Pricing options under processes with unknown characteristic functions

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General framework

• We consider an asset price which is modelled as,

$$S_t = \mathbb{1}_{\{t < \zeta\}} e^{X_t}.$$

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- ► The asset price is an exponential function of some process X_t.
- ► We allow for default in the asset price, and assume the default occurs with some intensity γ(s, X_s).
- ► We are interested in pricing derivatives with the log-underlying some stochastic process X_t.

European options

Consider a European option with maturity time T. The payoff at T is given by $\Phi(T, S_T)$. The option value v(t, x) is defined by

$$v(t,x) = E\left[e^{-\int_t^T r ds} \Phi(T,S_T)|X_t = x\right], \ t \in [0,T].$$

This can be rewritten using $S_t = \mathbb{1}_{\{\zeta > t\}} e^{X_t}$ as

$$v(t,x) = \mathbb{1}_{\{\zeta > t\}} E\left[e^{-\int_t^T (r+\gamma(s,X_s))ds} \phi(T,X_T) | X_t = x\right], \ t \in [0,T],$$

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where we have defined $\phi(x) := \Phi(e^x)$.

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Bermudan put option

Consider *M* exercise moments $\{t_1, ..., t_M\}$ with payoff at exercise time t_m to be $\phi(t_m, x)$. The option value v(t, x) is defined recursively as

$$v(t_M, x) = \mathbb{1}_{\{\zeta > t_M\}}\phi(t_M, x),$$

and

$$\begin{cases} c(t,x) = E\left[e^{\int_t^{t_m}(r+\gamma(s,X_s))ds}v(t_m,X_{t_m})|X_t=x\right], \ t\in[t_{m-1},t_m[\\v(t_{m-1},x) = \mathbb{1}_{\{\zeta>t_{m-1}\}}\max\{\phi(t_{m-1},x),c(t_{m-1},x)\}, \ m\in\{2,\ldots,M\}, \end{cases}$$

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followed by

$$v(0,x)=c(0,x).$$

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Computing the expected value

In order to compute the option price, we must evaluate functions of the form

$$u(t,x) := E\left[e^{-\int_t^T \gamma(s,X_s)ds}\phi(T,X_T)|X_t=x\right].$$

The function u can be represented as an integral with respect to the transition distribution of the defaultable log-price process log *S*:

$$u(t,x) = \int_{\mathbb{R}} \phi(y) \Gamma(t,x;T,dy).$$

The characteristic function of $\log S$ is given by

$$\hat{\mathsf{\Gamma}}(t,x;\,\mathsf{T},\xi):=\mathcal{F}(\mathsf{\Gamma}(t,x;\,\mathsf{T},\cdot))(\xi)=\int_{\mathbb{R}}e^{i\xi y}\mathsf{\Gamma}(t,x;\,\mathsf{T},dy),\;\;\xi\in\mathbb{R}$$

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Least Squares Monte Carlo

- 1. Generate paths using a Monte Carlo simulation
- 2. Calculate continuation value in a backwards recursive manner for every path at every time step using a least-squares regression:

$$\hat{c}(t_m, x(\omega)) = \sum_{k=0}^{K} \alpha_{t_m}(k) \psi_k(x(\omega)),$$

with ψ_k , k = 0, ..., K a set of basis functions and the coefficients α_{t_m} chosen by fitting a regression between the discounted future payoffs and the current underlying values.

- 3. Set up cash flow matrix by comparing exercise and continuation: $\max(v(t_m, x(\omega)), c(t_m, x(\omega)))$
- 4. Finally, the option price is the sum of discounted cash flows averaged over the paths.

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Approximation for expected values

With the COS method we calculate expected values (integrals):

$$u(t,x) = \int_{\mathbb{R}} \phi(T,y) \Gamma(t,x;T,dy),$$

$$\approx \sum_{k=0}^{N-1} \operatorname{Re}\left(e^{-ik\pi \frac{a}{b-a}} \hat{\Gamma}\left(t,x;T,\frac{k\pi}{b-a}\right)\right) V_k(T),$$

by truncating the integration to [a, b], replacing the distribution with its cosine expansion and truncating the summation to Nterms. Here $V_k(T)$ is the Fourier-cosine coefficient of the payoff function

$$V_k(T) = \frac{2}{b-a} \int_a^b \cos\left(k\pi \frac{y-a}{b-a}\right) \phi(T, y) dy,$$

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and $\hat{\Gamma}$ is the characteristic function.

