}, \ \tilde{c} \text{ is bounded below} \end{split}$$

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Formulation of CPT Portfolio Choice Model

Portfolio Choice/Consumption Model under CPT

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$$(CPT)$$

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• u_{\pm} is assumed to be concave so overall value function $u_{+}(x)\mathbf{1}_{x\geq 0} - u_{-}(x)\mathbf{1}_{x<0}$ is S-shaped; $u_{\pm}(0) = 0$

Formulation of CPT Portfolio Choice Model

Portfolio Choice/Consumption Model under CPT

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$$(CPT)$$

u_± is assumed to be concave so overall value function u₊(x)1_{x≥0} - u₋(x)1_{x<0} is S-shaped; u_±(0) = 0
 w₊ is in general non-convex/non-concave

Formulation of CPT Portfolio Choice Model

Portfolio Choice/Consumption Model under CPT

The model

$$\begin{split} \underset{\tilde{c}}{\text{Max}} & V(\tilde{c}) = \int_{0}^{\infty} w_{+} \left(\mathbf{P} \left(u_{+} \left((\tilde{c} - \tilde{B})^{+} \right) > x \right) \right) dx \\ & - \int_{0}^{\infty} w_{-} \left(\mathbf{P} \left(u_{-} \left((\tilde{c} - \tilde{B})^{-} \right) > x \right) \right) dx \\ \text{subject to} & E[\tilde{\rho}\tilde{c}] \leq x_{0}, \ \tilde{c} \text{ is bounded below} \end{split}$$

$$(CPT)$$

- u_{\pm} is assumed to be concave so overall value function $u_{+}(x)\mathbf{1}_{x\geq 0} u_{-}(x)\mathbf{1}_{x<0}$ is S-shaped; $u_{\pm}(0) = 0$
- w_± is in general non-convex/non-concave
 B̃ = 0 without loss of generality

Formulation of CPT Portfolio Choice Model

CPT Preference

Write
$$V(\tilde{c}) = V_{+}(\tilde{c}^{+}) - V_{-}(\tilde{c}^{-})$$
 where
 $V_{+}(\tilde{c}) := \int_{0}^{\infty} w_{+} \left(P(u_{+}(\tilde{c}) > x) \right) dx$
 $V_{-}(\tilde{c}) := \int_{0}^{\infty} w_{-} \left(P(u_{-}(\tilde{c}) > x) \right) dx$

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-Formulation of CPT Portfolio Choice Model

Mathematical Challenges

Two difference sources



Formulation of CPT Portfolio Choice Model

Mathematical Challenges

- Two difference sources
- Probability weighting and S-shaped value function

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Formulation of CPT Portfolio Choice Model

Literature





Formulation of CPT Portfolio Choice Model

Literature

Almost none

 Berkelaar, Kouwenberg and Post (2004): no probability weighting; two-piece power value function

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Formulation of CPT Portfolio Choice Model

Standing Assumptions

- $\tilde{\rho} > 0$ a.s., atomless, with $E[\tilde{\rho}] < +\infty$.
- $u_{\pm}: [0,\infty) \to \mathbb{R}$ are strictly increasing, concave, with $u_{\pm}(0) = 0$. Moreover, u_{+} is continuously differentiable on $(0,\infty)$, strictly concave, and satisfies the Inada condition: $u'_{+}(0+) = \infty$, $u'_{+}(\infty) = 0$.
- $w_{\pm}: [0,1] \rightarrow [0,1]$ are strictly increasing and continuously differentiable, and satisfies $w_{\pm}(0) = 0$, $w_{\pm}(1) = 1$.

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Divide and Conquer



Divide and Conquer

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Our Model (Again)

$$\begin{split} \underset{\tilde{c}}{\operatorname{Max}} & V(\tilde{c}) = \int_{0}^{\infty} w_{+} \left(\operatorname{P} \left(u_{+}(\tilde{c}^{+}) > x \right) \right) dx \\ & -\int_{0}^{\infty} w_{-} \left(\operatorname{P} \left(u_{-}(\tilde{c}^{-}) > x \right) \right) dx \end{split} \tag{P} \\ \text{subject to} & E[\tilde{\rho}\tilde{c}] \leq x_{0}, \ \tilde{c} \geq 0 \end{split}$$

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This problem admits a quantile formulation

Divide and Conquer

Divide and Conquer

We do "divide and conquer"



Divide and Conquer

Divide and Conquer

We do "divide and conquer"

■ Step 1: divide into two problems: one concerns the **gain** part of \tilde{c} and the other the **loss** part of \tilde{c}

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Divide and Conquer

Divide and Conquer

We do "divide and conquer"