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Lévy processes

With exponential Lévy processes the asset price is modelled as an exponential function of a Lévy process L_t,

$$S_t = e^{L_t}.$$

Each Lévy process can be characterised by a triplet (μ, σ, ν) with μ ∈ ℝ, σ ≤ 0 and ν a measure with ν(0) = 0 and

$$\int_{\mathbb{R}}\min(1,|x|^2)\nu(dx)<\infty.$$

 For the Lévy process we have an explicit form of the characteristic function (Lévy-Khinchine formula)

$$\widehat{\Gamma}(t,x,T,\zeta) = e^{(T-t)\left(i\mu\zeta - \frac{1}{2}\sigma^2\zeta^2 + \int_{\mathbb{R}} (e^{i\zeta x} - 1 - i\zeta x \mathbb{1}_{\{|x| < 1\}}\nu(dx))\right)}.$$

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Motivation Fourier methods

Fourier methods are methods that are

- computationally fast,
- not restricted to Gaussian-based models,
- work as long as we have the characteristic function (available for Lévy processes and Heston model).

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- Problem: there are interesting dynamics, with lots of flexibility, for which we do not have explicit characteristic functions.
- We have to resort to techniques to approximate them.

Local Lévy process

We consider a defaultable asset S whose risk-neutral dynamics are given by:

$$S_{t} = \mathbb{1}_{\{t < \zeta\}} e^{X_{t}},$$

$$dX_{t} = \mu(t, X_{t})dt + \sigma(t, X_{t})dW_{t} + \int_{\mathbb{R}} d\tilde{N}_{t}(t, X_{t-}, dz)z,$$

$$d\tilde{N}_{t}(t, X_{t-}, dz) = dN_{t}(t, X_{t-}, dz) - \nu(t, X_{t-}, dz)dt,$$

$$\zeta = \inf\{t \ge 0 : \int_{0}^{t} \gamma(s, X_{s})ds \ge \varepsilon\},$$
(1)

where $\tilde{N}_t(t, x, dz)$ is a compensated random measure with state-dependent Lévy measure $\nu(t, x, dz)$ and $\varepsilon \sim \text{Exp}(1)$ and is independent of X.

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Approximating the characteristic function (Ruijter, Oosterlee, 2015)

- Suppose we have no jumps, i.e. $dX_t = \mu(X_t)dt + \sigma(X_t)dW_t$.
- ► Discretize the process, by e.g. Euler scheme, Milstein scheme or order 2.0 weak Taylor scheme.
- ▶ In a general form,

$$X_{m+1}^{\Delta} = x + m(x)\Delta t + s(x)\Delta W_{m+1} + k(x)(\Delta W_{m+1})^2, \quad X_m^{\Delta} = x.$$

► The characteristic function of X_{m+1}^{Δ} given $X_m^{\Delta} = x$ is given by

$$\hat{\Gamma}(t_m,x;t_{m+1},\zeta) = e^{i\zeta x + i\zeta m(x)\Delta t - \frac{\frac{1}{2}\zeta^2 s^2(x)\Delta t}{1 - 2i\zeta k(x)\Delta t}} (1 - 2i\zeta k(x)\Delta t)^{-\frac{1}{2}}$$

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Adjoint expansion of the characteristic function (Pagliarani, Pascucci, Riga, 2013)

The density $\Gamma(t, x; T, y)$ of a process solves the Cauchy problem

$$\begin{cases} L(t,x)\Gamma(t,x;T,y) = 0, & t \in [0,T[, x \in \mathbb{R}, \\ \Gamma(T,\cdot;T,y) = \delta_y, & x \in \mathbb{R}, \end{cases}$$
(2)

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where L(t, x) is the integro-differential operator (of the process)

$$\begin{split} \mathcal{L}(t,x) &= \partial_t + r\partial_x + \gamma(t,x)(\partial_x - 1) \\ &+ \frac{\sigma^2(t,x)}{2}(\partial_{xx} - \partial_x) - \int_{\mathbb{R}} \nu(t,x,dz)(e^z - 1 - z)\partial_x \\ &+ \int_{\mathbb{R}} \nu(t,x,dz)(e^{z\partial_x} - 1 - z\partial_x). \end{split}$$

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A Taylor expansion of the coefficients

Use an expansion of the space-dependent coefficients in the operator L around some point \bar{x} .

Consider for simplicity only a local-volatility. Define

$$a(t,x) := rac{\sigma^2(t,x)}{2}, \quad a_k = rac{\partial_x^k a(ar x)}{k!}$$

The *n*th-order approximation of *L* is

$$L_n = L_0 + \sum_{k=1}^n \left((x - \bar{x})^k a_k (\partial_{xx} - \partial_x) \right),$$

$$L_0 = \partial_t + r \partial_x + a_0 (\partial_{xx} - \partial_x).$$

Notice that

$$L_h - L_{h-1} = (x - \bar{x})^h a_h (\partial_{xx} - \partial_x).$$

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Cauchy problems of the expansion The *n*th-order approximation of Γ is defined as

$$\Gamma^{(n)}(t,x;T,y) = \sum_{k=0}^{n} G^{k}(t,x;T,y),$$

with G^0 solving

$$\begin{cases} L_0 G^0(t,x;T,y) = 0, \\ G^0(T,\cdot;T,y) = \delta_y. \end{cases}$$

and G^k for $k \ge 1$ defined through

$$\begin{cases} L_0 G^k(t, x; T, y) = -\sum_{h=1}^k (L_h - L_{h-1}) G^{k-h}(t, x; T, y), \\ G^k(T, x; T, y) = 0. \end{cases}$$

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for $t \in [0, T[, x \in \mathbb{R}$

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Solving the Adjoint Cauchy problems in Fourier space

The *n*th-order approximation of the characteristic function $\hat{\Gamma}$ is defined to be

$$\widehat{\Gamma}^{(n)}(t,x;T,\xi) = \sum_{k=0}^{n} \mathcal{F}\left(G^{k}(t,x;T,\cdot)\right)(\xi) := \sum_{k=0}^{n} \widehat{G}^{k}(t,x;T,\xi), \ \xi \in \mathbb{R}.$$

Note that Fourier transform is taken with respect to (T, y), but L acts on (t, x). We will:

- ► Solve the adjoint Cauchy problems in the Fourier space. This immediately gives Γ̂.

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Theorem (Dual formulation)

The function $G^0(t, x; \cdot, \cdot)$ is defined through the following dual Cauchy problem

$$\left\{egin{aligned} & \widetilde{L}_0^{(\mathcal{T},y)}G^0(t,x;\mathcal{T},y)=0 \qquad & \mathcal{T}>t,\; y\in\mathbb{R},\ & G^0(\mathcal{T},x;\mathcal{T},\cdot)=\delta_x. \end{aligned}
ight.$$

For any $k \geq 1$ the function $G^k(t, x; \cdot, \cdot)$ is defined through

$$\begin{cases} \tilde{L}_{0}^{(T,y)}G^{k}(t,x;T,y) = -\sum_{h=1}^{k} \left(\tilde{L}_{h}^{(T,y)} - \tilde{L}_{h-1}^{(T,y)} \right) G^{k-h}(t,x;T,y) \\ G^{k}(T,x;T,y) = 0 \end{cases}$$

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with
$$\tilde{L}_{0}^{(T,y)}$$
 and $\tilde{L}_{h}^{(T,y)} - \tilde{L}_{h-1}^{(T,y)}$ being the adjoint operators.

Solution in Fourier space

We have

$$\tilde{L}_0^{(\mathcal{T},y)} = -\partial_{\mathcal{T}} - r\partial_y + a_0(\partial_{yy} + \partial_y).$$

Then

$$\mathcal{F}\left(\tilde{L}_{0}^{(\mathcal{T},\cdot)}G^{k}(t,x;\mathcal{T},\cdot)\right)(\xi)=\psi(\xi)\hat{G}^{k}(t,x;\mathcal{T},\xi)-\partial_{\mathcal{T}}\hat{G}^{k}(t,x;\mathcal{T},\xi),$$

where

$$\psi(\xi)=i\xi r+a_0(-\xi^2-i\xi).$$

Then the solution to the adjoint Cauchy problems is given by

$$\hat{G}^{0}(t,x;T,\xi) = e^{i\xi x + (T-t)\psi(\xi)},$$
$$\hat{G}^{k}(t,x;T,\xi) = -\int_{t}^{T} e^{\psi(\xi)(T-s)} \mathcal{F}\left(\sum_{h=1}^{k} \left(\tilde{L}_{h}^{(s,\cdot)} - \tilde{L}_{h-1}^{(s,\cdot)}\right) G^{k-h}(t,x;s,\cdot)\right)(\xi) ds$$

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The characteristic function

The approximation of order n of the characteristic function is of the form

$$\hat{\Gamma}^{(n)}(t,x;T,\xi) := e^{i\xi x} \sum_{h=0}^{n} (x-\bar{x})^{h} g_{n,h}(t,T,\xi),$$

where the coefficients $g_{n,h}$, with $0 \le h \le n$, depend only on t, T and ξ , but not on x.