- Step 1: divide into two problems: one concerns the **gain** part of \tilde{c} and the other the **loss** part of \tilde{c}
- Step 2: combine them together via solving another problem

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Step 1 – Gain Part Problem (GPP)

A problem with parameters (A, x_+) :

$$\begin{aligned} & \text{Max} & V_{+}(\tilde{c}) = \int_{0}^{\infty} w_{+} \left(\mathbf{P} \left(u_{+}(\tilde{c}) > x \right) \right) dx \\ & \text{subject to} & \begin{cases} E[\tilde{\rho}\tilde{c}] = x_{+}, & \tilde{c} \geq 0 \\ \tilde{c} = 0 \text{ on } A^{C}, \end{cases} \end{aligned}$$
 (1)

where $x_+ \ge x_0^+ \ (\ge 0)$ and $A \in \mathcal{F}$ with $\mathrm{P}(A) \le 1$

• Define its optimal value to be $v_+(A, x_+)$

Step 1 – Loss Part Problem (LPP)

A problem with parameters (A, x_+) :

where $x_+ \ge x_0^+$ and $A \in \mathcal{F}$ with $P(A) \le 1$

• Define its optimal value to be $v_-(A, x_+)$

Divide and Conquer

Step 2

In Step 2 we solve

Max
$$v_{+}(A, x_{+}) - v_{-}(A, x_{+})$$

subject to
$$\begin{cases} A \in \mathcal{F}, \ x_{+} \ge x_{0}^{+}, \\ x_{+} = 0 \text{ when } P(A) = 0, \\ x_{+} = x_{0} \text{ when } P(A) = 1. \end{cases}$$
(3)

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It Works

Theorem

(Jin and Zhou 2008) Given \tilde{c}^* , define $A^* := \{\omega : \tilde{c}^* \ge 0\}$ and $x^*_+ := E[\tilde{\rho}(\tilde{c}^*)^+]$. Then \tilde{c}^* is optimal for the CPT portfolio choice problem (CPT) iff (A^*, x^*_+) are optimal for Problem (3) and $(X^*)^+$ and $(X^*)^-$ are respectively optimal for Problems (1) and (2) with parameters (A^*, x^*_+) .

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Proof. Direct by definitions of maximum/minimum.

Solution Flow

■ Solve GPP for any parameter (A, x₊), getting optimal solution c̃₊(A, x₊) and optimal value v₊(A, x₊)

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Solution Flow

- Solve GPP for any parameter (A, x_+) , getting optimal solution $\tilde{c}_+(A, x_+)$ and optimal value $v_+(A, x_+)$
- Solve LPP for any parameter (A, x₊), getting optimal solution c̃₋(A, x₊) and optimal value v₋(A, x₊)

Solution Flow

- Solve GPP for any parameter (A, x₊), getting optimal solution c
 ₊(A, x₊) and optimal value v₊(A, x₊)
- Solve LPP for any parameter (A, x₊), getting optimal solution c̃₋(A, x₊) and optimal value v₋(A, x₊)

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Solve Step 2 problem and get optimal (A^*, x^*_+)

Solution Flow

- Solve GPP for any parameter (A, x₊), getting optimal solution c
 ₊(A, x₊) and optimal value v₊(A, x₊)
- Solve LPP for any parameter (A, x₊), getting optimal solution c̃₋(A, x₊) and optimal value v₋(A, x₊)
- Solve Step 2 problem and get optimal (A^*, x^*_+)
- Then $\tilde{c}^* := \tilde{c}_+(A^*, x^*_+) \tilde{c}_-(A^*, x^*_+)$ solves the CPT model

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Simplification

Recall Step 2 problem

$$v_+(A, x_+) - v_-(A, x_+)$$

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optimisation over a set of random events A: hard to handle

Simplification

Recall Step 2 problem

$$v_+(A, x_+) - v_-(A, x_+)$$

optimisation over a set of random events A: hard to handle

Theorem

(Jin and Zhou 2008) For any feasible pair (A, x_+) of Problem (3), there exists $c \in [\text{essinf } \tilde{\rho}, \text{esssup } \tilde{\rho}]$ such that $\bar{A} := \{\omega : \tilde{\rho} \leq a\}$ satisfies

$$v_{+}(\bar{A}, x_{+}) - v_{-}(\bar{A}, x_{+}) \ge v_{+}(A, x_{+}) - v_{-}(A, x_{+}).$$
 (4)

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Simplification

Recall Step 2 problem

$$v_+(A, x_+) - v_-(A, x_+)$$

optimisation over a set of random events A: hard to handle

Theorem

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$$v_{+}(\bar{A}, x_{+}) - v_{-}(\bar{A}, x_{+}) \ge v_{+}(A, x_{+}) - v_{-}(A, x_{+}).$$
 (4)

Proof. One needs only to look for $\tilde{c} = g(\tilde{\rho})$ where g is non-increasing. Hence $A = \{\omega : \tilde{c} \ge 0\} = \{\omega : g(\tilde{\rho}) \ge 0\} = \{\omega : \tilde{\rho} \le a\}.$

Step 2 Problem Rewritten

■ Use $v_+(a, x_+)$ and $v_-(a, x_+)$ to denote $v_+(\{\omega : \tilde{\rho} \le a\}, x_+)$ and $v_-(\{\omega : \tilde{\rho} \le a\}, x_+)$ respectively

Step 2 Problem Rewritten

- Use $v_+(a, x_+)$ and $v_-(a, x_+)$ to denote $v_+(\{\omega : \tilde{\rho} \le a\}, x_+)$ and $v_-(\{\omega : \tilde{\rho} \le a\}, x_+)$ respectively
- Problem (3) is equivalent to

Max $v_+(a, x_+) - v_-(a, x_+)$

subject to
$$\begin{cases} \text{essinf } \tilde{\rho} \le a \le \text{esssup } \tilde{\rho}, \quad x_+ \ge x_0^+, \quad (5) \\ x_+ = 0 \text{ when } a = \text{essinf } \tilde{\rho}, \\ x_+ = x_0 \text{ when } a = \text{esssup } \tilde{\rho} \end{cases}$$

Solutions to GPP and LPP

Section 3

Solutions to GPP and LPP

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Solutions to GPP and LPP

GPP

Max
$$V_{+}(\tilde{c}) = \int_{0}^{\infty} w_{+} \left(\mathbf{P} \left(u_{+}(\tilde{c}) > x \right) \right) dx$$

subject to
$$\begin{cases} E[\tilde{\rho}\tilde{c}] = x_{+}, \ \tilde{c} \ge 0 \\ \tilde{c} = 0 \text{ on } A^{C}, \end{cases}$$
 (6)

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where $x_+ \ge x_0^+$ and $A = \{\omega : \tilde{\rho} \le a\}$ with essinf $\tilde{\rho} \le a \le \text{esssup } \tilde{\rho}$ We have solved this problem – RDUT portfolio choice!

Solutions to GPP and LPP

Integrability Condition

Impose the intergrability condition

$$E\left[u_+\left((u'_+)^{-1}\left(\frac{\tilde{\rho}}{w'_+(F_{\tilde{\rho}}(\tilde{\rho}))}\right)\right)w'_+(F_{\tilde{\rho}}(\tilde{\rho}))\right] < +\infty$$

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Solutions to GPP and LPP

Integrability Condition

Impose the intergrability condition

$$E\left[u_+\left((u'_+)^{-1}\left(\frac{\tilde{\rho}}{w'_+(F_{\tilde{\rho}}(\tilde{\rho}))}\right)\right)w'_+(F_{\tilde{\rho}}(\tilde{\rho}))\right] < +\infty$$

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In the following, we always assume the integrability condition holds Solutions to GPP and LPP

Solutions to GPP

Theorem

(Jin and Zhou 2008) Assume $M(z) = \frac{w'_{\pm}(1-z)}{F_{\bar{\rho}}^{-1}(1-z)}$ is non-decreasing on $z \in (0, 1)$.

(i) If
$$x_+ = 0$$
, then optimal solution of (6) is $\tilde{c}^* = 0$ and $v_+(a, x_+) = 0$.

(ii) If $x_+ > 0$ and $a = \text{essinf } \tilde{\rho}$, then there is no feasible solution to (6) and $v_+(a, x_+) = -\infty$.

(iii) If $x_+ > 0$ and essinf $\tilde{\rho} < a \le \text{esssup } \tilde{\rho}$, then optimal solution to (6) is $\tilde{c}^* = (u'_+)^{-1} \left(\frac{\lambda^* \tilde{\rho}}{w'_+(F_{\tilde{\rho}}(\tilde{\rho}))}\right) \mathbf{1}_{(\tilde{\rho} \le a)}$ with the optimal value $v_+(a, x_+) = E \left[u_+ \left((u'_+)^{-1} (\frac{\lambda^* \tilde{\rho}}{w'_+(F_{\tilde{\rho}}(\tilde{\rho}))}) \right) w'_+(F_{\tilde{\rho}}(\tilde{\rho})) \mathbf{1}_{(\tilde{\rho} \le a)} \right]$, where λ^* is determined by $E(\tilde{\rho}\tilde{c}^*) = x_+$. Mathematical Behavioural Finance A Mini Course <u>Solutions</u> to GPP and LPP