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Back to the Bermudan option valuation [1/2]

Remember we had to value the continuation value of the form:

$$\hat{c}(t,x) = e^{-r(t_{m+1}-t)} \sum_{k=0}^{N-1} \operatorname{Re}\left(e^{-ik\pi \frac{a}{b-a}} \hat{\Gamma}\left(t,x;t_{m+1},\frac{k\pi}{b-a}\right)\right) V_k(t_{m+1}),$$
$$V_k(t_m) = \frac{2}{b-a} \int_a^b \cos\left(k\pi \frac{y-a}{b-a}\right) \max\{\phi(t_m,y),c(t_m,y)\} dy.$$

We can rewrite

$$V_k(t_m) = \frac{2}{b-a} \int_{x_m^*}^b \cos\left(k\pi \frac{y-a}{b-a}\right) c(t_m, y) dy + C_k,$$

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with x_m^* being the early-exercise point such that $c(t_m, x_m^*) = \phi(t_m, x_m^*).$

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Back to the Bermudan option valuation [2/2]

Inserting $\hat{c}(t, x)$ into the formula for $V_k(t_m)$ we find in vectorized form:

$$\hat{\mathbf{V}}(t_m) = \sum_{h=0}^{n} e^{-r(t_{m+1}-t_m)} \operatorname{Re}\left(\mathcal{M}^h(x_m^*, b) \boldsymbol{u}^h\right) + \mathbf{C}, \qquad (3)$$

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with

$$M_{k,j}^{h}(x_{m}^{*},b) = \frac{2}{b-a} \int_{x_{m}^{*}}^{b} e^{ij\pi\frac{x-a}{b-a}} (x-\bar{x})^{h} \cos\left(k\pi\frac{x-a}{b-a}\right) dx \quad (4)$$

The matrix-vector multiplication $\mathcal{M}(x_m^*, b)\boldsymbol{u}$ can be calculated using a fast Fourier transform.

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A quick example

Consider a process under the CEV-Merton dynamics with local vol. and Gaussian jumps.

Table: Prices for a European and a Bermudan Put option (T = 1 and 10 exercise dates) in the CEV-Merton model for the 2nd-order approximation of the characteristic function, and a Monte Carlo method.

	European		Bermudan	
K	MC 95% c.i.	Value	MC 95% c.i.	Value
0.8	0.02526-0.02622	0.02581	0.02617-0.02711	0.02520
1	0.08225-0.08395	0.08250	0.08480-0.08640	0.08593
1.2	0.1965 - 0.1989	0.1977	0.2097-0.2115	0.2132
1.4	0.3560-0.3589	0.3574	0.3946-0.3957	0.3954
1.6	0.5341 - 0.5385	0.5364	0.5930-0.5941	0.5932

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Other applications: Gas storage pricing

- Optimal operation of a storage facility amounts to finding the optimal times to inject and withdraw gas, depending on the current and expected spot/futures prices.
- ▶ The contract then allows the holder to take an action u_n at any time t_n , n = 1, ..., N 1.
- Injection at time t_n as a positive volume change Δv_n and a withdrawal as a negative volume change Δv_n .
- The volume in the storage tank satisfies a constraint, $v_n^{\min} \le v_n \le v_n^{\max}$.
- ► The withdrawal rate is assumed to satisfy, $\alpha^w(n, v_n) \le \Delta v_n \le \alpha^i(n, v_n)$, with α^w the (negative) maximum withdrawal rate, and α^i the (positive) maximum withdrawal rate.

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Pricing gas contracts

• Define the set of allowed actions at time t_n given the volume v_n to be,

$$\mathcal{D}(n, v_n) := \left\{ \Delta v | v_{n+1}^{\min} \leq v_n + \Delta v \leq v_{n+1}^{\max}, \text{ and } \alpha^w(n, v_n) \leq \Delta v \leq \alpha^i(n, v_n)
ight\}$$

▶ Denote the value of a storage contract starting at time t_n with volume v_n by $u(n, S_n, v_n)$, the payoff after taking some action as $h(S_n, \Delta v)$ and define the continuation value $c(n, S_n, v_{n+1})$ as the value we attach to the contract after taking an allowed action $\Delta v \in \mathcal{D}(n, v_n)$,

$$c(n,S_n,v_{n+1}):=\mathbb{E}_n\left[e^{-r\Delta t}u(n+1,S_{n+1},v_n+\Delta v)\right].$$

▶ Then we find the dynamic programming backwards recursion,

$$u(N, S_N, v_N) = q(S_N, v_N), u(n, S_n, v_n) = \max_{\Delta v \in \mathcal{D}(n, v_n)} (h(S_n, \Delta v) + c(n, S_n, v_{n+1})), \quad n = N - 1, ..., 0.$$

We can solve this using a Least Squares Monte Carlo or as usual the COS method approach.

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The challenges

- ► The spot price is typically a complex process; seasonality, mean-reversion, price spikes should be included.
- Previous work included modelling the asset price as a time in-homogeneous exponential Lévy process (Safarov and Atkinson (2017)).
- Alternatively, the local Lévy model might be of interest to use.
- The gas storage value is very sensitive to the modeling assumptions. Therefore, a good asset model is of the essence.

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Future work: combining the COS method with an asset model for which we can approximate the characteristic function for fast and efficient gas storage valuation.

For Further Reading

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