Idea of Proof

• Work on conditional probability space $(\Omega \cap A, \mathcal{F} \cap A, \mathbf{P}_A := \mathbf{P}(\cdot|A))$

Solutions to GPP and LPP

Idea of Proof

- $\blacksquare \mbox{ Work on conditional probability space} \\ (\Omega \cap A, \mathcal{F} \cap A, \mathcal{P}_A := \mathcal{P}(\cdot|A))$
- Revise weighting function

$$w_A(x) := w_+(x\mathbf{P}(A))/w_+(\mathbf{P}(A)), \ x \in [0,1]$$

Solutions to GPP and LPP

Idea of Proof

- Work on conditional probability space $(\Omega \cap A, \mathcal{F} \cap A, P_A := P(\cdot|A))$
- Revise weighting function

$$w_A(x) := w_+(x\mathbf{P}(A))/w_+(\mathbf{P}(A)), \ x \in [0,1]$$

GPP is rewritten as

Max $V_+(\tilde{c}) = w_+(\mathbf{P}(A)) \int_0^\infty w_A \left(\mathbf{P}_A \left(u_+(\tilde{c}) > x\right)\right) dx$ subject to $\begin{cases} E_A[\tilde{\rho}\tilde{c}] = x_+/\mathbf{P}(A), \ \tilde{c} \ge 0 \end{cases}$

Solutions to GPP and LPP

Idea of Proof

- Work on conditional probability space $(\Omega \cap A, \mathcal{F} \cap A, P_A := P(\cdot|A))$
- Revise weighting function

$$w_A(x) := w_+(x\mathbf{P}(A))/w_+(\mathbf{P}(A)), \ x \in [0,1]$$

GPP is rewritten as

Max $V_+(\tilde{c}) = w_+(\mathbf{P}(A)) \int_0^\infty w_A \left(\mathbf{P}_A \left(u_+(\tilde{c}) > x\right)\right) dx$ subject to $\begin{cases} E_A[\tilde{\rho}\tilde{c}] = x_+/\mathbf{P}(A), \ \tilde{c} \ge 0 \end{cases}$

Apply result in Chapter 2

Solutions to GPP and LPP

LPP

Min
subject to
$$\begin{cases}
V_{-}(\tilde{c}) = \int_{0}^{\infty} w_{-} \left(P\left(u_{-}(\tilde{c}) > x \right) \right) dx \\
E[\tilde{\rho}\tilde{c}] = x_{+} - x_{0}, \quad \tilde{c} \ge 0 \\
\tilde{c} = 0 \text{ on } A, \quad \tilde{c} \text{ is bounded}
\end{cases}$$
(7)

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where $x_+ \ge x_0^+$ and $A = \{\omega : \tilde{\rho} \le a\}$ with essinf $\tilde{\rho} \le a \le \text{esssup } \tilde{\rho}$ This is a minimisation problem!

Solutions to GPP and LPP

A General Problem

$\begin{array}{ll} \underset{\tilde{c}}{\text{Min}} & \int_{0}^{\infty} w \left(\mathbf{P} \left(u(\tilde{c}) > x \right) \right) dx \\ \text{subject to} & E[\tilde{\rho}\tilde{c}] \ge x_{0}, \ \tilde{c} \ge 0 \end{array}$ (G)

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Solutions to GPP and LPP

Hardy–Littlewood Inequality (Again)

Lemma

(Jin and Zhou 2008) We have that $\tilde{c}^* := G(F_{\tilde{\rho}}(\tilde{\rho}))$ solves $\max_{\tilde{c}' \sim \tilde{c}} E[\tilde{\rho}\tilde{c}']$, where G is quantile of \tilde{c} . If in addition $-\infty < E[\tilde{\rho}\tilde{c}^*] < +\infty$, then \tilde{c}^* is the unique optimal solution.

Hardy, Littlewood and Pòlya (1952), Dybvig (1988)

Solutions to GPP and LPP

Quantile Formulation

The quantile formulation of (G) is:

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To minimise a concave functional: "wrong" direction!

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To minimise a concave functional: "wrong" direction!
... which originates from S-shaped value function

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- ... which originates from S-shaped value function
- Solution must have a very different structure compared with the maximisation counterpart

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Lagrange fails (positive duality gap)

- To minimise a concave functional: "wrong" direction!
- ... which originates from S-shaped value function
- Solution must have a very different structure compared with the maximisation counterpart
- Lagrange fails (positive duality gap)
- Solution should be a "corner point solution": essentially a combinatorial optimisation in an infinite dimensional space

Solutions to GPP and LPP

Characterising Corner Point Solutions

Proposition

(Jin and Zhou 2008) Assume $u(\cdot)$ is strictly concave at 0. Then the optimal solution to (Q), if it exists, must be in the form $G^*(z) = q(b)\mathbf{1}_{(b,1)}(z), z \in [0,1)$, with some $b \in [0,1)$ and $q(b) := \frac{a}{E[\tilde{\rho}\mathbf{1}_{\{F_{\tilde{\rho}}(\tilde{\rho}) > b\}}]}$. Moreover, in this case, the optimal solution is $\tilde{c}^* = G^*(F_{\tilde{\rho}}(\tilde{\rho}))$.

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• One only needs to find an optimal **number** $b \in [0, 1)$

Solutions to GPP and LPP

Characterising Corner Point Solutions

Proposition

(Jin and Zhou 2008) Assume $u(\cdot)$ is strictly concave at 0. Then the optimal solution to (Q), if it exists, must be in the form $G^*(z) = q(b)\mathbf{1}_{(b,1)}(z), z \in [0,1)$, with some $b \in [0,1)$ and $q(b) := \frac{a}{E[\tilde{\rho}\mathbf{1}_{\{F_{\tilde{\rho}}(\tilde{\rho}) > b\}}]}$. Moreover, in this case, the optimal solution is $\tilde{c}^* = G^*(F_{\tilde{\rho}}(\tilde{\rho}))$.

■ One only needs to find an optimal number b ∈ [0, 1)
 ■ ... which motivates introduction of the following problem

$$\begin{array}{ll} \underset{b}{\underset{b}{\text{Min}}} & f(b) := \int_{0}^{1} u(G(z))w'(1-z)dz \\ \text{subject to} & G(\cdot) = \frac{a}{E[\rho\mathbf{1}_{(F_{\bar{\rho}}(\bar{\rho}) > b)]}}\mathbf{1}_{(b,1]}(\cdot), \ \ 0 \le b < 1. \end{array}$$

Solutions to GPP and LPP

Solving (G)

Theorem

(Jin and Zhou 2008) Assume $u(\cdot)$ is strictly concave at 0. Then (G) admits an optimal solution if and only if the following problem

$$\min_{0 \leq b < \mathrm{esssup}\; \tilde{\rho}} u\left(\frac{x_0}{E[\tilde{\rho}\mathbf{1}_{(\tilde{\rho} > b)}]}\right) w(\mathbf{P}(\tilde{\rho} > b))$$

admits an optimal solution b^* , in which case the optimal solution to (G) is $\tilde{c}^* = \frac{x_0}{E[\tilde{\rho}\mathbf{1}_{(\tilde{\rho} > b^*)}]}\mathbf{1}_{(\tilde{\rho} > b^*)}$.

Solutions to GPP and LPP

Solutions to LPP

Theorem

(Jin and Zhou 2008) Assume $u(\cdot)$ is strictly concave at 0.

- (i) If $a = \text{esssup } \tilde{\rho}$ and $x_+ = x_0$, then optimal solution of (7) is $\tilde{c}^* = 0$ and $v_-(a, x_+) = 0$.
- (ii) If $a = \text{esssup } \tilde{\rho}$ and $x_+ \neq x_0$, then there is no feasible solution to (7) and $v_-(a, x_+) = +\infty$.

(iii) If essinf
$$\tilde{\rho} \leq a < \text{esssup } \tilde{\rho}$$
, then
 $v_{-}(a, x_{+}) = \inf_{b \in [a, \text{esssup } \tilde{\rho})} u_{-} \left(\frac{x_{+} - x_{0}}{E[\tilde{\rho}\mathbf{1}_{(\tilde{\rho} > b)}]}\right) w_{-} (1 - F_{\tilde{\rho}}(b)).$
Moreover, Problem (7) admits an optimal solution \tilde{c}^{*} iff the following problem

$$\min_{b \in [a, \text{esssup } \tilde{\rho})} u_{-} \left(\frac{x_{+} - x_{0}}{E[\tilde{\rho} \mathbf{1}_{(\tilde{\rho} > b)}]} \right) w_{-} \left(1 - F_{\tilde{\rho}}(b) \right)$$
(8)

admits an optimal solution b^* , in which case $\tilde{c}^* = \frac{x_+ - x_0}{E[\tilde{\rho}\mathbf{1}_{(\tilde{\rho} > b^*)}]} \mathbf{1}_{\tilde{\rho} > b^*}$.

Grand Solution



Grand Solution

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A Mathematical Programme

Consider a mathematical programme in (a, x_+) :

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Grand Solution

Theorem

(Jin and Zhou 2008) Assume $u_{-}(\cdot)$ is strictly concave at 0 and M is non-decreasing. Let (a^*, x^*_{+}) solves (MP). Then the optimal solution to (CPT) is

$$\tilde{c}^* = \left[(u'_+)^{-1} \left(\frac{\lambda \tilde{\rho}}{w'_+(F_{\tilde{\rho}}(\tilde{\rho}))} \right) \right] \mathbf{1}_{(\tilde{\rho} \le a^*)} - \left[\frac{x_+^* - x_0}{E[\tilde{\rho} \mathbf{1}_{(\tilde{\rho} > a^*)}]} \right] \mathbf{1}_{(\tilde{\rho} > a^*)}.$$

Interpretations and Implications

$$\tilde{c}^* = \left[(u'_+)^{-1} \left(\frac{\lambda \tilde{\rho}}{w'_+(F_{\tilde{\rho}}(\tilde{\rho}))} \right) \right] \mathbf{1}_{(\tilde{\rho} \le a^*)} - \left[\frac{x^*_+ - x_0}{E[\tilde{\rho} \mathbf{1}_{(\tilde{\rho} > a^*)}]} \right] \mathbf{1}_{(\tilde{\rho} > a^*)}$$

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Interpretations and Implications

$$\tilde{c}^* = \left[(u'_+)^{-1} \left(\frac{\lambda \tilde{\rho}}{w'_+(F_{\tilde{\rho}}(\tilde{\rho}))} \right) \right] \mathbf{1}_{(\tilde{\rho} \le a^*)} - \left[\frac{x^*_+ - x_0}{E[\tilde{\rho} \mathbf{1}_{(\tilde{\rho} > a^*)}]} \right] \mathbf{1}_{(\tilde{\rho} > a^*)}$$

• Future world divided by "good" states (where you have gains) and "bad" ones (losses), *completely* determined by whether $\tilde{\rho} \leq a^*$ or $\tilde{\rho} > a^*$

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• Agent buy claim
$$\left[(u'_{+})^{-1} \left(\frac{\lambda \tilde{\rho}}{w'_{+}(F_{\tilde{\rho}}(\tilde{\rho}))} \right) \right] \mathbf{1}_{(\tilde{\rho} \leq a^{*})}$$
 at cost $x^{*}_{+} \geq x_{0}$ and sell $\left[\frac{x^{*}_{+} - x_{0}}{E[\tilde{\rho}\mathbf{1}_{(\tilde{\rho} > a^{*})}]} \right] \mathbf{1}_{(\tilde{\rho} > a^{*})}$ to finance shortfall $x^{*}_{+} - x_{0}$

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- Agent not only invests in stocks, but also generally takes a leverage to do so
- Optimal strategy is a *gambling* policy, betting on the good states while accepting a **known** loss on the bad

Continuous Time and Time Inconsistency

Section 5

Continuous Time and Time Inconsistency

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Continuous Time and Time Inconsistency

A Continuous-Time Economy

• An economy in which m+1 securities traded continuously

Continuous Time and Time Inconsistency

A Continuous-Time Economy

- An economy in which m+1 securities traded continuously
- Market randomness described by a complete filtered probability space $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t\geq 0}, P)$ along with an \mathbb{R}^m -valued, \mathcal{F}_t -adapted standard Brownian motion $W(t) = (W^1(t), \cdots, W^m(t))'$ with $\{\mathcal{F}_t\}_{t\geq 0}$ generated by $W(\cdot)$

Continuous Time and Time Inconsistency

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- A bond whose price process $S_0(t)$ satisfies

$$dS_0(t) = r(t)S_0(t)dt; \ S_0(0) = s_0$$

Continuous Time and Time Inconsistency

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• m stocks whose price processes $S_1(t), \dots S_m(t)$ satisfy stochastic differential equation (SDE)

$$dS_{i}(t) = S_{i}(t) \left(\mu_{i}(t)dt + \sum_{j=1}^{m} \sigma_{ij}(t)dW^{j}(t) \right); \ S_{i}(0) = s_{i}$$

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Continuous Time and Time Inconsistency

Tame Portfolios

Let

$$\sigma(t) := (\sigma_{ij}(t))_{m \times m}$$

$$B(t) := (\mu_1(t) - r(t), \cdots, \mu_m(t) - r(t))'$$

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• An \mathcal{F}_t -progressively measurable process $\pi(t) = (\pi_1(t), \cdots, \pi_m(t))'$ represents a (monetary) portfolio, where $\pi_i(t)$ is the capital amount invested in stock i at t

Continuous Time and Time Inconsistency

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 A portfolio π(·) is admissible if

$$\int_{0}^{T} |\sigma(t)'\pi(t)|^{2} dt < +\infty, \ \int_{0}^{T} |B(t)'\pi(t)| dt < +\infty, \ \text{a.s}$$

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An agent has an initial endowment x_0
Continuous Time and Time Inconsistency

Wealth Equation

• Wealth process $x(\cdot)$ follows the *wealth equation*

$$\begin{cases} dx(t) = [r(t)x(t) + B(t)'\pi(t)]dt + \pi(t)'\sigma(t)dW(t) \\ x(0) = x_0 \end{cases}$$

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Continuous Time and Time Inconsistency

Wealth Equation

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$$\begin{cases} dx(t) &= [r(t)x(t) + B(t)'\pi(t)]dt + \pi(t)'\sigma(t)dW(t) \\ x(0) &= x_0 \end{cases}$$

■ An admissible portfolio π(·) is called *tame* if the corresponding wealth process x(·) is uniformly lower bounded

Continuous Time and Time Inconsistency

Market Assumptions

Market assumptions:

- (i) There exists $k \in \mathbb{R}$ such that $\int_0^T r(t) dt \ge k$,
- (ii) $\int_0^T \left[\sum_{i=1}^m |b_i(t)| + \sum_{i,j=1}^m |\sigma_{ij}(t)|^2\right] dt < +\infty,$
- (iii) Rank $(\sigma(t)) = m, t \in [0, T],$
- (iv) There exists an \mathbb{R}^m -valued, uniformly bounded, \mathcal{F}_t -progressively measurable process $\theta(\cdot)$ such that $\sigma(t)\theta(t) = B(t)$

Continuous Time and Time Inconsistency

Pricing Kernel

Define

$$\rho(t) := \exp\left\{-\int_0^t \left[r(s) + \frac{1}{2}|\theta(s)|^2\right] ds - \int_0^t \theta(s)' dW(s)\right\}$$

Continuous Time and Time Inconsistency

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Denote $\tilde{\rho} := \rho(T)$

Continuous Time and Time Inconsistency

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- $\blacksquare \text{ Denote } \tilde{\rho} := \rho(T)$
- Assume that $\tilde{\rho}$ is atomless

Continuous Time and Time Inconsistency

Continuous-Time Portfolio Choice under EUT

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Continuous Time and Time Inconsistency

Forward Approach: Dynamic Programming

• Let v be the value function corresponding to (9): v(t, x) is the optimal value of (9) if the initial time is t (instead of 0) and the initial budget is x (instead of x_0)

Continuous Time and Time Inconsistency

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Time (dynamic) consistency: $E(\tilde{c}|\mathcal{F}_t) = E[E(\tilde{c}|\mathcal{F}_s)|\mathcal{F}_t]$ $\forall t < s$ Continuous Time and Time Inconsistency

Forward Approach: Dynamic Programming

- Let v be the value function corresponding to (9): v(t, x) is the optimal value of (9) if the initial time is t (instead of 0) and the initial budget is x (instead of x₀)
- Time (dynamic) consistency: $E(\tilde{c}|\mathcal{F}_t) = E[E(\tilde{c}|\mathcal{F}_s)|\mathcal{F}_t]$ $\forall t < s$
- v satisfies the Hamilton–Jacobi–Bellman (HJB) equation:

$$\begin{cases} v_t + \sup_{\pi \in \mathbb{R}^m} \left(\frac{1}{2} \pi' \sigma \sigma' \pi v_{xx} + B \pi v_x \right) + rxv_x = 0, \quad (t, x) \in [0, T) \times \mathbb{R}, \\ v(T, x) = u(x) \end{cases}$$
(10)

Continuous Time and Time Inconsistency

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Verification theorem: optimal portfolio

$$\pi^*(t,x) = -(\sigma(t)')^{-1}\theta(t)\frac{v_x(t,x)}{v_{xx}(t,x)}$$
(11)

Continuous Time and Time Inconsistency

Backward Approach: Replication

One solves first a static optimization problem in terms of terminal wealth, *c*:

$$\begin{array}{ll} \text{Max} & E[u(\tilde{c})] \\ \text{subject to} & E[\tilde{\rho}\tilde{c}] = x_0; \; \tilde{c} \; \text{is} \; \mathcal{F}_T \text{-measurable} \end{array}$$
(12)

Continuous Time and Time Inconsistency

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$$\begin{aligned} & \underset{\tilde{c}^{*}}{\operatorname{Max}} \quad E[u(\tilde{c})] \\ & \text{subject to} \quad E[\tilde{\rho}\tilde{c}] = x_{0}; \; \tilde{c} \; \text{is } \mathcal{F}_{T}\text{-measurable} \end{aligned}$$

$$\begin{aligned} & (12) \\ & \tilde{c}^{*} = (u')^{-1} (\lambda^{*}\tilde{\rho}) \end{aligned}$$

Continuous Time and Time Inconsistency

Backward Approach: Replication

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$$E[u(\tilde{c})]$$

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$$\widetilde{c}^* = (u')^{-1}(\lambda^* \widetilde{\rho})$$

Solve backward stochastic differential equation (BSDE) in $(x^*(\cdot), z^*(\cdot))$:

 $dx^{*}(t) = [r(t)x^{*}(t) + \theta(t)'z^{*}(t)]dt + z^{*}(t)'dW(t); \ x^{*}(T) = \tilde{c}^{*} \ \ \textbf{(13)}$

Continuous Time and Time Inconsistency

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 $dx^{*}(t) = [r(t)x^{*}(t) + \theta(t)'z^{*}(t)]dt + z^{*}(t)'dW(t); \ x^{*}(T) = \tilde{c}^{*}$ (13)

Setting $\pi^*(t) = (\sigma(t)')^{-1} z^*(t)$ and $(x^*(\cdot), \pi^*(\cdot))$ is optimal pair

Continuous Time and Time Inconsistency

Time Inconsistency under Probability Weighting

• Choquet expectation $\hat{E}[\tilde{X}] = \int \tilde{X} d(w \circ \mathbf{P}) = \int_0^\infty w(\mathbf{P}(\tilde{X} > x)) dx$

Continuous Time and Time Inconsistency

Time Inconsistency under Probability Weighting

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How to define "conditional Choquet expectation"?

Continuous Time and Time Inconsistency

Time Inconsistency under Probability Weighting

- Choquet expectation $\hat{E}[\tilde{X}] = \int \tilde{X} d(w \circ P) = \int_0^\infty w(P(\tilde{X} > x)) dx$
- How to define "conditional Choquet expectation"?
- Even if a conditional Choquet expectation can be defined, it will not satisfy $\hat{E}(\tilde{c}|\mathcal{F}_t) = \hat{E}[\hat{E}(\tilde{c}|\mathcal{F}_s)|\mathcal{F}_t]$

Continuous Time and Time Inconsistency

Time Inconsistency under Probability Weighting

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- Dynamic programming falls apart
- Consider a weak notion of "optimality" equilibrium portfolio in other settings (Ekeland and Pirvu 2008, Hu, Jin and Zhou 2012, Bjork, Murgoci and Zhou 2012)

Continuous Time and Time Inconsistency

Replication: Pre-Committed Strategies

 Solve a static optimisation problem (with probability weighting) in terms of terminal wealth

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Replication: Pre-Committed Strategies

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- Find a dynamic portfolio replicating the obtained optimal terminal wealth
- Such a portfolio is an optimal pre-committed strategy (Jin and Zhou 2008, He and Zhou 2011)

Summary and Further Readings

Section 6

Summary and Further Readings

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Summary

 Portfolio choice under CPT - probability weighting and S-shaped value function

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- Inherent time inconsistency for continuous-time behavioural problems

Summary and Further Readings

Essential Readings

- A. Berkelaar, R. Kouwenberg and T. Post. Optimal portfolio choice under loss aversion, Review of Economics and Statistics, 86:973–987, 2004.
- H. Jin and X. Zhou. Behavioral portfolio selection in continuous time, Mathematical Finance, 18:385–426, 2008; Erratum, Mathematical Finance, 20:521–525, 2010.

Summary and Further Readings

Other Readings

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I. Karatzas and S. E. Shreve. Methods of Mathematical Finance, Springer, New York, 1998.

Final Words



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Two Revolutions in Finance

 Finance ultimately deals with interplay between market risk and human judgement

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Two Revolutions in Finance

- Finance ultimately deals with interplay between market risk and human judgement
- History of financial theory over the last 50 years characterised by two revolutions
 - Neoclassical (maximising) finance starting 1960s: Expected utility maximisation, CAPM, efficient market theory, option pricing
 - Behavioural finance starting 1980s: Cumulative prospect theory, SP/A theory, regret and self-control, heuristics and biases

Neoclassical: the world and its participants are rational "wealth maximisers"

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 - It seeks to explore the consistency and predictability in human flaws so that such flaws can be avoided or even exploited for profit

Mathematical Behavioural Finance A Mini Course

Do We Need Both?

Foundations of the two



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 Neoclassical finance: Rationality (correct beliefs on information, risk aversion) – A normative theory

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- Behavioural finance tells what people actually do
- Robert Shiller (2006), "the two ... have always been interwined, and some of the most important applications of their insights will require the use of both approaches"

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- We use CPT/RDUT/SPA and specific value functions as the carrier for exploring the "predictable irrationalities"
- Mathematical behavioural finance: research is in its infancy, yet potential is unlimited – or so we believe